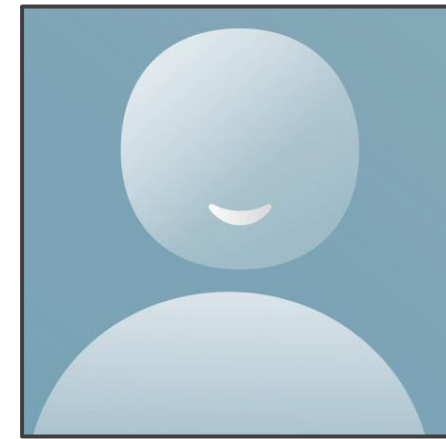


Event-Driven Based CMOS Interface for Magnetic Sensing



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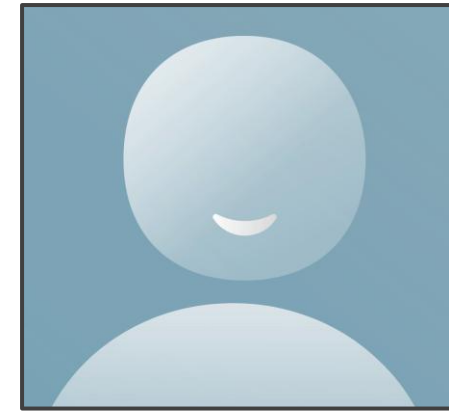
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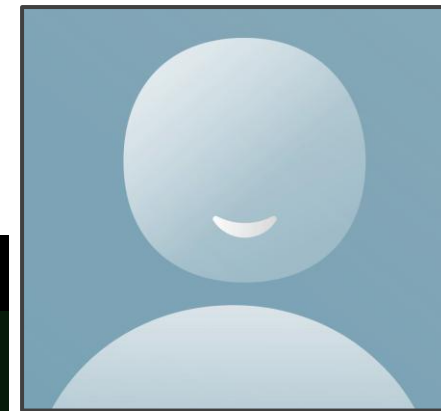
Arman Shahryari



Arman Shahryari received the master's degree in Electronic Engineering in the University of Valencia, Spain in 2024. He is currently a doctoral student majoring in Microelectronics Engineering at the University of Valencia, ETSE-UV.

His current research interests include magnetic sensing systems based on resistive technologies, event-driven and neuromorphic sensor architectures and analog and mixed-signal integrated circuit design.

Research Group



GMR Sensors + CMOS integration

INESC MN
Microsistemas e Nanotecnologias

Free ferromagnetic layer (FMI)
Insulator layer (IM) / Insulated ferromagnetic layer (IFM)
Antiferromagnetic layer (AF)

$$R = f(B)$$

AMS035 + GMR

Magnetic event driven sensor

CMOS IC current

IC current sensor

IMB-CNM + GMR

TSMC180 + GMR

Mixed signal CMOS design

Redundant flash ADC

Quasi-digital dC-to-t converter

UMC180

TSMC180

Device modeling

a) b) c)

