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On the Regularization of a Low-Complexity Recursive Least-Squares Adaptive Algorithm

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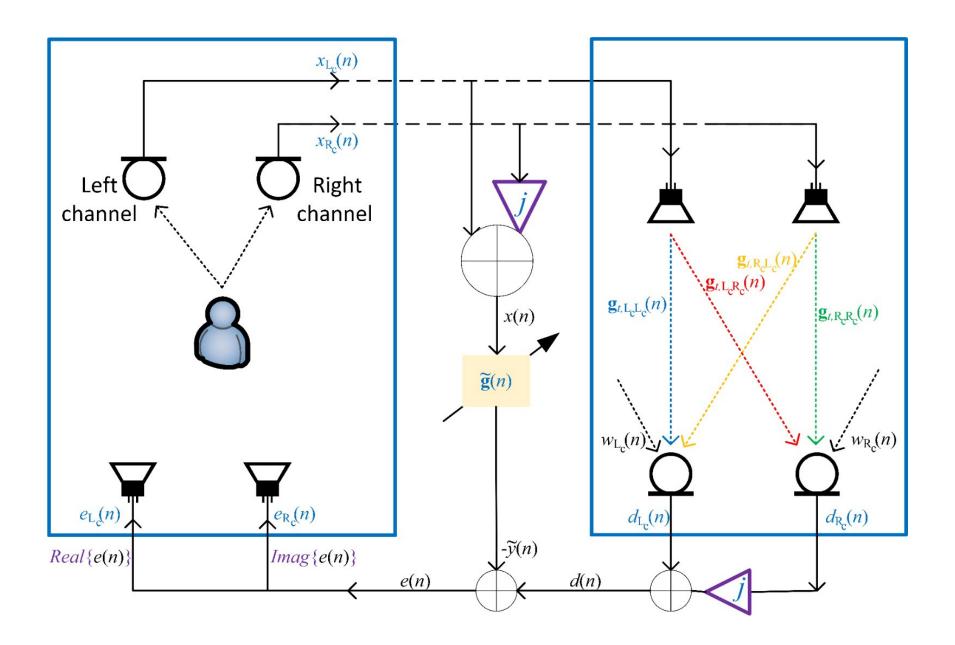
Summary

- Introduction
- System Model WL Framework
- WL-RLS-LSM
- VR-WL-RLS-LSM
- Simulation Results
- Conclusions

Introduction

- Stereophonic Acoustic Echo Cancellation (SAEC):
 - Estimation of 4 echo paths => the loudspeaker-to-microphone pairs
- The LMS method (standard approach):
 - 4 individual systems => low arithmetic complexity and limited performance for highly correlated signals due to gradient noise
- The WL-RLS-LSM algorithms:
 - Complex-valued line search methods
 - Solve an auxiliary system of equations
 - Have a key parameter performance vs complexity
- The VR-WL-RLS-LSM algorithms:
 - Improved performance for small echo-to-noise (ENR) values
 - Improved performance when double-talk (DT) situations occur

System Model – WL



WL-RLS-LSM

$$\mathbf{R}(n)\mathbf{g}(n) = \mathbf{p}(n)$$
 \mathbf{RLS} $\tilde{\mathbf{g}}(n)$ • Classical Approach• Direct Solution

$$\mathbf{R}(n)\Delta \mathbf{g}(n) = \mathbf{p}_{0}(n)$$
• LSM Approaches
$$\mathbf{p}_{0}(n+1) = \lambda \mathbf{r}(n) + \mathbf{x}(n+1)e(n+1)$$

$$\mathbf{R}(n+1)\Delta \mathbf{g}(n+1) = \mathbf{p}_{0}(n+1)$$

$$\mathbf{r}(n+1), \mathbf{\tilde{g}}(n+1)$$

$$\mathbf{R}(n)\Delta\mathbf{g}(n)=\mathbf{p}_0(n)$$

$$\mathbf{R}(n)\Delta\mathbf{g}(n) = \mathbf{p}_0(n)$$

$$k > 1$$
? $\mathbf{d} \leftarrow \mathbf{r} + \frac{\rho_{k-1}}{\rho_{k-2}} \mathbf{d}$

$$\mathbf{R}(n)\Delta\mathbf{g}(n) = \mathbf{p}_0(n)$$

$$\alpha \leftarrow \frac{\rho_{k-1}}{\mathbf{d}^{\mathrm{H}} \mathbf{R}_{\tilde{\mathbf{x}}}(n) \mathbf{d}}$$

