

National University Corporation Tsukuba University of Technology





### **One-Handed Signs:** Standardization for Vehicle Interfaces and Groundwork for Automated Sign Language Recognition

#### ○Akihisa Shitara<sup>†</sup>, Taiga Kasama<sup>\*</sup>, Fumio Yoneyama<sup>\*</sup>, Yuhki Shiraishi<sup>\*</sup>

<sup>†</sup>Graduate School of Library, Information, and Media Studies, University of Tsukuba, Japan \*Faculty of Industrial Technology, Tsukuba University of Technology, Japan

Email: theta-akihisa@digitalnature.slis.tsukuba.ac.jp

DigitalWorld 2024 Congress The Seventeenth International Conference on Advances in Computer-Human Interactions ACHI 2024 May 26, 2024 to May 30, 2024 - Barcelona, Spain



## Presenter: <u>Akihisa Shitara</u>



- d/Deaf
- Ph.D Student
  - University of Tsukuba
- Part-time Researcher Faculty of Industrial Technology, Tsukuba University of Technology
- Research Topics
  - Accessibility
  - Human Computer Interaction
  - Deaf Physicality



Graduate School of Library, Information, and Media Studies,

## Contents

## 1. Introduction

- 2. Related Work
- **3.Needs Survey**
- **4. Proposal of Vehicle Interfaces Standard**
- **5.Data Collection and Annotation Rules**

## 6. Discussion

7. Conclusion and Future Work





## Contents





## Introduction



- Act for Eliminating Discrimination against Persons with Disabilities
- Disgualification provisions stipulated in Article 88 of the Road Traffic Act

#### <u>environmental sounds</u> (emergency information etc)







5

National University Corporation Tsukuba University of Technology



#### hearing aids / cochlear implants

#### or

#### magnifying glasses and hearing impairment markers

#### **Communication** issues





## In-vehicle sign language recognition standard

- Installation location of drive recorders
- One-handed sign that occurs during sign language conversations



### This research topics:

1. Proposing limited sign language by selecting one-handed signs 2. Evaluation of the one-handed signs by the parties concerned



6







## Image recognition

- Mukai et al. [4]: 41 static fingerspelling in JSL average recognition accuracy of 86%
- Hosoe et al. [5]: only static fingerspelling in JSL recognition rate of 93%
- Jalal et al. [6]: static fingerspelling in ASL recognition rate of 99%
- Kondo et al. [7]: static and dynamic fingerspelling in JSL 93.8% identification rate

[4] N. Mukai, N. Harada, and Y. Chang, "Japanese fingerspelling recognition based on classification tree and machine learning," in 2017 Nicograph International New York, NY, USA: IEEE (Institute of Electrical and Electronics Engineers), June 2017, pp. 19–24. [5] H. Hosoe, S. Sako, and B. Kwolek, "Recognition of jsl finger spelling using convolutional neural networks," in 2017 Fifteenth IAPR International Conference on Machine Vision Applications (MVA), May 2017, pp. 85–88.

[6] M. A. Jalal, R. Chen, R. K. Moore, and L. Mihaylova, "American sign language posture understanding with deep neural networks," in 2018 21st International Conference on Information Fusion (FUSION). New York, NY, USA: IEEE (Institute of Electrical and Electronics Engineers), July 2018, pp. 573-579.

[7] M. Kondo, N. Kato, K. Fukui, and A. Okazaki, "Development and evaluation of an interactive training system for both static and dynamic fingerspelling using depth image," IEICE technical report, vol. 114, no. 512, 2015, pp. 23–28, (in Japanese).





## Related Work

### Sensor glove recognition

- Cabrera et al. [8]: static fingerspelling in ASL recognition rate of 94.07%
- Mummadi et al. [10]: fingerspelling in FSL with an F1-score of 91%.
- Kakoty et al. [11]: fingerspelling (C, I, J, L, O, U, Y, W) in ISL fingerspelling (A to Z) in ASL signed numbers (0 to 9) average recognition rate of 96.7%

#### Chong et al. [12]: 28 sentences in ASL accuracy of up to 99.89%

Cabrera, J. M. Bogado, L. Fermin, R. Acuna, and D. Raley. "Glove-based gesture recognition system," in Adaptive Mobile Robotics. World Scientific, np. 747-753,

[10] C. K. Mummadi, F. P. P. Leo, K. D. Verma, S. Kasireddy, P. M. Scholl, and K. Van Laerhoven, "Real-time embedded recognition of sign language alphabet fingerspelling in an imu-based glove," in Proceedings of the 4th International Workshop on Sensor-Based Activity Recognition and Interaction, ser. iWOAR '17. New York, NY, USA: Association for Computing Machinery, 2017, pp. 1–6. [Online]. Available: https://doi.org/10.1145/3134230.3134236 [11] N. M. Kakoty and M. D. Sharma, "Recognition of sign language alphabets and numbers based on hand kinematics using a data glove," Procedia Computer Science, vol. 133, 2018, pp. 55-62.

