



Il futuro alla portata di tutti



REGIONE
PUGLIA

*Operazione finanziata con il Fondo Europeo di Sviluppo Regionale Puglia
POR Puglia 2014-2020*

Asse I - Obiettivo specifico 1a - Azione 1.1 (R&S)

Programma PBI/MCM8
MIR: A0101.168
Importo del contributo 62%



Isotta Fraschini Motori

Employing HDF5 File Format for Marine Engine Systems Data Storage

[ID: 60018]

a FINCANTIERI Company

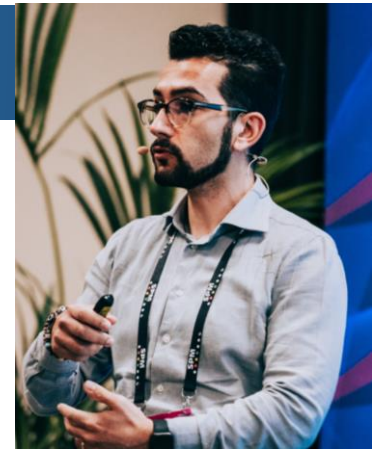
Presenter: Giuseppe Giannino

Co-author: Michelangelo Tricarico and Andrea Orlando

Company: ISOTTA FRASCHINI MOTORI (Italy)

e-mail: giuseppe.giannino@isottafraschini.it

ABOUT ME



2015 - POLYTECHNIC OF BARI

BACHELOR'S
DEGREE IN
ELECTRONIC &
TELCO
ENGINEERING

2017 - CORK INSTITUTE OF
TECHNOLOGY

RESEARCH
PROGRAM FOR
MASTER'S DEGREE
THESIS IN OPTICAL
DEVICES

2018 - KAZAN NATIONAL RESEARCH
TECHNICAL UNIVERSITY

RESEARCH
PROGRAM FOR
STUDENT
EXCHANGE IN
RADIOPHOTONIC,
ANTENNA DESIGN
AND MOBILE
COMMUNICATIONS

2018 - POLYTECHNIC OF BARI

MASTER'S
DEGREE IN
TELCO
ENGINEERING

2018-2021 - ANGEL COMPANY
(ITALY)