- Compact Electrical
- FEM (multiphysics)
- Thermal
- Magnetic
- Microfluidics

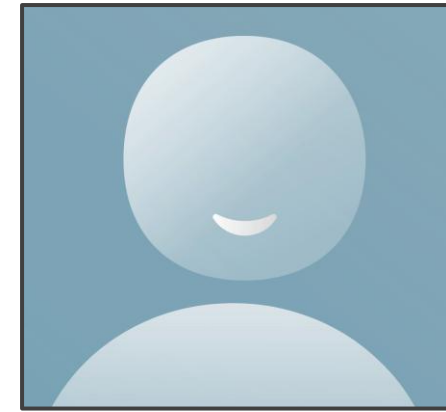
Test + characterization

- I/V, f (also RF)
- Noise
- Thermal
- Magnetic
- Microfluidics

LabVIEW

MATLAB

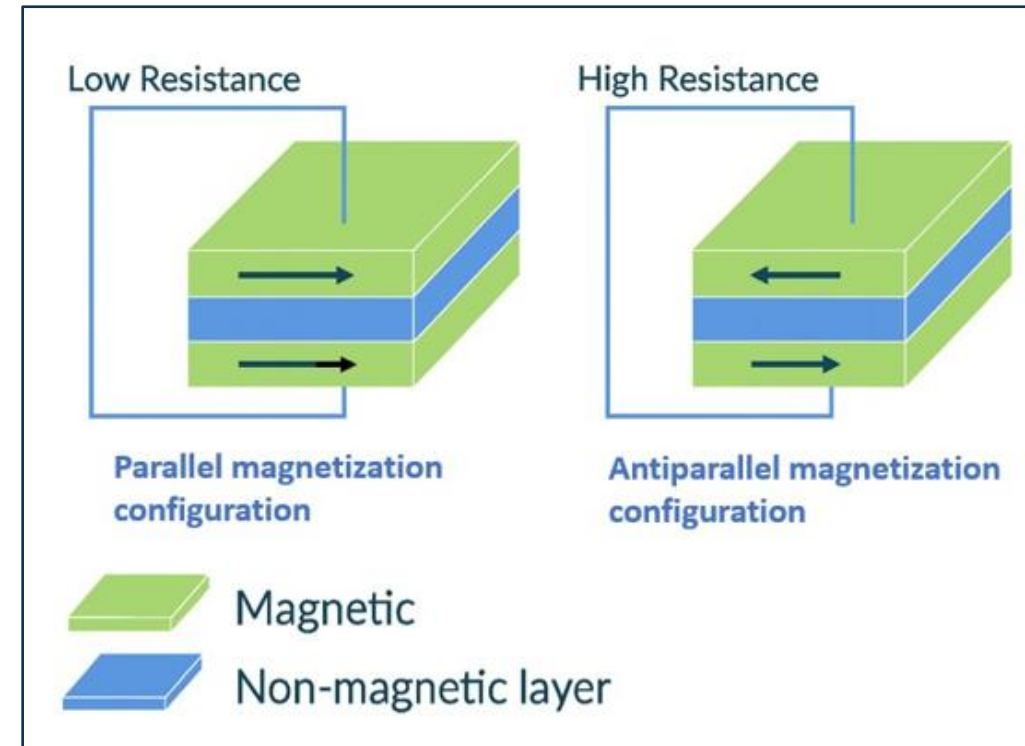
Giant Magnetoresistive Sensors



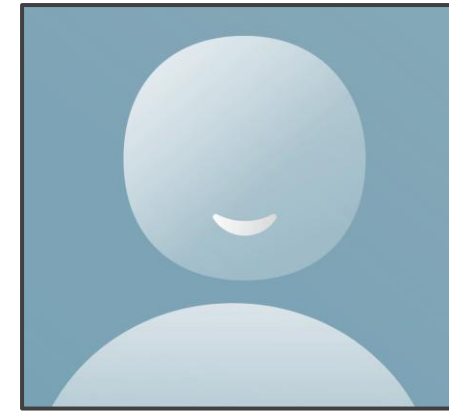
Multilayered materials, alternating thin films of ferromagnetic and non-magnetic metals
Resistance value is **inversely** proportional to magnetic field

Advantages

- Compatible with CMOS process
- Precisely designable resistive sensors



Aims and Contributions of our Paper



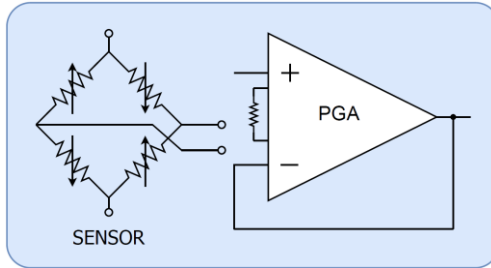
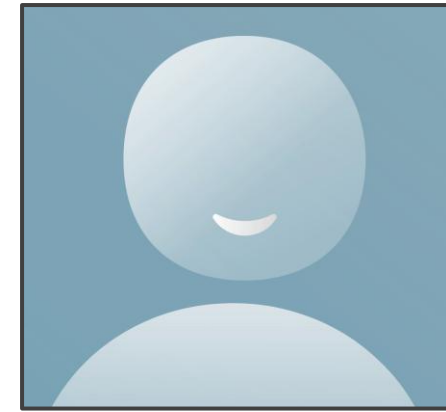
In our paper we aimed at:

1. developing a Selective Change-Driven interface for magnetic sensing and,
2. evaluating its capability for efficient detection and tracking magnetic particles.

