Design of Infrastructure-Based Prescriptive Control Use Cases in CAV

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Speaker Introduction

- **Ki Hun Jang** received the **Ph.D. degree** in transportation engineering from Ajou University, South Korea, in 2021.
- His doctoral dissertation was titled "A Study on the Development of Estimation Model for Emergency Vehicle Travel Time using Deep Learning Model."
- He is working at ITS Korea, where he is actively involved in various fields including autonomous driving, data-driven analysis, and ITS innovation projects.

1.1 Related Project Overview

Initiative name

Korea Autonomous driving Development Innovation (Korean National Police Agency)

Project name

Development of Transportation Safety Infrastructure Standard and Evaluation Technology for Lv.4 Connected Autonomous Driving

Project Period

 $2021.04.01 \sim 2026.12.31$ (5 years and 9 months)

Reserch Objectives Development of Traffic Safety Device(TSD) Infrastructure Standards Considering

Lv.4 Autonomous Cooperative Driving and Coexistence with Normal Vehicles

Integrated Architecture for Autonomous Driving TSD 02

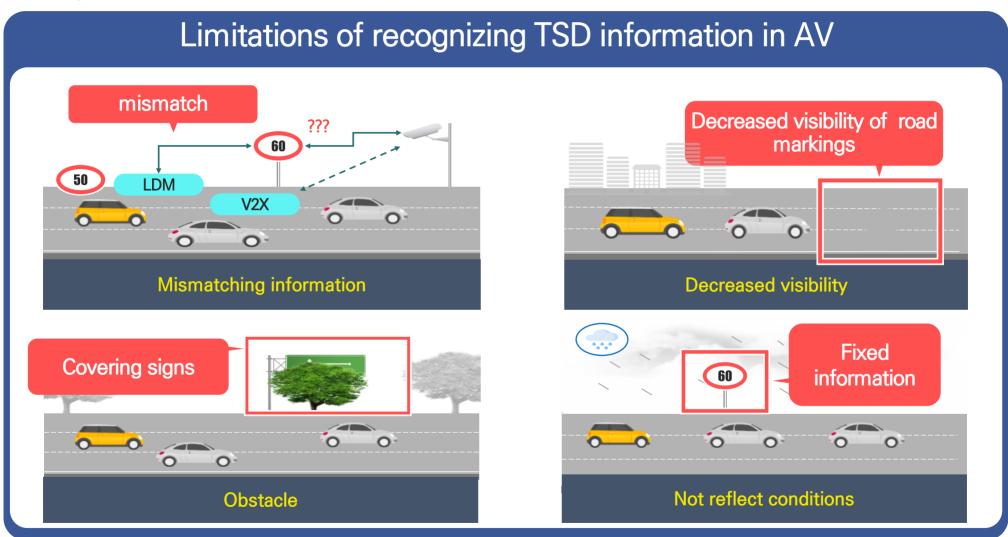
Level4 TSD Infrastructure Standard Development TSD Infrastructure

