

ece

Light Field: A Quest for the Perfect Picture





Dr. Panos Nasiopoulos



March 2023



Hypervsn – holographic solutions





https://www.youtube.com/watch?v=4a0_Vb0elek





Capture and display what the human eye can see



Glasses





Capture and display what the human eye can see

Multiview displays



Image source: DIMENCO



Image source: Alioscopy

FOCUS & CONVERGENCE





Capture and display what the human eye can see





4K: improved resolution HDR: High Dynamic Range



HDR

A quest for the perfect picture

CAPTURE INFORMATION THAT CAN HELPS US APPROXIMATE HUMAN PERCEPTION







We live in a Visual World





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We live in a Visual World







We live in a Visual World





FIRST PHOTO TAKEN BY A CAMERA - 1826





FIRST COLOUR PHOTOGRAPH - 1861





FIRST DIGITAL PHOTOGRAPH - 1957

176 x 176





HOLODECK – 20??





WE SEE THE WORLD BECAUSE OF LIGHT



WE SEE THE WORLD BECAUSE OF LIGHT



WE SEE THE WORLD BECAUSE OF LIGHT



WE FOCUS ON CONVERGING RAYS



WE FOCUS ON CONVERGING RAYS



WE FOCUS ON CONVERGING RAYS



HOW TO RECREATE THE SCENE USING LIGHT FIELD?





























A picture is worth a 1000 words but ...



UBC

IARIA

Digital Multimedia




A picture is worth a 1000 words but ...









© Adelson, E.H., Bergen, J.R. (1991).

Light Field Technology





2006, Ren Ng

Current Light Field Capture Systems

Microlens

Raytrix







Light Field Camera – Concept of Sub-Aperture Images

5 5 Image Micro Main 5 5 5 5 Sensor Lenses Lens 0 4 4 5 Image sensor array 4 4 1 4 4 4 3 3 2 3 s_1 3 3 ϑ_2 3 3 2 3 s_1 2 2 1 2 4 s_0 2 0 5 1 | 1 1 1 F_U 0 0 0 0 0 0 The same color means they come from the same perspective.

Simplified model (Constant)

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Light Field Camera – Perspective Feature



15X15 different perspectives



Freely changing perspectives

Light Field Camera – Perspective Feature



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Light Field Frame





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Sub-Aperture Images







Refocusing: Shift & Sum

Identify the depth layer in all the views



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Refocusing: Shift & Sum

SShifaltable viewstooncatechetherebeefe wiewd view



Base view





Focused on the "Tire"







IARIA

Focused on the "Small Flower"





Focused on the "Flowers"







IARIA

Focused on the "Leafs"





IARIA

Focused on the "other tire"





Microlens depth limitation





Current Light Field Capture Systems

Camera Array



© Stanford

Raytrix



Microlens





REFOCUSING – DOES NOT WORK FOR CAMERA ARRAY CONTENT





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REFOCUSING – DOES NOT WORK FOR CAMERA ARRAY CONTENT



Original

Refocused





REFOCUSING – DOES NOT WORK FOR CAMERA ARRAY CONTENT

Due to the longer baseline Shifting only aligns to the sharpest part



Occluded objects/ new details creates ghosting





REFOCUSING & PERSPECTIVE VIEWING IN ENTERTAINMENT



Applications:

- Live sports
- Interactive Movies
- Games

Pros:

- Every Sub-aperture image is captured from slightly different vantage point
- Better depth estimation than 3D
- Many focus points
- Better Object separation/recognition







ENTERTAINMENT – LIGHT FIELD





Changing the AR/VR Landscape



- Accurate Object Recognition
- Accurate Depth Estimation
- Accurate Overlay

Magic Leap has raised more than \$2.7 billion in funding in 2 years (AT&T is one of the investors)



 Existing AR: Challenging precise overlay of synthetic augmentations on real-life content



Segmentation, object identification, depth estimation have been extremely difficult challenges for real-time applications









Combine eye trackers with light field AR

Eye trackers can check where the viewer looks (heat map)



Light field properties are used to identify object of interest and focus only on that plane and location

Visual information from light field camera is analyzed to identify area





LIGHT FIELD IN AUTONOMOUS DRIVING Understanding Environment and Actions is the basis for success



Cameras

 Detect traffic lights, read road signs, keep track of the position of other vehicles, look for pedestrians and obstacles.