A.T.E. DESIGNER
AND
DEVELOPER
VALIDATION &
INTEGRATION
ENGINEER

2021-today - ISOTTA FRASCHINI
MOTORI

R&D
AUTOMATION,
CONTROL AND
SUPERVISION
SYSTEM
ENGINEER
HW/SW
INTEGRATOR



Isotta Fraschini Motori

a **FINCANTIERI** Company

MAIN TOPICS IN OUR R&D TEAM

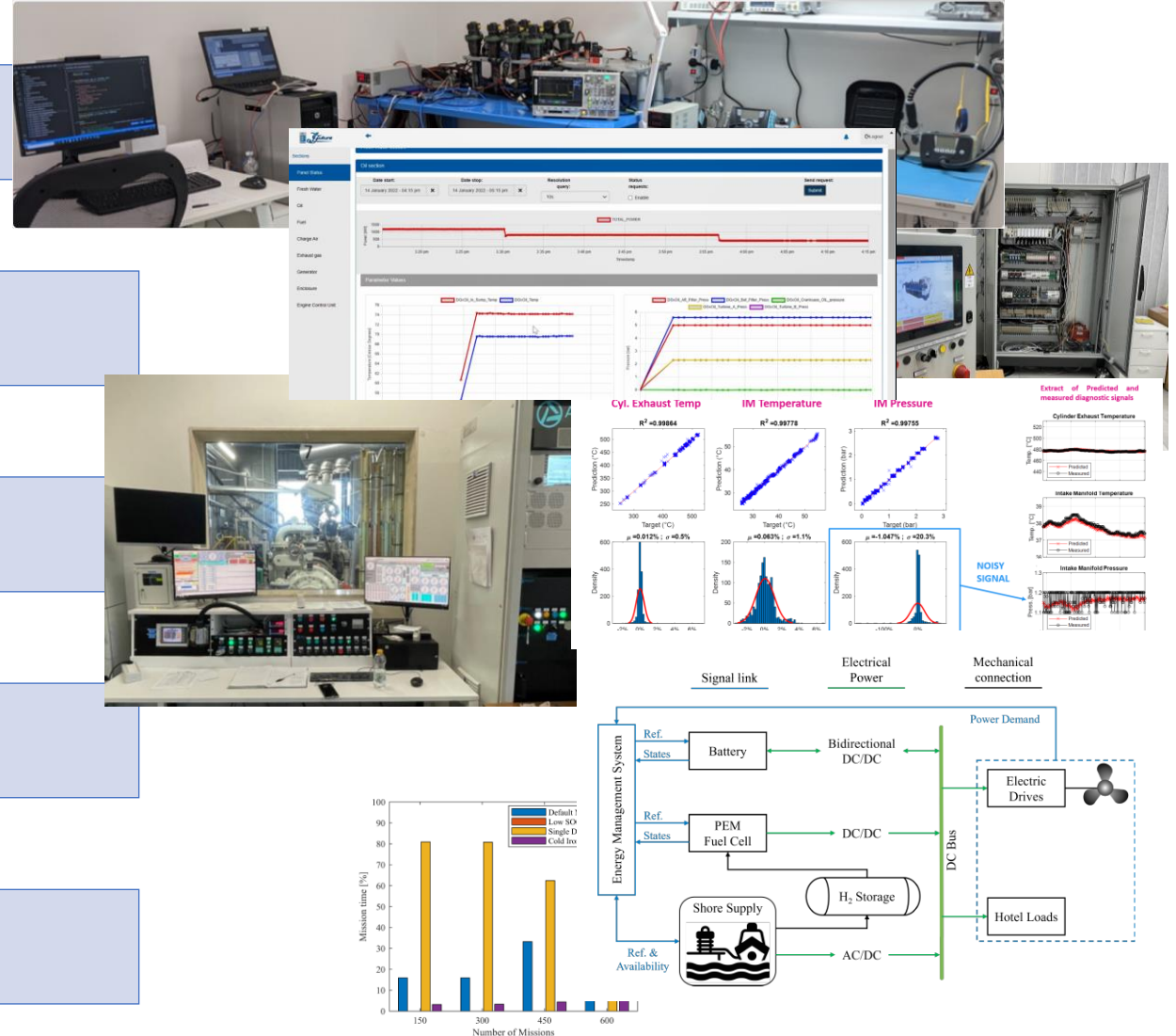
IoT SYSTEMS FOR REMOTE ASSET MONITORING AND MANAGEMENT

DATA ANALYSIS FOR PREDICTIVE PURPOSES

DIGITAL TWINS FOR ICE AND PMS

POWER AND ENERGY MANAGEMENT SYSTEMS (PMS AND EMS)

INNOVATIVE POWER SOURCES (FUEL CELLS, GREEN FUELS, BATTERIES, ETC.)



AGENDA

INTRODUCTION

HDF5 FILE FORMAT

POPULAR COMMUNICATION PROTOCOLS IN MARINE ENGINE APPLICATIONS

HDF5 and MARINE ENGINES

FILE BENCHMARKING

HDF5 VISUALIZATION TOOL (IFM developments)

CONCLUSIONS AND FUTURE WORK



Isotta Fraschini Motori

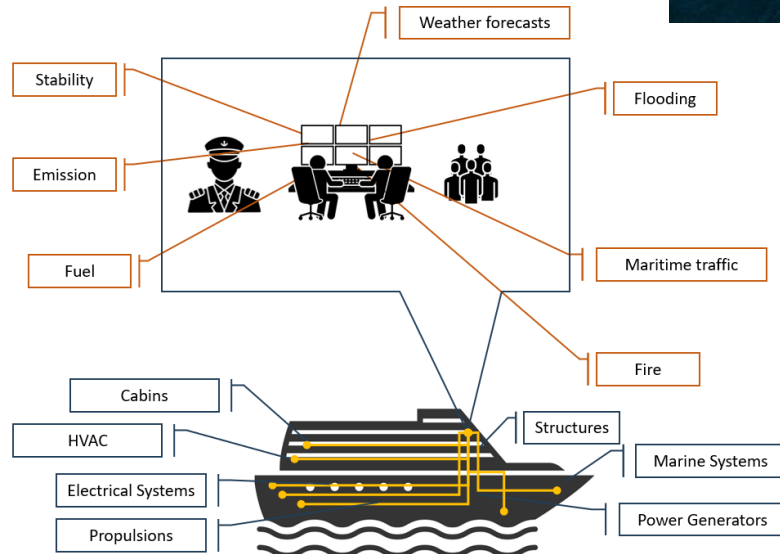
INTRODUCTION

[Ship Technology Transition]

The smart ships of the future will require a strong effort for re-designing the current architectures to allow the implementation of new functionalities mostly based on data analysis and less on human mind.

