# A Numerical Investigation of Rider Injury Risks From Falling off an E-scooter

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## Prof. Costin Untaroiu

Dr. Costin Untaroiu is currently an Associate Professor of Biomedical Engineering & Mechanics at Virginia Tech. Dr. Untaroiu has a vast experience in the field of Computational Mechanics and Biomechanics. He is co-author of more than 80 peer reviewed journal papers and more than 100 conference papers. Dr. Untaroiu has extensive experience in rigid-body and finite-element modeling, including probabilistic models. He is also a Fellow of ASME.

#### Education

PhD, Mech. & Aero. Engineering, Univ. of Virginia May 2005 Diploma (BS & MSc) Applied Mathematics: Solid Mechanics May 1996 University of Bucharest, Romania Diploma (BS & MSc) Mechanical Engineering May 1990 "Politehnica" University of Bucharest, Romania

#### **Professional Experience**

Associate Professor of Biomedical Engineering 2015-present Research Associate Professor 2011-2015 Virginia Tech and Wake Forest University Research Assistant Professor 2008-2011, Univ. of Virginia



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### 1. Introduction

- Head and limbs most frequently injured regions [1]
- Fractures/dislocations and contusions are the most common types of injuries
   [1]
- Most e-scooter crashes are caused by falls





Data taken from Aizpuru et al. [1]

### 2. Methods: FE setup of Scooter Accident Simulation

- Dummy model used was of a standing 50% male Hybrid III dummy (78.1 kg, 1700 mm height). The FE model contained 4,301 elements and 7,355 nodes (LSTC/Ansys model).
- Flat ground created
  - Deformable top layer
    - Concrete material
  - Rigid bottom layer created to keep top layer stationary
- A stopper placed in path of scooter



### 2. Methods : Geometry Reconstruction & Meshing



FARO laser scanner system (Point clouds) Rhino 3D (NURBS surfaces) HyperMesh (model mesh)

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### 2. Methods: Calibration of HIII FE Model

Several tests were simulated and used to calibrate the HIII model



Knee Impact Test

Neck Pendulum extension/flexion Tests

6.7 m/s

### 3. HIII Calibration Example: Head and Thorax Calibration



## 3. Impact Simulations: Impact variables tested

Stopper height
52 mm
Approach angle



- Impact speed
  - 3.2 m/s
  - 4.48 m/s
  - 11.16 m/s

## 3. Impact Simulations: Arm activation

- Arm activation added to all head-on collisions
- Accomplished by loading the shoulder and elbow joints
- Ran a total of 45 e-scooter crash simulations

a) No arm activation



a) Arm activation included



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#### 3. Impact Simulations: Injury Risks Calculation

- Injury metrics extracted from simulations
  - Head injury criteria (HIC)
  - Neck injury criteria (N<sub>ij</sub>)
  - Chest Deflection
  - Maximum femur force
- Used to calculate Rider Injury Measure (RIM)

$$RIM_{AIS3+} = 1 - (1 - P_{HIC}) * (1 - P_{N_{ij}}) * (1 - P_{chest}) * (1 - P_{femur})$$

### 3. Impact Simulations: Statistical Analysis

- Correlation coefficients measured the relationship between pre-impact variables and injury risks
- Sobol's global sensitivities compared the effect of each pre-impact variable
- Student t-tests determined if arm activation caused any significant changes to injury risks

4. Results & Discussion: Injury Metrics

- About half of all neck and head injury risks were higher than 25%
- 4 of the 5 lowest RIM scores occurred simulations using smaller approach angles
- Nearly all simulations with RIM scores of 1 occurred during head-on collisions



### 4. Results & Discussion: Approach Angle

- The approach angle had strong positive correlations with head, neck, chest, and overall injury risks
- E-scooter impacting a 52 mm stopper at 11.16 m/s
  - Head-on collision



•  $30^{\circ}$  approach angle



### 4. Results & Discussion: Impact Speed

- The impact speed had small negative correlations with RIM and chest injury and small positive correlations with head, neck, and chest injury risks
- E-scooter impacting a 52 mm stopper with a  $90^{\circ}$  approach angle
  - 3.2 m/s impact speed



• 11.16 m/s impact speed



### 4. Results & Discussion: Stopper Height

- Stopper height had the lowest contribution to injury risk
- E-scooter impacting a stopper with a 90° approach angle at 3.2 m/s
  - 52 mm stopper



• 152 mm stopper



#### 4. Results & Discussion: Correlation Coefficients and Global Sensitivities



### 4. Results & Discussion: Arm Activation

- Reduced RIM scores were reduced in two-thirds of the head-on crash simulations
- Arm activation had a statistically significant effect on neck injury risk (p=0.042)
- E-scooter impacting a 52 mm stopper at a speed of 3.2 m/s



### 4. Results & Discussion: Key points

- Key conclusions
  - The approach angle had the greatest impact on injury risk
  - The impact speed had a negative correlation with injury risks for small angles of approach
  - Overall arm activation did reduce RIM scores
- Limitations
  - Limited selection of injury measures
  - Coarse HIII dummy model

- Risks of serious injury were greatest for the head and neck regions
  - Corroborated by experimental data [2]
- A future study will look at impacts involving a collisions with vehicles
- This study showed a higher risk of serious injury than observed in hospitals

• This project was funded in part by the Safety through Disruption (Safe-D) National University Transportation Center (UTC), a grant from the U.S. Department of Transportation – Office of the Assistant Secretary for Research and Technology, University Transportation Centers Program [1] Aizpuru, M., Farley, K. X., Rojas, J. C., Crawford, R. S., Moore Jr, T. J., and Wagner, E. R., 2019, "Motorized scooter injuries in the era of scooter-shares: a review of the national electronic surveillance system," The American Journal of Emergency Medicine, 37(6), pp. 1133-1138.

[2] Trivedi, T. K., Liu, C., Antonio, A. L. M., Wheaton, N., Kreger, V., Yap, A., Schriger, D., and Elmore, J. G., 2019, "Injuries associated with standing electric scooter use," JAMA network open, 2(1), pp. e187381-e187381.