Prescriptive Control
Strategies for Cooperative
Autonomous Driving



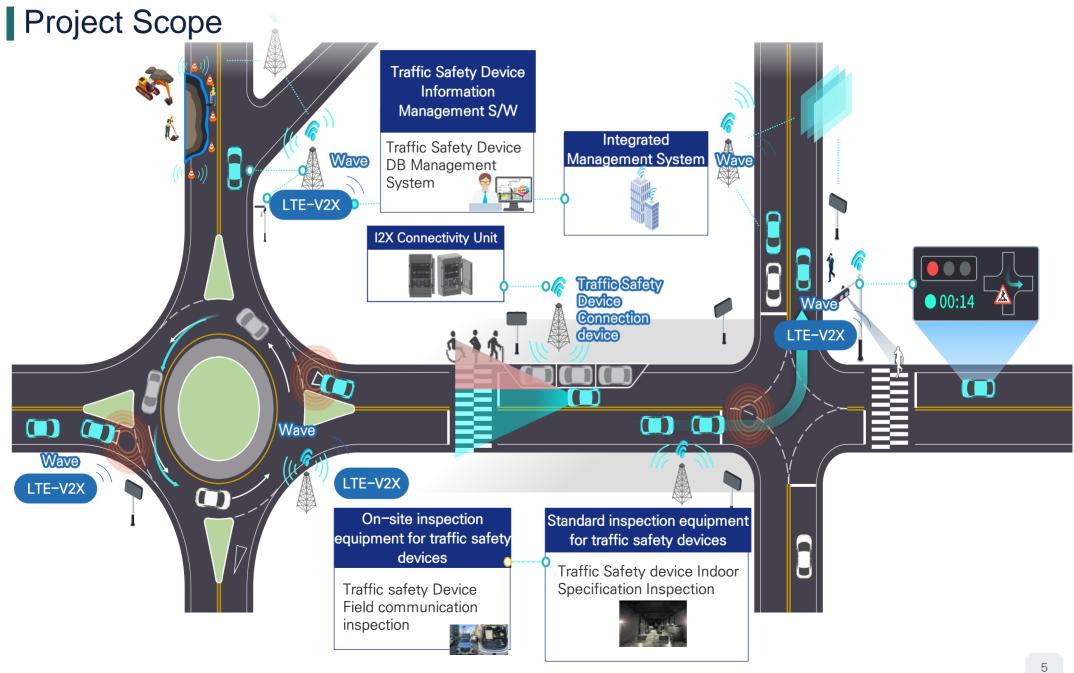
1.1 Related Project Overview

Background



X Traffic safety device(TSD): Infra to prevent car accidents and ensure smooth traffic flow (Applicable to traffic lights, safety signs, road markings)

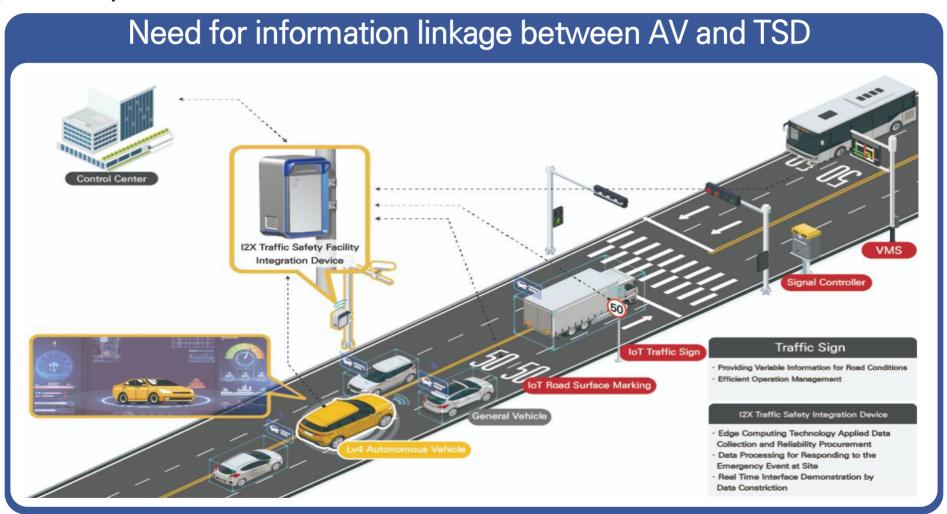
Related Project Overview





1.1 Related Project Overview

Project Scope



Need for Traffic Safety Device to improve automated driving safety

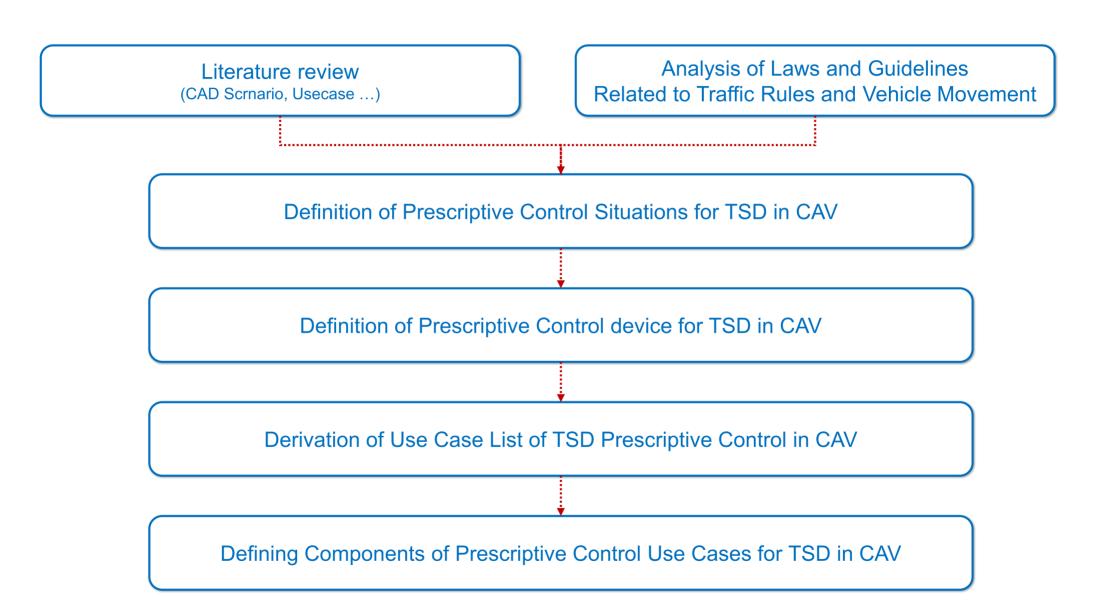
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1.2 Research Purpose



