AIMEDIA2025, The First International Conference on AI-based Media Innovation

A Novel Synthetic Dataset for Broadcast Motorsports Scene Understanding

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Presenter

Luca Francesco Rossi

	Ph.D. candidate in Ingegneria Informatica E Dei Sistemi , 39 th cycle (2023-2026) Department of Control and Computer Engineering (DAUIN) Docente esterno e/o collaboratore didattico Department of Control and Computer Engineering (DAUIN) Image: state of the state of t	Profile
		Teaching
		Research
		Publications

programme path as **executive Ph.D.** built on an **industrial collaboration** with <u>netventure</u>, a company specializing in live broadcast graphics, augmented reality, and virtual graphics for international sporting events, live shows, and entertainment productions worldwide.

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Scenario and motivations

Al solutions are increasingly being customized to serve the needs of the automotive, healthcare, finance, <u>entertainment</u>, and other industries:

- > computer vision as a tool to perceive and understand the surrounding environment;
- shifting from vanilla recognition to a more proactive comprehension of the scene.



Share of fans who regularly watch sports at a venue in selected countries

Share of sports fans who regularly visit a stadium worldwide as of April 2023, by age



worldwide as of April 2023 Sports fans who watch sports in-venue worldwide 2023



Scenario and motivations

"25% of respondents **use AI**, a significant rise from just 9% in the 2024 report, **highlighting its growing adoption** in broadcast workflows."

HAIVISION, "AI in Broadcast: Current & Future Applications", in 2025 Broadcast Transformation Report, p. 16

- huge opportunities for motorsport racing;
- lack of common benchmarks or **publicly available** datasets;
- bridge the gap between industrial and academic solutions;

Synthetic data generation to provide a standardized setting.





CARLA – Car Learning to Act

- UE5-based open-source simulator for autonomous driving research.
- Support for training, prototyping and validation of autonomous driving models, including both perception and control.
- flexible setup of sensor suites.



Dosovitskiy, A., Ros, G., Codevilla, F., Lopez, A. and Koltun, V. (2017). CARLA: An Open Urban Driving Simulator. Proceedings of the 1st Annual Conference on Robot Learning, in Proceedings of Machine Learning Research 78:1-16 Available from https://proceedings.mlr.press/v78/dosovitskiy17a.html



Synthetic data generation

Goal: fully-automated pipeline.

- A. RGB frame capture
- B. 3D bounding boxes detection
- C. 2D bounding boxes **estimate**
- D. 2D bounding boxes refinement via segmentation
- E. LiDAR point cloud for keypoint **visibility**
- F. Detection and pose merge









Bridging the gap

TABLE I. SYNTHETIC	DATASET METRICS	FOR BROY	DETECTION
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Split	P_B	R_B	$mAP50_B$	mAP50-95 _B
Validation	0.952	0.793	0.897	0.793
Test	0.962	0.773	0.884	0.784

TABLE II. SYNTHETIC DATASET METRICS FOR POSE ESTIMATION.

Split	P_P	R_P	$mAP50_P$	mAP50-95 _P
Validation	0.924	0.728	0.842	0.816
Test	0.918	0.716	0.827	0.795



Synth2Real adaptation: disparity in performance between synthetic and realdomain data.

Addressing the reliability of the generated dataset via **transfer learning** on a real dataset comprising 293 frames from Mexico City ePrix (**train**) and 42 frames from Portland ePrix (**validation**).

Nikolenko, Sergey I. (2021). Synthetic Data for Deep Learning. In Springer Optimization and Its Applications, Springer Cham. Series ISSN: 1931-6828, under exclusive license to Springer Nature Switzerland AG 2021, doi: 10.1007/978-3-030-75178-4



Bridging the gap (broadcasting)



Reverse-engineer the PnP problem to achieve 3D orientation from pose in real-time.



Next steps

Future research should prioritize the development of advanced **domain adaptation strategies**, and the integration of **physics-based simulations** to further mitigate the domain gap:

- enhancing the fully automated generation pipeline to produce even more reliable synthetic data,
- incorporating additional detection classes to facilitate livery recognition (thus mitigating the often-biased distribution of real-world data).





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