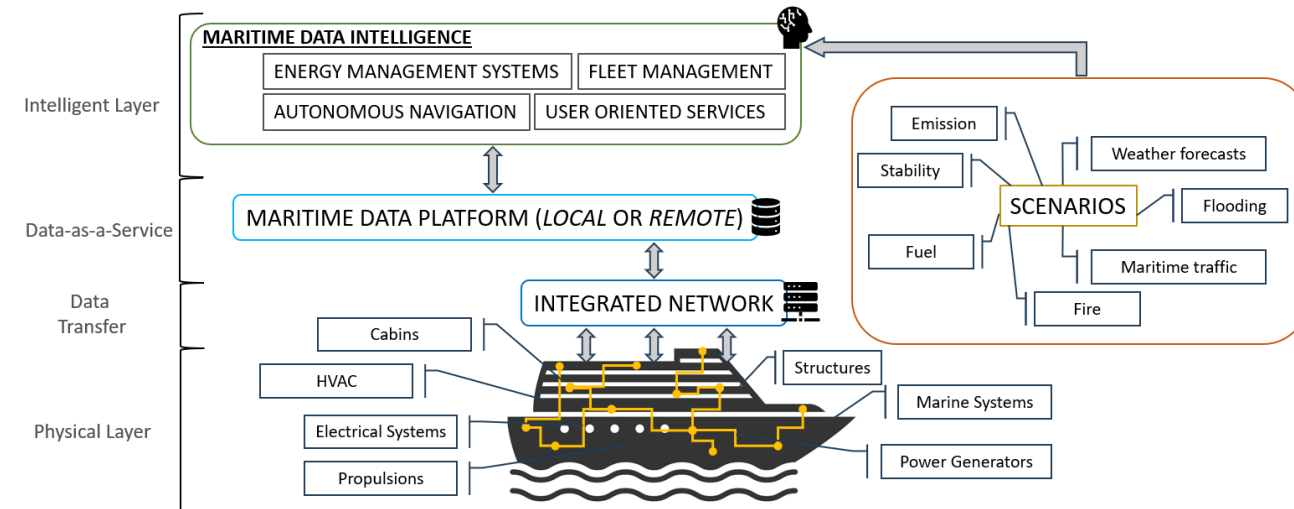
Human Centered Approach

- Decisions constrained to human mind
- Large crew
- Lots of expertise among crew
- Low level of correlation between sub-systems information
- Poor optimization for energy resources, emissions, etc.



Data Driven Approach

- Decisions mainly based on data analysis by means of algorithms
- Minimized crew
- Less competencies requested among crew
- High correlation between data shared by sub-systems
- Higher asset optimization (energy resources, emissions, etc.) and safety improvements