Contributions:

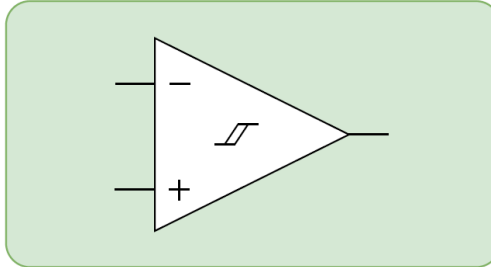
1. we designed and implemented a 1x8 GMR-based interface in CMOS technology,
2. validated the system through Cadence Virtuoso simulations using both electrical stimuli and synthetic magnetic signals generated via particle modeling,
3. we demonstrated the utility of event-driven magnetic sensing for reducing data redundancy and enabled efficient particle tracking applications.

Analog Building Blocks



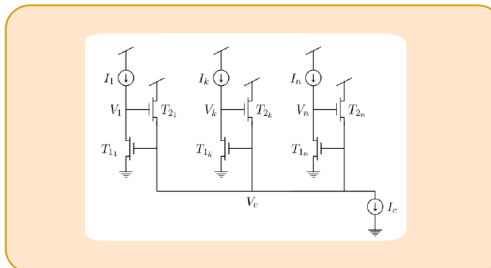
Sensing and Conditioning

Adjustable transconductance
Dynamic baseline



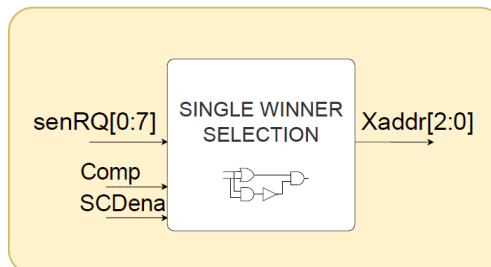
Capacitive Comparator

DC Isolation
Dynamic Sensitivity



WTA ON / OFF

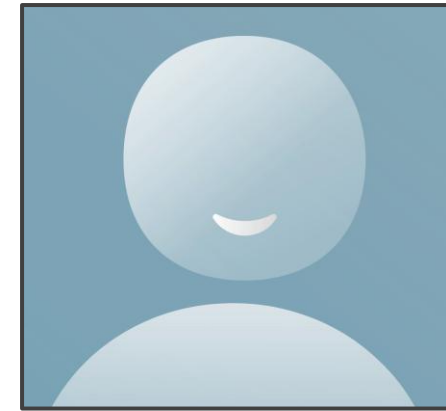
Detects strongest positive or negative variation