Lidar

 Bounces pulses of light off the surroundings.
They are analyses to identify lane markings and the edges of roads

Radar sensors

 Monitor position of other vehicles nearby. Already used in adaptive cruise control systems.

LIGHT FIELD IN AUTONOMOUS DRIVING Understanding Environment and Actions is the basis for success



For now, autonomous vehicles/driving are limited to some places, isolated streets, specific controlled environment (depth information may suffice)

Why? Limited Visual Information



LIGHT FIELD IN AUTONOMOUS DRIVING

But the long term goal, which is 5 years and beyond, will expand these to a much broader application which will need our visual solutions to step up...






LIGHT FIELD IN AUTONOMOUS DRIVING

But the long term goal, which is 5 years and beyond, will expand these to a much broader application which will need our visual solutions to step up...



Capture

- light intensity and directional information,
- focus and depth properties, and
- visual cues.



LIGHT FIELD IN AUTONOMOUS DRIVING

The rich, immersive video information provided by Light Field will help Al "act" as close as possible to a human



Capture

- light intensity and directional information,
- focus and depth properties, and
- visual cues.





LIGHT FIELD IN DIGITAL HEALTH Accurate Less Intrusive Endoscopy

A regular surgical camera



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Accurate Less Intrusive Endoscopy

Light Field Display



<image>



5G enables real-time remote surgery





© TransEnterix





Non-Intrusive Monitoring







Labelling





Training -LRCN



Long Term Recurrent Convolutional Network

- Use a CNN to extract key features from frames
- Feed into LSTM to gain temporal information





Non-Intrusive Monitoring



Light Field information will improve this accuracy, since richer visual information will be processed by the system.

This type of visual information will allow us to accurately track behaviour and determine changes that may be associated with various medical conditions, for early diagnosis and prevention.





DIGITAL HEALTH & COMMUNICATIONS- Challenges





- Bandwidth
- Real-time streaming
- Security



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Compression



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Compression IBP frames

Trade=öff!beftween overhead=and=residuals





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LIGHT FIELD – MASSIVE DATA: COMPRESSION

Conventional Video



Light Field Video



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LIGHT FIELD – Existing Compression Methods





LIGHT FIELD – Existing Compression Methods

LF-MVC (Wang Et al. 2016)



Is Top Left the Best Place to get started?

Khoury's Method (Khoury Et al. 2018)



Encode the central frame as I frame ✓ Again only vertical or horizontal references × 38.18% BD-Rate of LF-MVC (5 x 5 Views) ✓

Does not scale well ×





LIGHT FIELD – Existing Compression Methods

Full Scheme (Avramelos et al. 2019)



Maximizes B frames so compression efficient ✓

Again I frame at a corner ×

Diagonal references ×

Predicting frames from far \times

Performs 24% better than LF-MVC and 15% worse than Khoury's method

Does not scale well ×





SSIM heatmap for Chess Pieces (5x5)

	CHESS - VIEW 1				
0-		2 [0.998]	6 [0.994]	12 [0.989]	17 [0.984]
1 -	1	4	8	15	20
	[0.998]	[0.996]	[0.992]	[0.987]	[0.982]
2 -	3	7	11	16	21
	[0.997]	[0.994]	[0.99]	[0.985]	[0.98]
3 -	5	9	14	19	23
	[0.994]	[0.991]	[0.987]	[0.983]	[0.978]
4 -	10	13	18	22	24
	[0.991]	[0.988]	[0.984]	[0.98]	[0.975]
35	ò	i	2	3	4

8		CHESS - VIEW 2			
0 -	3	0	2	9	17
	[0.997]	[1.0]	[0.998]	[0.994]	[0.989]
1 -	5	1	6	12	20
	[0.996]	[0.998]	[0.995]	[0.992]	[0.987]
2 -	7	4	10	16	21
	[0.995]	[0.996]	[0.993]	[0.989]	[0.984]
3 -	11	8	13	19	23
	[0.993]	[0.994]	[0.991]	[0.987]	[0.982]
4 -	15	14	18	22	24
	[0.99]	[0.99]	[0.987]	[0.984]	[0.979]
20	Ó	i	2	3	4