$$\mathbf{R}(n)\Delta\mathbf{g}(n) = \mathbf{p}_0(n)$$

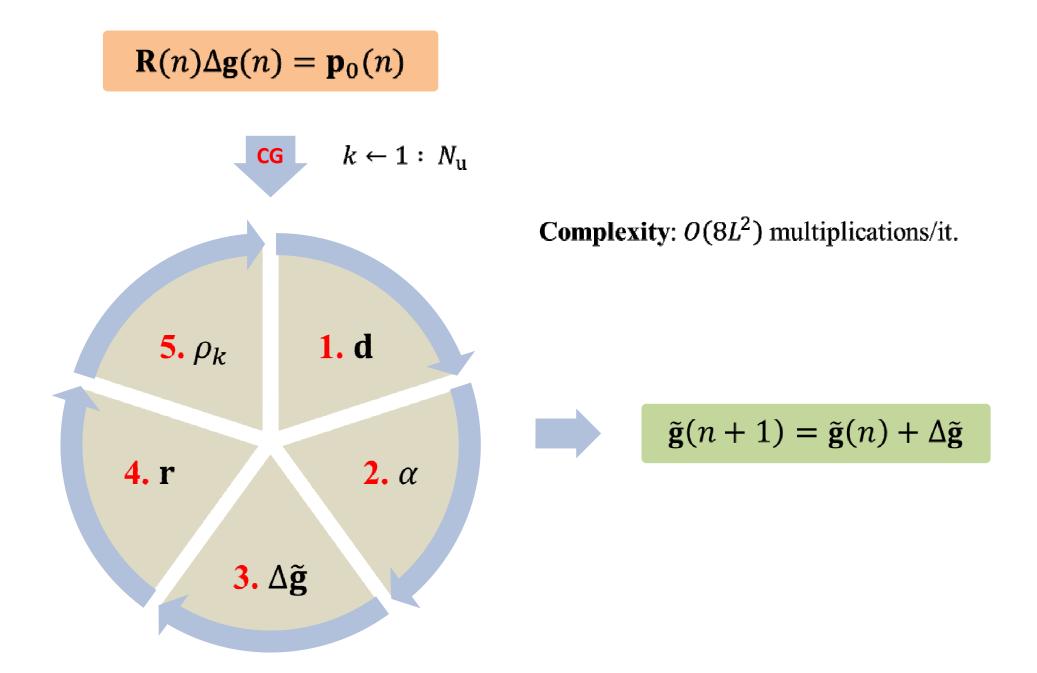
$$\Delta \tilde{\mathbf{g}} \leftarrow \Delta \tilde{\mathbf{g}} + \alpha \mathbf{d}$$

$$\mathbf{R}(n)\Delta\mathbf{g}(n) = \mathbf{p}_0(n)$$

$$\mathbf{r} \leftarrow \mathbf{r} - \alpha \mathbf{R}_{\tilde{\mathbf{x}}}(n) \mathbf{d}$$

$$\mathbf{R}(n)\Delta\mathbf{g}(n) = \mathbf{p}_0(n)$$

$$\rho_k \leftarrow \mathbf{r}^{\mathrm{H}} \mathbf{r}$$



Dichotomous Coordinate Descent

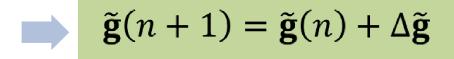
	$\mathbf{R}(n)\Delta\mathbf{g}(n) = \mathbf{p}_0(n)$		Complexity : no multiplications/it.		
$\Delta \tilde{\mathbf{g}} \leftarrow 0_{2Lx1}$ $\mathbf{r} \leftarrow \mathbf{p}_0(n)$ $k \leftarrow 1 : N_u$					
$\begin{array}{c} \alpha \ \leftarrow H \\ m \ \leftarrow 0 \end{array}$	Step	A	ction		
	1	$ \{val_1; pos_1\} \leftarrow \max_{i=1\dots 2L} \{ Re\{r_i\} \} $ $ \{val_2; pos_2\} \leftarrow \max_{i=1\dots 2L} \{ Im\{r_i\} \} $ $ (p;\eta) \leftarrow (val_1 > val_2) ? (pos_1; 1) : (pos_2; j) $ $ \textbf{Jump to step 4} $			
	2	$\alpha \leftarrow \alpha/2$;	$m \leftarrow m + 1$		
	3	If $(m > 1)$	M _b) RETURN		
	4	$r_{temp} \leftarrow (\eta == 1)$) ? $Re\{r_p\} : Im\{r_p\}$		
	5	If $\left(\left r_{temp}\right \le \frac{\alpha}{2}\right)$	$(R_{p,p})$ Jump to step 2		
6		$\Delta \tilde{g}_{p} \leftarrow \Delta \tilde{g}_{p}$ -	⊦ sign{r _{temp} }ηα		
	7	$\mathbf{r} \leftarrow \mathbf{r} - \operatorname{sign}\{$	r_{temp} } $\eta \alpha \mathbf{R}^{(p)}(n)$		$\tilde{\mathbf{g}}(n+1) = \tilde{\mathbf{g}}(n) + \Delta \tilde{\mathbf{g}}$

Variable Regularization



 $[\mathbf{R}(n) + \phi(n)\mathbf{I}_{2L}]\Delta \mathbf{g}(n) = \mathbf{p}_0(n)$

$$\Phi(n) = 2L\widetilde{\sigma}_x^2(n)(1+\sqrt{1+\widetilde{\mathrm{ENR}}})/(\widetilde{\mathrm{ENR}})$$

