



International Academy, Research, and Industry Association

Best Paper Award

Performance Improvement of Loop Closure Detection Using Semantic
Segmentation in LiDAR SLAM

By

Shuya Muramatsu, Masafumi Hashimoto, Kazuhiko Takahashi

Presented during ALLSENSORS 2025, The Tenth International Conference on Advances in Sensors, Actuators,
Metering and Sensing, held in Nice, France during May 18 - 22, 2025


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