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CHESS - VIEW 1	CHESS - VIEW 2	CHESS - VIEW 3	CUTCC AND A	CUTOE LADAR
0 2 6 12 17 [0.998] [0.994] [0.939] [0.934]	0 ⁻ (0.997) 0 2 9 17 (0.997) 10 (0.998) (0.994) (0.599)	0. (0.335) (0.336) [1.0] (0.338] (0.335)	0- 18 11 3 0 2 [0.996] [0.991] [0.996] [1.0] [0.997]	0- 21 16 8 2 0 (0.98] [0.985] [0.99] [0.996] [10]
1 (0.996) (0.996) (0.992) (0.967) (0.962)	1 (0.996) (0.998) (0.995) (0.992) (0.967)	1. (0.991) (0.995) (0.990) (0.995) (0.991)	1- [0.906] [0.991] [0.995] [0.995] [0.995]	1- 20 15 (0.98) (0.985) (0.985) (0.999)
2 3 7 11 16 21 (0.997) (0.994) (0.99) (0.905) (0.90	2 - 7 4 10 16 21 (0.995) (0.996) [0.993] [0.993] [0.909]	2 (0.991) (0.994) (0.996) (0.993) (0.988)	2-21 13 7 4 10 [0.966] [0.99] [0.994] [0.996] [0.992]	2- 22 17 10 5 3 (0.98) (0.585) (0.99) (0.994) (0.995)
3- [0.994] 9 14 19 23 [0.991] [0.907] [0.903] [0.978]	3- 11 8 13 19 23 (0.993) [0.994] [0.991] [0.907] [0.907]	3- (0.989) [0.992] [0.994) [0.99] [0.986]	3 17 9 8 16.993 (0.904) (0.909) (0.992) (0.993) (0.909)	3. 23 18 13 7 6 [0.979] [0.984] [0.988] [0.992] [0.992]
4 10 13 18 22 24 (0.991) (0.988) (0.984) (0.98) (0.975)	4 15 14 18 22 24 (0.99) (0.99) (0.987) (0.984) (0.979)	4- 21 18 17 22 24 (0.907) [0.99] [0.99] [0.907] [0.907]	4 - 24 19 14 15 22 4 - (0.903) (0.906) (0.99) (0.909) (0.906)	4- 24 19 14 11 12 (0.978) [0.962] [0.966] [0.969] [0.968]
CHESS - VIEW 6	CHESS - VIEW 7	CHESS - VIEW 8	CHESS - VIEW 9	CHEES , VIEW 10
4 10 14 18		20 9 2 4 32	23 19 10 7 4	24 19 14 7 2
• (0.998) (0.997) (0.993) (0.909) (0.964)	(0.995) (0.996) (0.997) (0.994) (0.999)	0 [0.99] [0.994] [0.998] [0.997] [0.993]	0. [0.984] [0.988] [0.993] [0.998] [0.996]	0 [•] [0.978] [0.962] [0.967] [0.993] [0.997]
3 (1.0) (0.997) (0.994) (0.969) (0.964)	¹ (0.996) (1.0) (0.998) (0.994) (0.908)	1 (0.931) (0.906) (1.01 (0.908) (0.903)	1 (0.500) (0.501) (0.500) (1.0) (0.507)	1- (0.979) [0.384] [0.99] [0.996] [1.0]
2- [0.998] [0.995] [0.992] [0.987] [0.982]	2. (0.992) (0.498) (0.996) (0.992) (0.586)	2* (0.991) (0.995) (0.998) (0.995) (0.991)	2* (0.595) (0.59) (0.595) (0.595) (0.595)	2* (0979) [0.984] [0.99] [0.995] [0.998]
3 (0.996) (0.994) (0.989) (0.964) (0.979)	3. (0.994) (0.996) (0.993) (0.909) (0.983)	3- 19 10 6 14 23 (0.99) [0.94] [0.946] [0.992] [0.988]	3 (0.905) (0.99) (0.993) (0.995) (0.992)	3 (0.979) [0.984] [0.989] [0.993] [0.995]