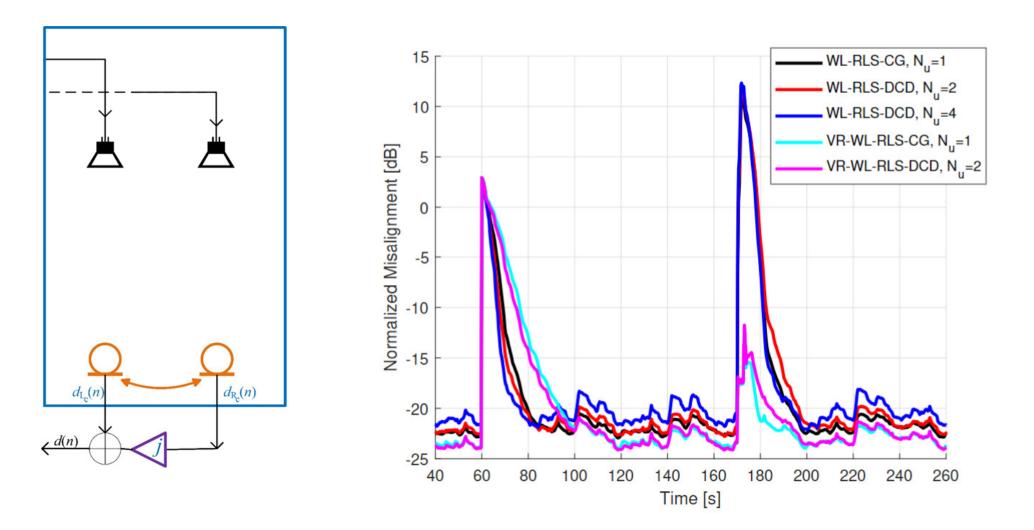


Simulation Results

- Tracking & Double Talk:
 - WL-RLS-CG vs WL-RLS-DCD vs VR-WL-RLS-CG vs VR-WL-RLS-DCD
- Input signal:
 - High quality speech sequence
- **Unknown systems** (*left* and *right*):
 - Real measured impulse responses (decimated)
 - L = 256
 - ENR = 25 dB & 10 dB
- Performance measure:

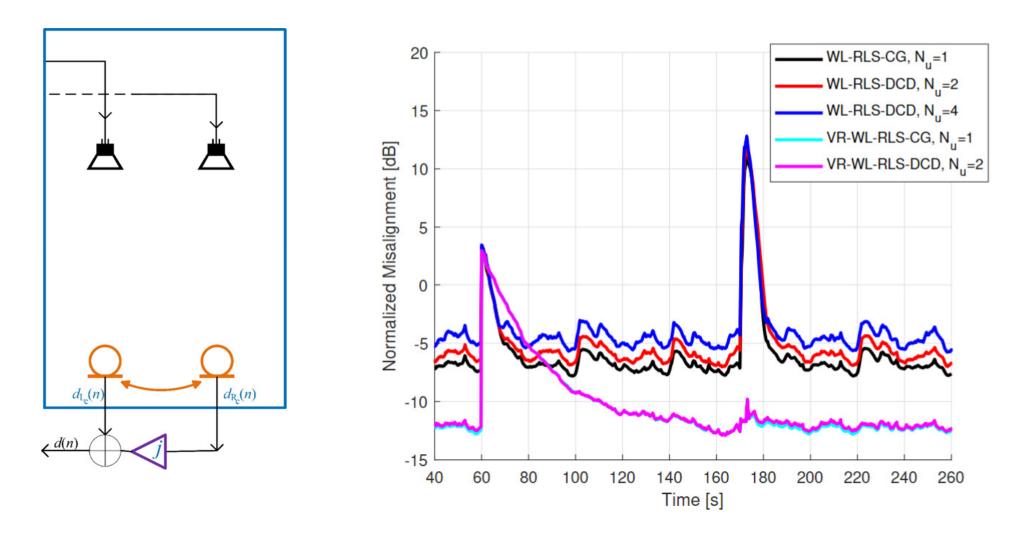
$$\operatorname{Mis}(n) = 20 \log_{10} \left[\frac{\|\tilde{\mathbf{g}}_{t} - \tilde{\mathbf{g}}(n)\|_{2}}{\|\tilde{\mathbf{g}}_{t}\|_{2}} \right] (dB)$$

Simulation Results



Performance of the LSM algorithms for L=256 and ENR = 25dB. The unknown system changes at $t_0 = 60$ s due to the interchanging of the microphone positions. Double-talk situation in the time interval [170; 174]s.

Simulation Results



Performance of the LSM algorithms for L=256 and ENR = 10dB. The unknown system changes at $t_0 = 60$ s due to the interchanging of the microphone positions. Double-talk situation in the time interval [170; 174]s.

Conclusions

• VR-WL-RLS-LSM:

• Improves the performance of WL-RLS-LSM working in the SAEC setup with

small ENR values and/or when double-talk situations occur

- Extra arithmetical effort
- Tracking speed loses





Thank you!

Please refer any questions to:

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