



International Academy, Research, and Industry Association

# Best Paper Award

A ROS 2-Based Architecture for Indoor 3D Mapping and Autonomous Navigation with Azure Kinect and LiDAR

By

Itziar Goretti Alonso González, Miguel Ángel Quintana-Suárez, David Sánchez-Rodríguez, Valeria Santana-Cardona, Francisco José Cazorla-Hernández

Presented during ICWMC 2026, The Twenty-Second International Conference on Wireless and Mobile Communications, held in Valencia, Spain during March 8-12, 2026

IARIA Board