4 (0.994) [0.991] [0.987] [0.987] [0.992] [0.977]	4 15 11 17 22 24 (0.992) (0.994) (0.993) (0.906) (0.901)	4 (0.989) (0.992) (0.993) (0.99) (0.985)	4 0.504) [0.988] [0.992] [0.993] [0.989]	4 - <mark>23 18 13 9 8</mark> (0.978) (0.963) (0.968) (0.992) (0.992)
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CHESS - VIEW 11	CHESS - VIEW 12	CHESS - VIEW 13	CHESS - VIEW 14	CHESS - VIEW 15
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3 (0.996) (0.996) (0.991) (0.906) (0.901)	3 (0.995) (0.990) [0.996] [0.991] (0.986)	3· [0.99] [0.995] [0.998] [0.998] [0.995] [0.99]	3 19 15 10.9951 10.9951 10.9951 10.9951 10.9951	3 19 14 10 5 1 (0.979) (0.384) (0.989) (0.995) (0.998)
4- (0.996) (0.993) (0.969) (0.964) (0.978)	4 10 6 14 20 24 [0.994] [0.996] [0.993] [0.963] [0.963]	4- [0.99] 9 6 15 23 [0.994] [0.996] [0.992] [0.907]	4 - 21 16 9 6 13 [0.995] [0.999] [0.993] [0.995] [0.991]	4- (0.979) [0.964] [0.989] [0.993] [0.995]
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11 13 16 20 24	CHESS - VIEW 17	CHESS - VIEW 18	CHESS - VIEW 19	CHESS - VIEW 20
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			CHESS - VIEW 24	0 1 2 3 4
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0 [0.985] [0.984] [0.982] [0.98] [0.976]	0 [0.961] [0.963] [0.963] [0.962] [0.979]	0 (0.975) (0.979) (0.982) (0.982) (0.981)	0 [0.97] [0.973] [0.977] [0.961] [0.961	¹ 0 ⁻ 24 22 19 15 11 [0.964] [0.960] [0.972] [0.976] [0.90
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2- [0.993] [0.991] [0.989] [0.986] [0.982]	2 11 9 10 17 (0.989) (0.993) (0.992) (0.989) (0.985)	2 18 12 0 9921 (0.988) 10.9921 (0.992) 11 (0.988)	2- [0.977] [0.982] [0.987] [0.993] [0.991	2 21 17 12 6 3 2 (0.971) (0.975) (0.98) (0.986) (0.99
3 (0.998) (0.996) (0.993) (0.908) (0.983)	3 (0.993) (0.997) (0.996) (0.993) (0.988)	3 14 1 5 1 (0.993) 0.9937 (0.996) 10.9921	3 18 12 6 6 10 9921 10 9921 10 995	² 3- 18 13 8 10.9921 10.99
4 0 3 5 12 21 [0.993] [0.993] [0.993] [0.997] [0.982]	4 (0.996) (1.0) (0.997) (0.993) (0.907)	4 [0.39] 3 0 2 8 [0.39] [0.396] [1.0] [0.997] [0.592]	4 13 8 3 0 1 (0.994) (0.99) (0.996) 10 (0.997	1 4- 14 9 5 2 00 (0.977) (0.983) [0.989] [0.995] 10.0