[12] T.-W. Chong and B.-J. Kim, "American sign language recognition system using wearable sensors with deep learning approach," The Journal of the Korea Institute of Electronic Communication Sciences, vol. 15, no. 2, 2020, pp. 291–298.



National University Corporation Tsukuba University of Technology



# average recognition rate of 92%

## Related Work

## Data collection

### Image recognition

- PHOENIX-2014, PHOENIX-2014-T (GSL)[16, 17]
- Chinese Sign Language[16]

#### - ChicagoFSwild, ChicagoFSwild+ (Chicago Sign Language)[16-19]

[16] H. Zhou, W. Zhou, Y. Zhou, and H. Li, "Spatial-temporal multi-cue network for continuous sign language recognition," in Proceedings of the AAAI Conference on Artificial Intelligence, vol. 34, no. 07, 2020, pp. 13 009–13 016

[17] "PWTH-PHOENIX-Weather 2014-T)," 2019, URL: https://wwwi6. informatik.rwth-aachen.de/~koller/RWTH-PHOENIX-2014-T/ [retrieved: April, 2024]. [18] B. Shi and et al., "Fingerspelling recognition in the wild with iterative visual attention," in 2019 IEEE/CVF International Conference on Computer Vision (ICCV), 2019, pp. 5399-5408.

[19] "Chicago Fingerspelling in the Wild Data Sets (ChicagoFSWild, ChicagoFSWild+)," 2019, URL: https://home.ttic.edu/~klivescu/ChicagoFSWild [retrieved: April, 2024].

#### Sensor glove recognition

Not require pictures of the face; thus privacy concerns









## Needs Survey

### Method: Google Forms

Respondents: 143 (88: male, 53: female, 2: Unpecided) Mean age: 32.01 (SD: 13.87) Identity: Deaf 68, deaf 20, hard of hearing 35, hearing 4, unsure etc 11, others 3, invalid 2

#### Findings:

When calling out to the driver while driving

- hard of hearing more likely to use voice than Deaf (with a significant difference)

Communicate with the driver while the vehicle is in motion

- more than 75% of d/Dhh individuals wanted to use sign language

Over 75% of the respondents

- difficulties communicating with a person who can use sign language
- want to communicate with

ional University Corporation Tsukuba University of Technology



Shiraishi Lab

while sitting in the passenger seat

the person sitting in the passenger seat while driving



## Contents





### **In-vehicle sign language recognition standard**

- **Limitation:** must always face forward needs to grip the steering wheel



Shiraishi Lab



14

National University Corporation Tsukuba University of Technology

### **One-Handed Signs**

#### Rule:

15

- Select one-handed sign words and short sentences
- Not using grammar that: employs facial expressions, other elements



- driver's license
- driving experience

#### After completing the data collection experiment: Participants: 22 Sign language experience: 11.3 years (SD: 7.1 years)

### **Evaluation of Necessity:**

16

1. In-vehicle sign language recognition 2. Use of one-handed signs in side

Shiraishi Lab



#### After completing the data collection experiment: Participants: 10 Sign language experience: 11.6 years (SD: 5.76 years)

### **One-Handed Signs**

#### Expression for each word

- 1. Unnaturalness with all words
- 2. Selected word that negative responses was 3 or more
  - Binomial test's two-sided significance level of 0.05
  - No significant difference was confirmed (p=0.344)
- 3. Acceptability with 7 words
- 4. Negative responses was 1 or less
  - Binomial test's two-sided significance level of 0.05
  - No significant difference was confirmed





### **One-Handed Signs**

#### Expression for each word that Uncomfortable but acceptable



w2:休憩(rest)



w7:事故(accident)



National University Corporation

18



w4: 落ち着く(calm)



w10:信号(traffic light)



w27: 別(another)

Shiraishi Lab



w6: コンビニ(convenience)



w16:次(next)

