



## Replicating the Nature of Cooperative Behavior in the First-Person Perspective Task

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- Cooperative behavior is important in crossing interactions
  - Everyone can move bidimentionally (Weifeng et al., 2003)
  - It is not clear who has priority to cross (Uttley et al., 2020)



Shibuya Crossing in Japan





- Our previous study (Matsubayashi et al., 2024)
  - Bird's-Eye Perspective (BEP) experiment
  - Participants were asked to reach their goals through a space with **autonomous others**
  - Participants were given cooperative, nonurgent, or urgent intentions





Blue: Self-agent (participant) Gray: Autonomous others

	Cooperative	Nonurgent	Urgent
Completion time	+	++ ;	—
Amount of interruption		   /	+

Summary of Results of One-sample *t*-tests and ANOVA

- Nature of cooperative behavior:
  - Reduce interruption to others
  - Reach goals earlier compared to nonurgent behavior
- → providing **other's benefit**
- $\rightarrow$  providing **self-benefit**





 Can the nature of cooperative behavior be reproduced in a First-Person Perspective (FPP) experiment?





- Effect of perspective on moving behavior
  - FPP is difficult to accurately understand the positional relationship in a maze task (Nakanishi et al., 2010)
    - $\rightarrow$  FPP will make it difficult to move smoothly
    - $\rightarrow$  Cooperative behavior will not reduce interruption in FPP
- Effect of perspective on **psychological response** 
  - Virtual experience in the FPP elicits stronger emotional experiences (Gonzalez-Liencres et al., 2020)
    - $\rightarrow$  FPP will evoke a stronger motivation of cooperation
    - $\rightarrow$  Cooperative behavior will also reduce interruption in FPP





1<sup>st</sup> person condition











- Participants
  - 24 participants (*M*<sub>age</sub> = 48.08, *SD*<sub>age</sub> = 12.18)
- Stimulus
  - Driving simulator with 7 displays using Unity
  - Same joystick as BEP experiment
- Procedure
  - Almost same as BEP experiment
  - Independent variable: Instruction
    - Cooperative "Reach your goal while considering others"
    - Nonurgent "You have enough time and can go to your goal slowly"
    - Urgent "You do not have enough time and should reach your goal fast"
  - Dependent variable: Performance
    - Completion time
    - Amount of interruption









• Completion time

• Amount of interruption



Values indicate the differences from baseline with no instruction





- The trend of cooperative behavior could also be observed in FPP
  - Reduce completion time and interruption
- However, there were no salient differences from nonurgent behavior
  - Do not reduce completion time and interruption as much as nonurgent behavior



Summary of Results of One-sample t-tests and ANOVAs





- The basic nature of cooperative behavior was replicated in FPP experiment
  - Reduce interruption to others

• Reach goals earlier compared to nonurgent behavior  $\rightarrow$  providing self-benefit

- However, there were no salient difference between cooperative and nonurgent behaviors in FPP experiment
  - Why? FPP is difficult to accurately understand the positional relationship (Nakanishi et al., 2010)
    - FPP makes it difficult to notice others approaching from the left or right, or to identify the path to goals





FPP

 Participants might attempt to gain more positional information by making large turns, which leads to an increase in completion time

 $<sup>\</sup>rightarrow$  providing **other's benefit** 





- In general, it is difficult to verify human valid and reliable behavior in low-fidelity environments
  - e.g., game, training system, low-cost simulator
- However, moving behaviors were almost identical in our BEP and FPP experiments
  - BEP experiment is useful enough to verify moving behavior
  - Such low-fidelity environments have the advantage of facilitating factor control
     → We can obtain more insights about moving behavior using BEP experiment







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