Logic & Addressing

Single Winner selection
Asynchronous event handling

Validation I - Pulse excitation



Objective

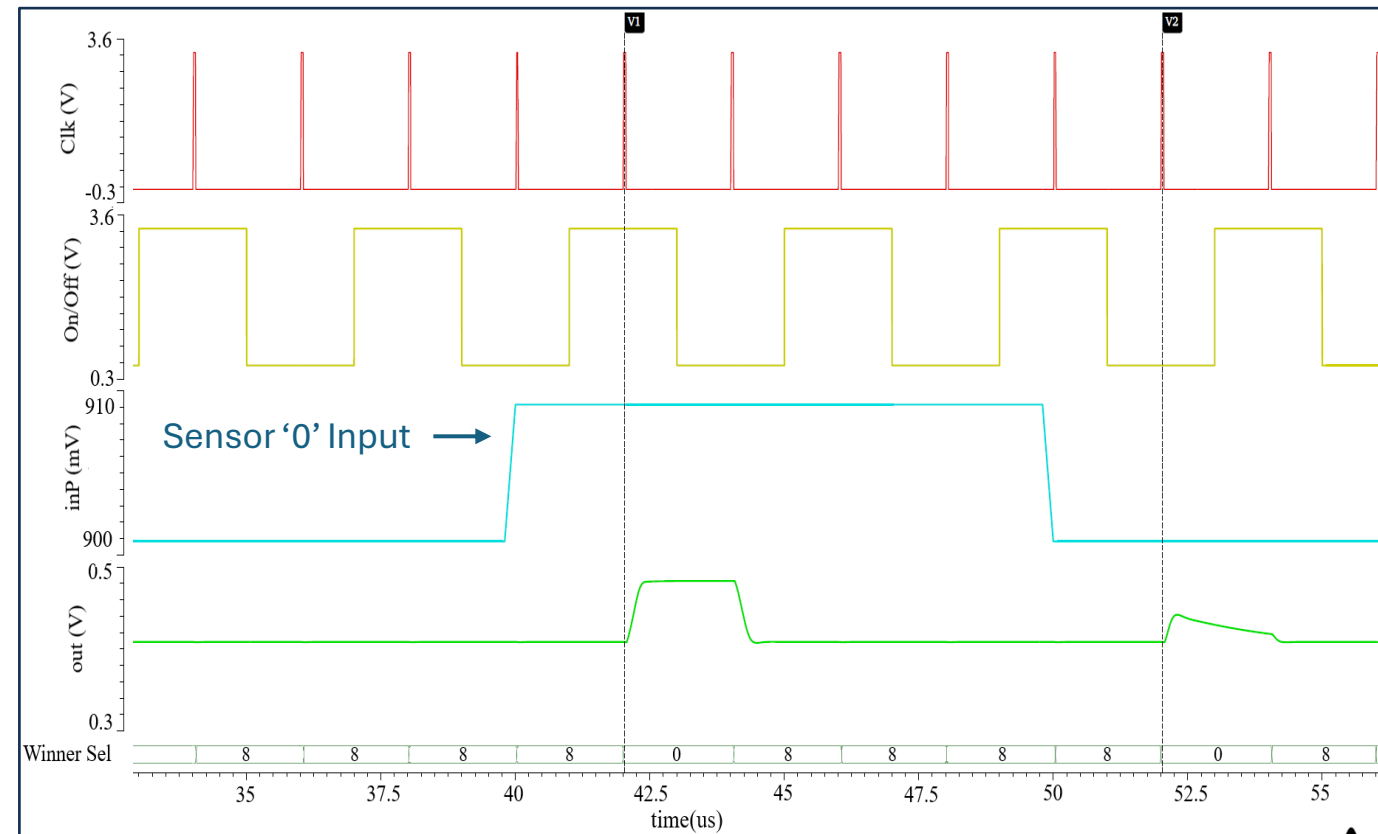
Validate the winner-selection logic and timing behavior of the SCD architecture.

Method

Cadence Virtuoso Spectre simulation
Sequential square pulses applied to each node

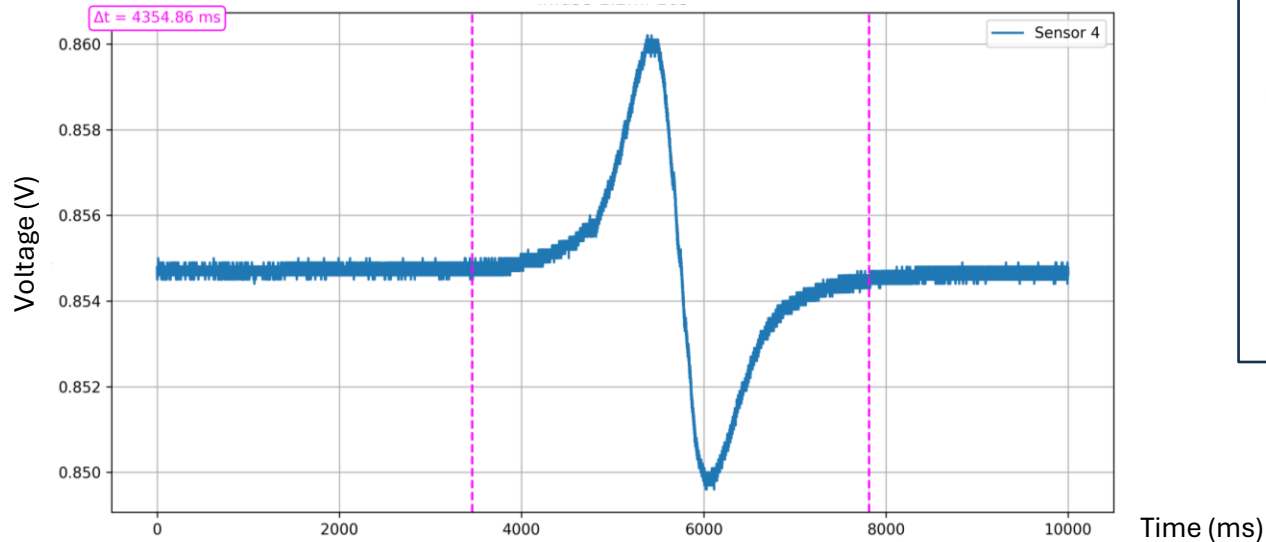
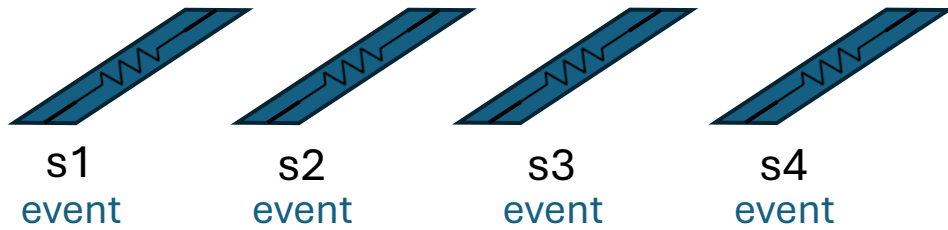
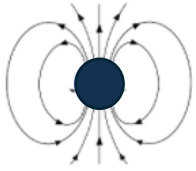
Verification