#### After completing the data collection experiment: Participants: 10 Sign language experience: 11.6 years (SD: 5.76 years)

### **One-Handed Signs**

### **Expression for each short sentence**

- 1. Unnaturalness with all short sentences
- 2. Selected short sentences that negative responses was 3 or more
  - Binomial test's two-sided significance level of 0.05
  - No significant difference was confirmed (p=0.344)
- 3. Acceptability with 12 short sentences
- 4. Negative responses was 1 or less
  - Binomial test's two-sided significance level of 0.05
  - No significant difference was confirmed





### **One-Handed Signs**

#### Expression for each short sentence that Uncomfortable but acceptable



s3: 危険, 落ち着いて見て [Danger, watch calmly]



s4: コンビニ, 行きますか? [Are we going to the convenience store]



s12:次はどこ行く? [Where are we going next?]



s13:次に左折するのはどこ? [Where do we turn left next?]



National University Corporation
Tsukuba University of Technology





#### s9:次の信号で右折 [Turn right at the next signal]



s18:別の道があるか調べて [Check if there is another route]

### **One-Handed Signs**

#### Expression for each short sentence that Uncomfortable but acceptable



s21: 緊急車両が来るから右寄せて [Pull over to the right because an emergency vehicle is coming]



s24: ガゾリンスタンドはない [There is no gas station]



s32: おーい, ウィンカー消して [Hey, turn off the turn signal]









s27: 左に止めても構わない [You can stop on the left]



s37: 3つ目の交差点で右折だから, 右寄せして [It's a right turn at the third intersection, so stay to the right.]

## Contents







## Data Collection and Annotation Rules

## **Data Collection**



### • 4 time each one short sentence driver seat and passenger seat

## Data Collection and Annotation Rules

## **Annotation Rules**

- Annotation labels: "word" and "transition"
- Dynamic sign language expressions • Start point: handshape is determined

  - End point: handshape collapses or hand moves away from the ending position
- Static sign language expressions
  - Start point: moment just before

 End point: moment when the hand moves away from the fixed position





reaching the fixed position

## Contents





## Discussion

#### Validity of One-Handed Sign Expressions Necessary to increase the number of participants and consider participant attributes

- Sign language experience, JSL or SJ
- Identity, Involvement in deaf school communities

### Annotation Rules

- "Here" and "There" use "number 1" that handshape "Here": points to one's own feet
  - "There": depends on which place is being pointed —> but since it is a high-context expression in Japanese
- "Why" and "Go" use "number 1" that handshape and twist the wrist downward from one's chest to the front

"Why": aiming for 45 to 90degrees, twice

"Go": aiming for more than 80 degrees, once

- "(Number)th"

Each "th" as a single "th"



National University Corporation
Tsukuba University of Technology

Shiraishi Lab

## Discussion

## Differences between Camera and Gloves

Not yet been examined:

- Differences between cameras and gloves
- As well as which one is more suitable

#### Necessary:

- Evaluate the accuracy of sign language recognition
- User studies to determine which input interface is preferable

### Limitation

Not yet been completed:

- Annotation process
- Evaluation experiments
- Cannot have validity of expressions
- Not targeted:

- facial expressions, other grammatical elements Annotation labels is not high of when generalized



National University Corporation Tsukuba University of Technology

Shiraishi Lab

## Contents





## Conclusion and Future Work

## **Conclusion**

#### <u>environmental sounds</u> (emergency information etc)





National University Corporation Tsukuba University of Technology

<u>Shiraishi Lab</u>

#### **Communication issues**

#### <u>Selecting</u>

- words
- short sentence

#### **Evaluating**

- uncomfortable
- acceptable

**Data Collection** 

- camera
- glove

## Conclusion and Future Work

## **Future Work**

- 1. Expand the dataset Robustness and generalizability of the sign language recognition
- 2. Develop and implement real-time recognition Assist d/Dhh drivers in communication and navigation
- 3. <u>Conduct user studies</u> Evaluate effectiveness and usability of the proposed system
- 4. Refine annotation rules Based on feedback from the d/Dhh community and research findings
- 5)<u>Investigate multimodal approaches</u> Explore the integration of other modalities, such as facial expression or eye-tracking





## Acknowledgment

#### This work was supported by:

- Woven by Toyota, Inc.
- JSPSKAKENHI Grant Number #19K11411
- Promotional Projects for **Advanced Education and Research in NTUT**