Need for Dynamic TSD Information Provision to Respond to Dynamic Situations

1.3 Methodology





2.1 Review

For safe AV, providing traffic safety device information through infrastructure is essential

Literature review



- •AV is supported by providing information such as speed, lane change, priority, and signal control during events like congestion or emergencies
- Delivered via V2I / LDM
- VMS informs normal vehicles in mixed traffic

Laws/Guidelines



- Road Traffic Act defines rules only for human-driven vehicles
- AV-specific regulations are not clearly defined
- Government and police require AVs to recognize and respond to TSD via infrastructure (e.g., V2I)



3.1

Definition of Prescriptive Control Situations for TSD

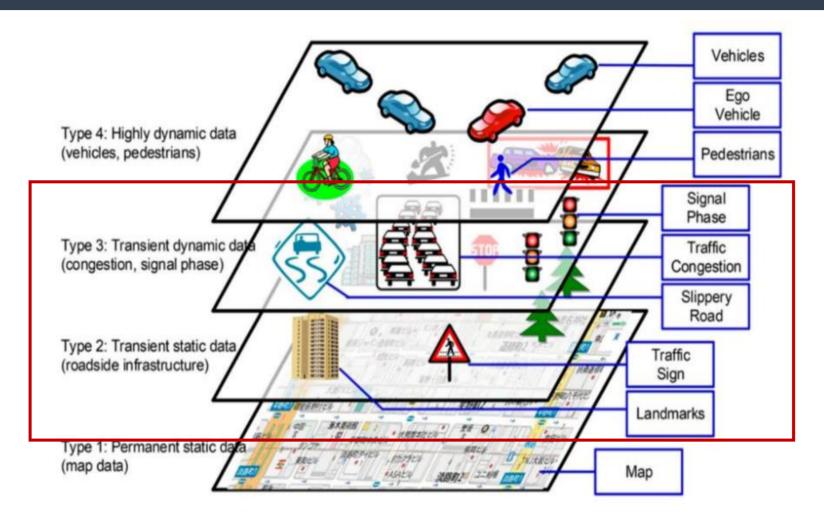
6 Situations Requiring Prescriptive Control Derived from the Road Traffic Act

Situation	Prescriptive Traffic control methods
Entering an Intersection	Slow/Stop, Yield, Counterclockwise movement
Traffic Congestion	Speed limit, No entry(temporarily), Shoulder driving
Traffic Accident / Obstacle	 Lane change within prohibited zone, Speed limit, No entry(temporarily)
Road Construction	Speed limit, Center/Left side driving, No entry(temporarily)
Adverse weather conditions	Speed reduction
Emergency Vehicles Operation	 Center/Left side driving, Priority for emergency vehicles, Shoulder driving, Crossing, U-turn, reverse driving



3.2 Definition of the Scope and Devices for Prescriptive Control of TSD

(Control Scope) Utilization of information corresponding to LDM* Layer 2 and Layer 3



^{*}LDM (Local Dynamic Map): A system that collects, stores, and processes various traffic—related dynamic data in real time based on a high—definition map (static information), and provides services for autonomous driving and C-ITS (Cooperative Intelligent Transport Systems).



3.2 Definition of the Scope and Devices for Prescriptive Control of TSD

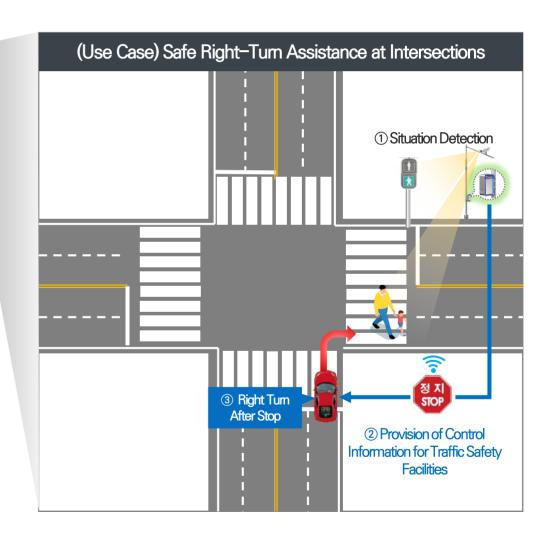
(Control Devices) By reviewing relevant regulations, 27 TSDs directly related to vehicle traffic were selected out of 297