Correct WTAON / WTAOFF operation
Sequential winner identification

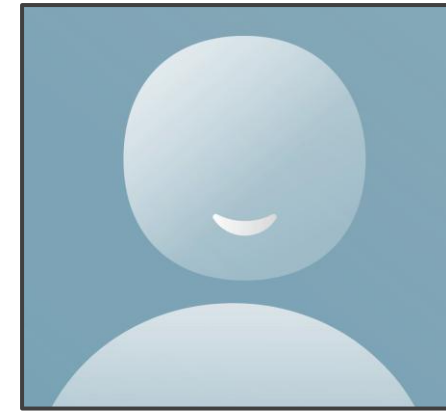


Possible Applications

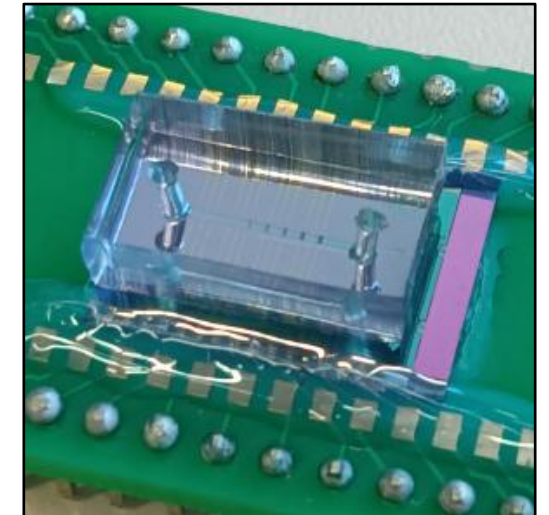
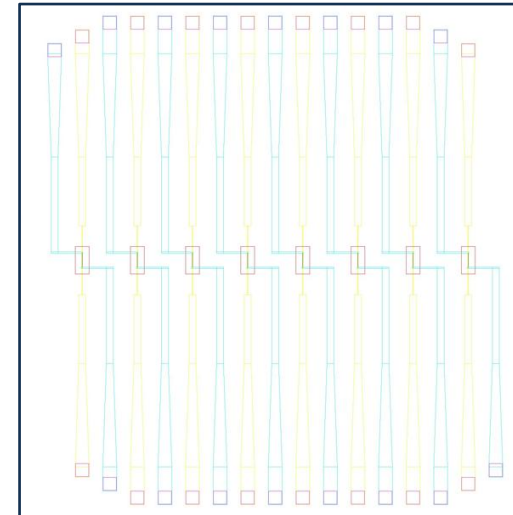
Magnetic particle tracking & Modeling