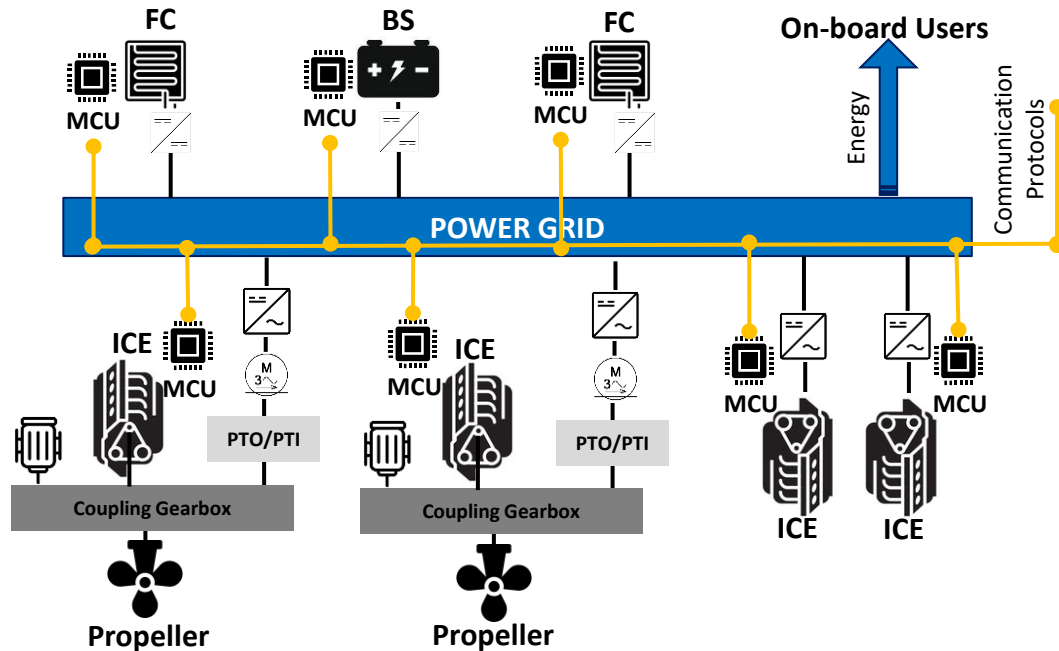


Ship Digital Transition

INTRODUCTION

[Energy Sources Sub-systems]

A complex hybrid energy system:



- Multiple energy sources → One common main DC bus and one energy source port for users
- Multiple MCU
- Multiple communication protocols
- Suitable for different operative conditions and loads requests

*ICE = Internal Combustion engine

FC = Fuel Cell

BS = Battery stack

MCU = Main Control Unit



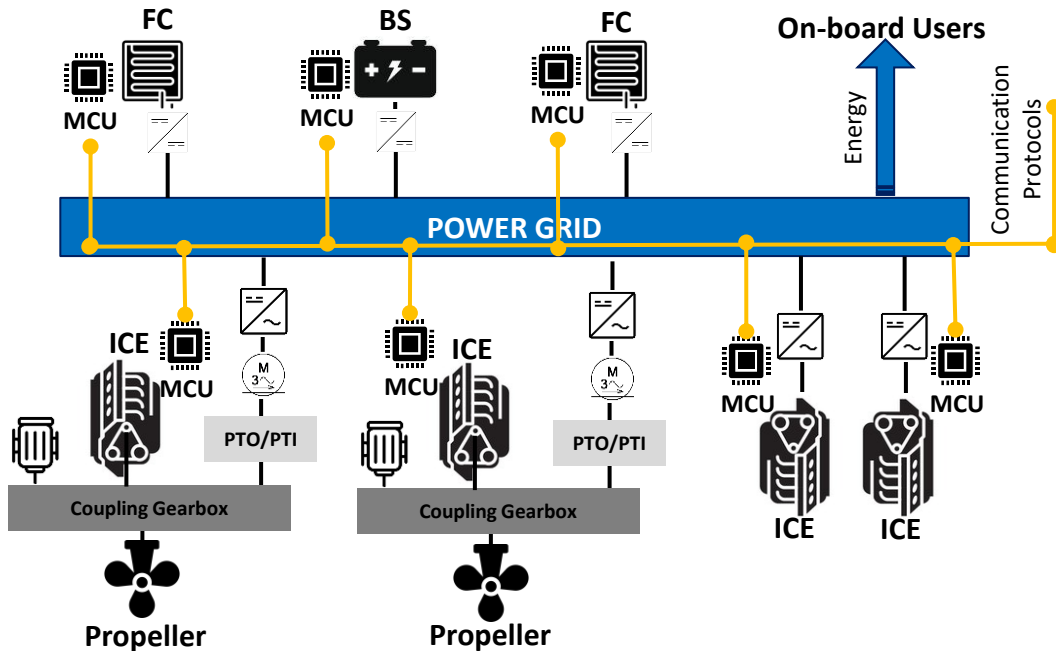
Isotta Fraschini Motori

a **FINCANTIERI** Company

INTRODUCTION

[Energy Sources Sub-systems]