	Category	Controllable Traff	ic Safety Devices
	Waming sign	During Road Construction, Traffic Priority, etc.	
Safety	Regulatory sign	Traffic prohibition, entry restriction, speed limit, stop requirement, straight—ahead prohibition, etc.	통행금지 전입금지 50 정지 STOP
signs	Guide sign	Go straight, right turn, left turn, U-turn, detour, one-way traffic, etc.	
	Supplementary sign	Distance, zone, date, time, safe speed, traffic regulations, traffic restrictions, etc.	100m 앞 부터 안전속도 시 내 전 역 차로엄수 건너가지마시오
Road	Regulatory sign	Center line, lane, exclusive lane, straight—ahead prohibition, speed limit, etc.	40
markings	Guide sign	Guidance, direction of travel, lane change, etc.	
	Traffic light	Traffic light	



19 Use Cases Derived for TSD Infrastructure-Based Prescriptive Control

			Geometric Structure		
Situation	No.	Information Control	Road Type	Number of Lanes (One-Way)	
Entering an Intersection	1	Safe Passage Support	Intersection	One or More Lanes	
	2	Variable Speed Limits and Speed	Single-Lane Road	One or More Lanes	
	3	Recommendations	Unsignalized Intersection	One or More Lanes	
Traffic Congestion	4	Lane Change Recommendation	Signalized Intersection	Three or More Lanes	
	5	Safe Passage Support	Unsignalized Intersection	One or More Lanes	
	6			One Lane	
	7	Lane Change Recommendation	Single-Lane Road	Two or More Lanes	
Traffic Accidents / Obstacles, etc.	8			Three or More Lanes	
	9	- Detour Guidance (Road Closure) -	Signalized Intersection	One or More Lanes	
	10	Detodi Guidalice (Hoad Ciosule)	Single-Lane Road	Two or More Lanes	
Road Construction	11	Lane Change Recommendation	Single-Lane Road	Two or More Lanes	
nodu Coristi uction	12	Detour Guidance	Signalized Intersection	One or More Lanes	
	13	Variable Speed Limits and Speed	Single-Lane Road	One or More Lanes	
Severe Weather	14	Recommendations	Single-Lane Road	One or More Lanes	
Conditions	15	Detour Guidance (Road Closure)	Underpass	Two or More Lanes	
	16			One Lane	
Emorgona (Vobiolo	17	Lane Change Recommendation	Single-Lane Road	Two or More Lanes	
Emergency Vehicle Operation	18	- Safe Passage Support	Signalized Intersection	One or More Lanes	
	19	odie i dosage ouppuit	Unsignalized Intersection	One or More Lanes	





Adverse weather conditions - Variable Speed Limit and Speed Recommendation

	Elements			Content	:s	
	Category		As-is		To-be	
Overall Situation Diagram	Traffic Safety Sign		☐ ② Ego Ve		에에 (국) (A)	Ego Vehicle
	Road Marking		80 80		40 40	9 4 (E) 4 (E)
	Туре		Traffic Safety Sign	F	Road Markings	Traffic Light
	Classification		Regulation	Regulation		-
Traffic Safety Device	Attributes		Maximum Speed Limit (No. 224) Keep Safe Distance (No. 223)	Speed Limit (Sign No. 517)		-
	Attribute Information	Before Control	100km/h		100km/h	-
		After Control	80km/h(40m) → 60km/h(30m)	80	0km/h → 60km/h	-



Traffic Accident – Lane change instruction

Elements			Contents			
	Overall Situation Diagram Category Traffic Safety Sign + Road Marking		As-is		To-be	
Situation			Traffic Accident Traffic Accident	ehicles		Ego Vehicle : Surrounding vehicles Fraffic Accident
	Туре		Traffic Safety Sign		Road Markings	Traffic Light
	Classification		Regulation		Prescriptive	-
Traffic Safety Device	Attributes		Stop(227)		Centerline(501)	-
	Attribute Information	Before Control	Driving		Yellow solid line	-
		After Control	Stop		Yellow dashed line	-