Avg of all views

Empirical results over 9 test sequences



SSIM based Compression Method







Universal Pseudo-sequence (UPS) SSIM based Compression Method



Unlike most of the PSB prediction structures and coding orders discussed above, the proposed Universal Pseudo-sequence (UPS) based structure takes full advantage of both horizontal and vertical correlation among the views





SSIM based Compression Method

Has highest similarity with its neighbors

SSIM of all the views

Highest one is I-frame

SSIM calculation makes smallest possible P frames

To maintain our structure, next level of P frames are predicted



5x5 views

B frames with vertical and horizontal references







SSIM based Compression Method

Can be extended to any number of views

Feasible for most camera array structures









Performance – Microlens content (5x5)





Performance – Animated content (3x3)



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B B

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B ·В

Performance – Camera Array content (3x5) and (4x4)

Light Field Video Compression for Random-access efficiency

Light Field – Random Access matters

Khoury's Method

Worst Frame to Decode: 6

LF-MVC

Worst Frame to Decode: 11

Full Scheme

Worst Frame to Decode: 18

Proposed Methods

Reduced worst case random-access from 6 to 4

Diagonal Reference Based Prediction structure

Highest SSIM

Increases compression efficiency by 15%

Average random-access increases from **2.56 to 2.72**

SSIM Assisted Diagonal Reference Based Prediction structure

Random Access performance

	Method	Random-access Complexity		
		Average	Worst-case	
	LF-MVC	4.92	11	
	Khoury's	3.2	6	
	Full scheme	6.08	17	
_	Diagonal reference	2.56	4	
\square	SSIM assisted RAE	2.72	6	
	UPS	3.84	8	
'				

Best Random-access

Best Random-access to compression trade-off

N. Malajaho, S. R. Leo, H. Walfe, J. Neur, and N. T. Fournard, "An Efficient Random Averas Light Field Mileo Compression: Milako, Dimpond Marffred Predicting In 2019 IEEE International Contenence on Many Francessing (1917), 2019; M. Mehrgalfe, M. Branzard, and S. Mender, 1931/Marsfred Frederic Bredellan Sinchure for Myht Field Mileo Compression: In 1998 International Contenence on Consumer (2019) UNIVERSITY OF BRITISH COLUMBIA

Refocusing

Performance – Animated content

The dense camera array consists of 25 camera modules fixed on a stainless steel stand

Our Light Field Camera array – Outdoors content

□ The video content is captured on the University campus, with the scene including walking people, bicycles, vehicles and buildings as background.

Sketch of the captured scene

Snapshot of the captured scene

Our Light Field Camera – Outdoors content

The frames from each camera are not perfectly aligned.

alignment

Our Light Field Camera array – Outdoors content

Color differences exist in the frames captured by different camera.

Camera1

Camera2

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Our Light Field Camera array – Outdoors content

Different types of geometry distortion for single camera and the camera array.

Tangential distortion
Problems - Geometry Distortion (2)

Different types of geometry distortion for single camera and the camera array.



This type of distortion is described by **extrinsic** parameters.



Rotation and translation between each two camera pairs.

Our Light Field Camera array – Outdoors content

Different types of geometry distortion for single camera and the camera array.



Images captured by 5 cameras in the SAME row. Lens distortion is already fixed.



Rotation and translation between cameras

This type of distortion is described by **extrinsic** parameters.



Performance – Visualization

Visual comparison before and after calibration and correction



- (c) Uncorrected, view 24
- (d) Uncorrected, view 25

(g) Corrected, view 24

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(h) Corrected, view 25



Performance – Quantitative Comparison

Quantitative comparison before and after calibration/correction



The bitrate vs. PSNR at four different QP levels (25, 28, 30, and 33)

On average, for the same bitrate the objective visual quality (PSNR) increases by **0.519dB**, while for the same quality the bitrate savings are **30.275%**.

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Light Field View Synthesis



Plenoptic Camera - challenges

- + High Angular Resolution
- Low Spatial Resolution







Huge amount of data to transmit



Transmission End



Receiver End





Network for View Synthesis





LF Data Representation

3) Epipolar Image Plane (EPI)











Improving Up-sampled Quality







Improving Up-sampled Quality



Low-resolution Up-sampled Sup-aperture Images



EPI representation of up-sampled LR images showing discontinuity in disparity EPI representation of HR images showing continuity in disparity High-resolution Up-sampled Sup-aperture Images





Results



Ground Truth



Ground Truth Close-up



LFCNN (x4) [8]



GMM (s4) [11]



GB (14) [12]





D-LFSSR (14) [16]



Proposed (x4)



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LFSSR



ResLF

Ground Truth





LF-ATO



Distg-Block



Proposed





Subjective Results



Side by side evaluation based on Recommendation BT.500-13 DSIS Number of subjects: 18 Number of sequences: 10 Subjects asked which method they prefer













GB Same Proposed

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Industry & Market











Magic Leap



- Dual plane per eye
- LCOS SLM
- Waveguide optics



Multi-Planar

magic

leap







Understanding Immersive Displays

Escape the Screen

We're creating a world where content escapes the screen and merges with reality.













Light Field Extended Reality (XR) eyewear which will provide medical professionals lifelike augmented imagery





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CONCLUSION

VISUAL ACQUISITION WILL HAVE MOST DISRUPTIVE IMPACT ON MANY TRENDS & MARKETS













Thank you! Contact:

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