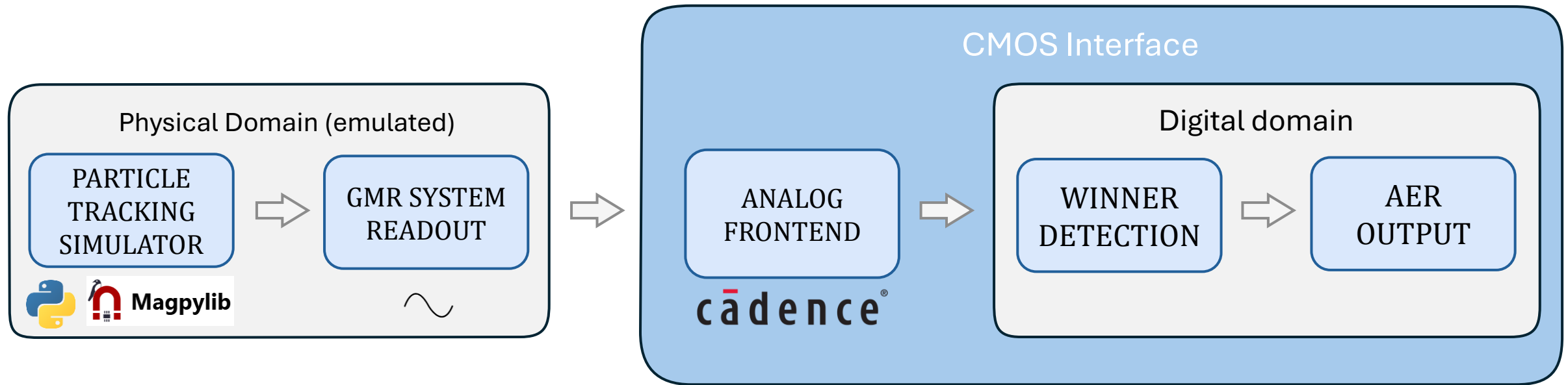
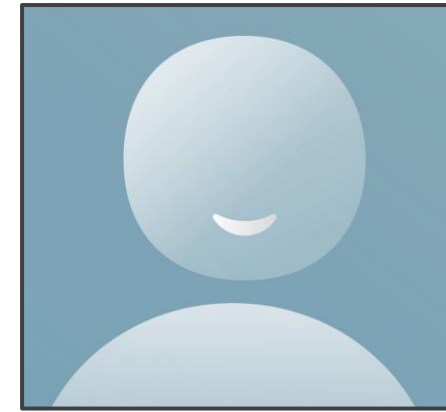
GMR Sensor response to flowing magnetic particle. Electrical signal



Microfluidics



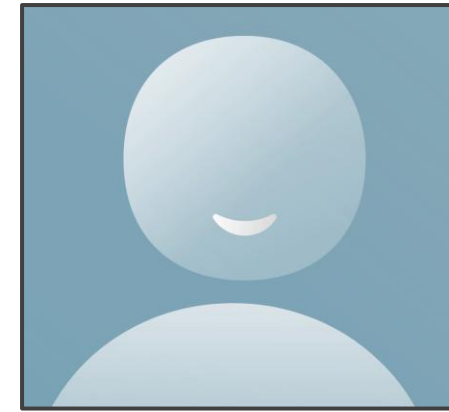
Emulated Particle Tracking Pipeline



Validated outputs

- Particle localization
- Sequential event generation
- Real-time particle tracking

Conclusions and Future Work



Conclusions

We developed and validated a neuromorphic interface for resistive sensors

We demonstrated the proper function of the system and its capabilities by use of Cadence/Virtuoso

We tracked and identified magnetic particles

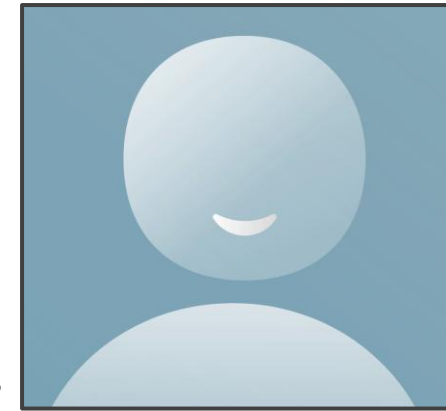
Future work

Transition from simulation to physical prototyping.

Tape-out in 180 nm CMOS chip to characterize the impact of thermal noise and substrate coupling.

The integrated system will be validated within a microfluidic setup.

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