■ Emergency Vehicles Operation – Safe Passage Support

Elements			Contents			
	Category		As-is		To-be	
Overall Situation Diagram	Traffic Safety Sign		Ego Vehicle	/ehicle	Emergency Vehicle	
	Road Marking				전임금지	
	Туре		Traffic Safety Sign	Road Markings	Traffic Light	
	Classification		Regulation	Regulation	-	
Traffic Safety Device	Attributes		No entry(211)	No entry(546)	-	
	Attribute Information	Before Control	Entry permitted	Entry permitted	-	
		After Control	No entry	No entry	-	

4.1 Conclusion

- Need for TSD-based Prescriptive Control to complement sensor limitations in cooperative autonomous driving
- 6 Prescriptive control situations & 19 use cases derived based on the Road Traffic Act
- This enhances the safety and reliability of autonomous vehicles and supports the establishment of traffic operation and management strategies
- However, real-time TSD information integration and reliable V2I communication are still required
- Future work includes message specification design, TSD priority setting, guideline development, and testbed validation.

4.2 Future Work

Define message specifications for each use case

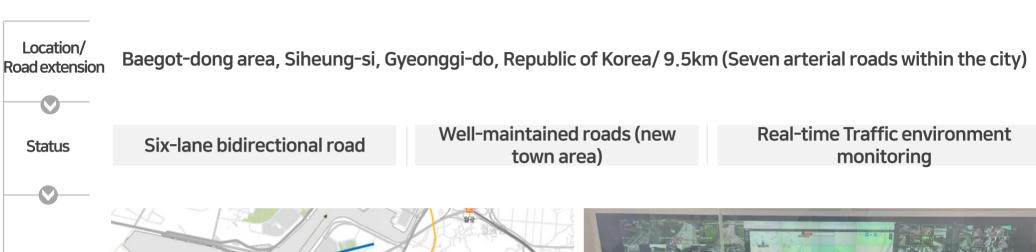
Plan to utilize ITIS codes within SAE J2735 messages (e.g., TIM, MAP, SPaT)

Message	TIM (SAE J2735)					
		DF_dataFrames DF_startTime_ DE_MinutOfTheYear				
	Message Generation Time	MinuteOfTheYear ::= INTEGER (0527040)				
		the value 527040 shall be used for invalid				
	Message Duration	DF_dataFrames DF_duratontime DE_MinutesDuration				
	Wessage Daration	MinutesDuration ::= INTEGER (032000) units of minutes				
		DE_extent (ENUMERATED (015))				
	Massaga Application	Extent ::= ENUMERATED				
Message	Message Application Distance	useInstantlyOnly (0),				
Components		useFor3meters (1),				
Componente		useFor10meters (2),				
		DF_ITIS_Phrase_SpeedLimit, DE_EXT_ITIS_Codes [ITIS]				
		ITIS Code 268, <num>, Kph, 8721, 13588 (今도)</num>				
		{SpeedLimit ::= SEQUENCE (SIZE(116)) OF SEQUENCE				
	Speed Limit Change	item CHOICE				
		itis ITIScodes,				
		text ITIStextPhrase},				
		ITIScodes ::= INTEGER (0 65535)				
Situation	Traffic congestion					
Oitation	Adverse weather conditi	Adverse weather conditions				

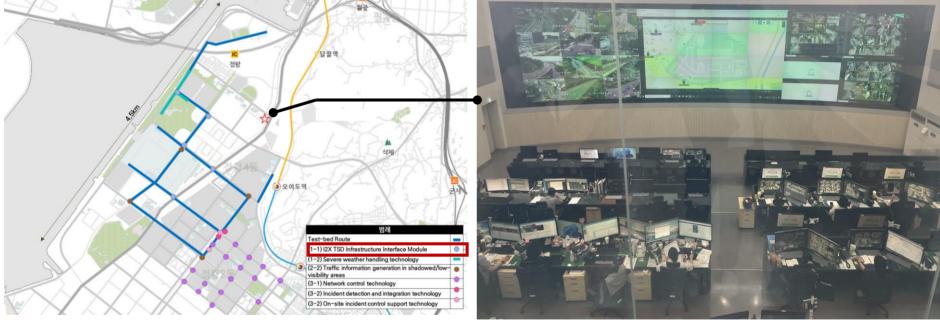


4.2 Future Work

Testbed demonstration



Construction Overview



<T.B Location>

<Siheung Urban Integrated Information Center control room>

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Thank you for your attention!