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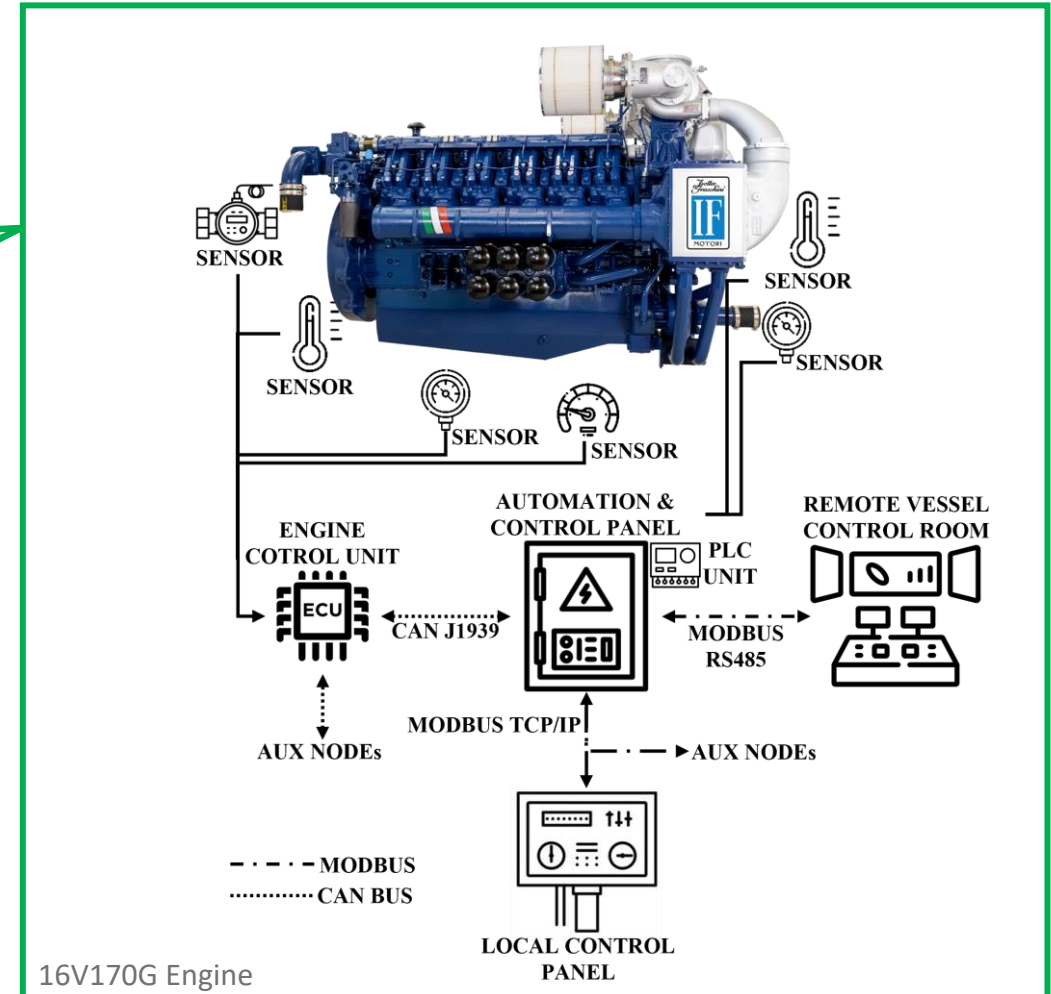
Lots of DATA:
Great to be used ... They just need
to be combined and analyzed!

[Energy Sources Sub-systems]

A typical ACS system for ICE designed by Isotta Fraschini Motori:



Isotta Fraschini Motori



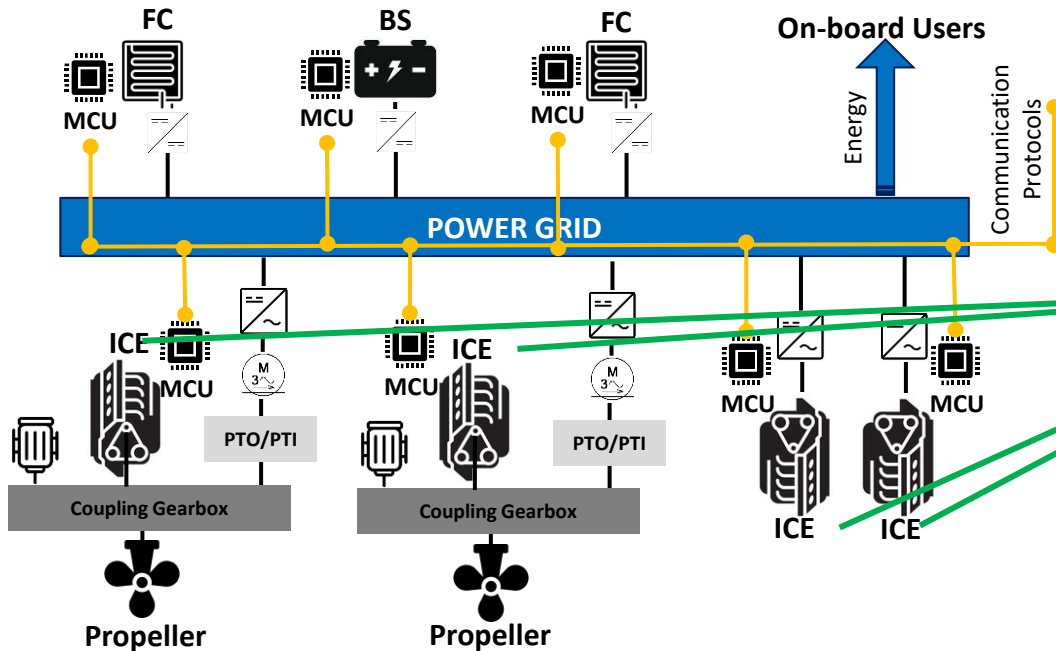
16V170G Engine

a **FINCANTIERI** Company

INTRODUCTION

[Energy Sources Sub-systems]

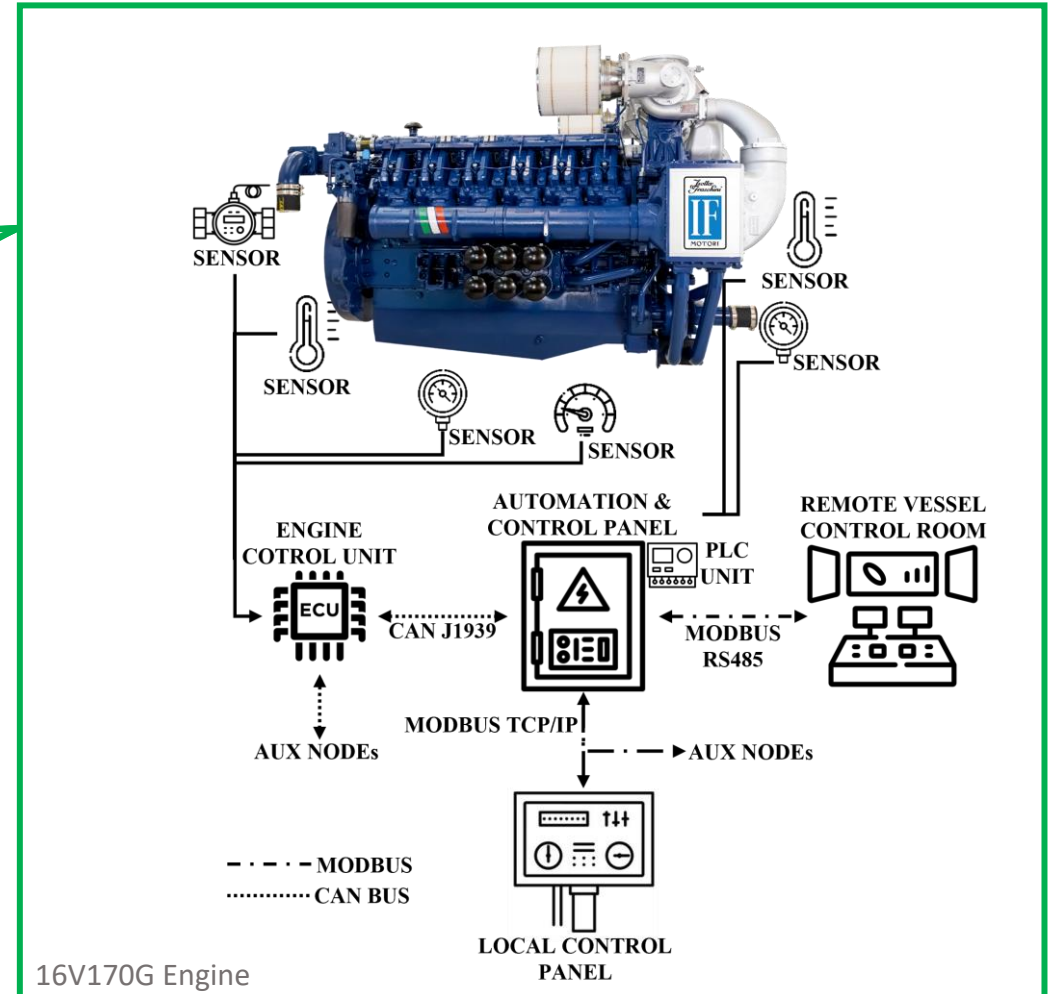
A complex hybrid energy system:



The approach could be exported to more complex systems

The idea is to aggregate all data acquired from communication protocols within one STANDARDIZED file format

A typical ACS system for ICE designed by Isotta Fraschini Motori:

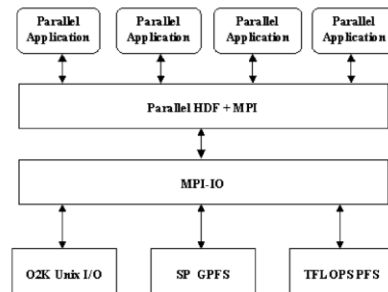


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HDF5 FILE FORMAT

[...in a nutshell]

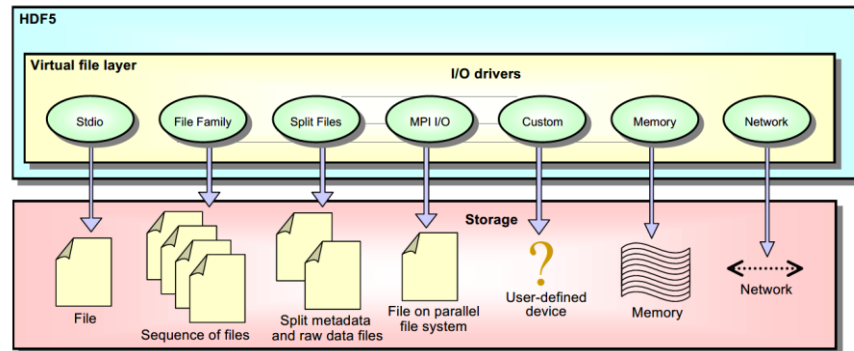


User Applications

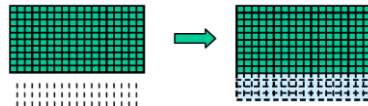
HDF library

Parallel I/O layer

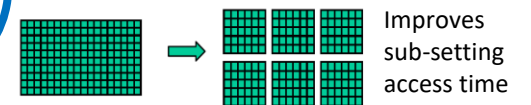
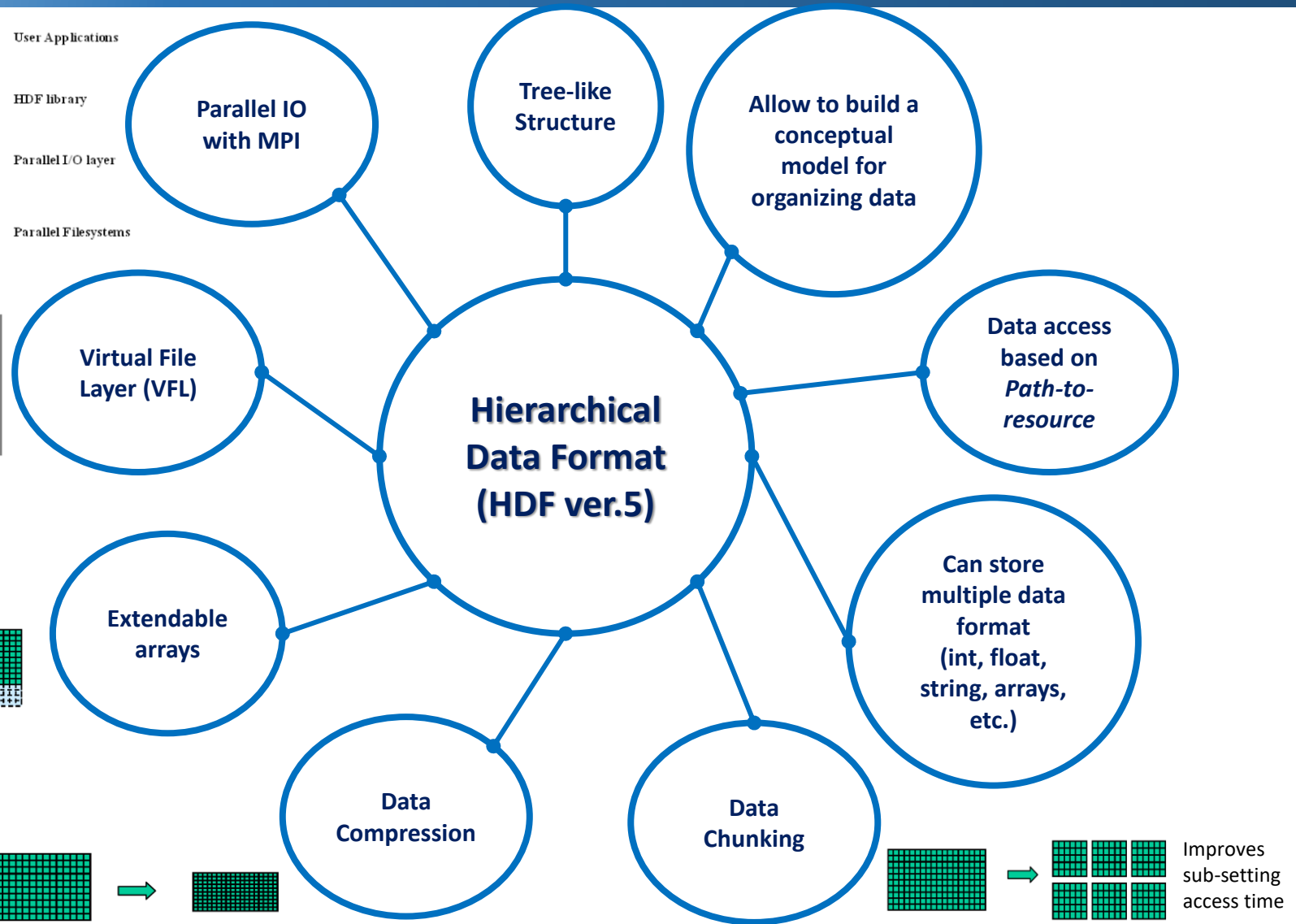
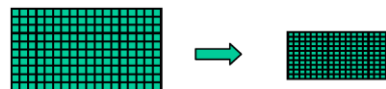
Parallel Filesystems



Extended in any direction

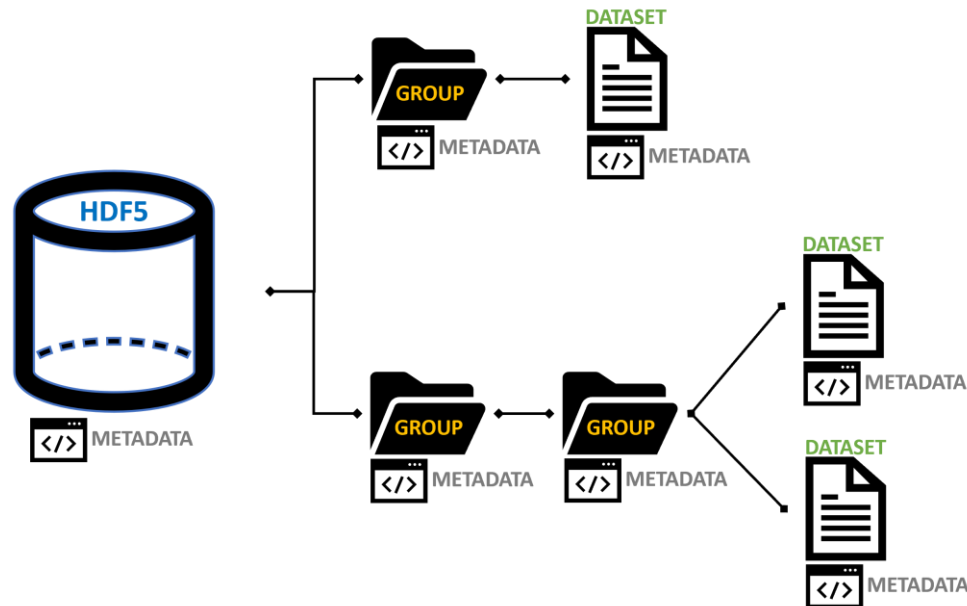


Improves efficiency and data transmission speed



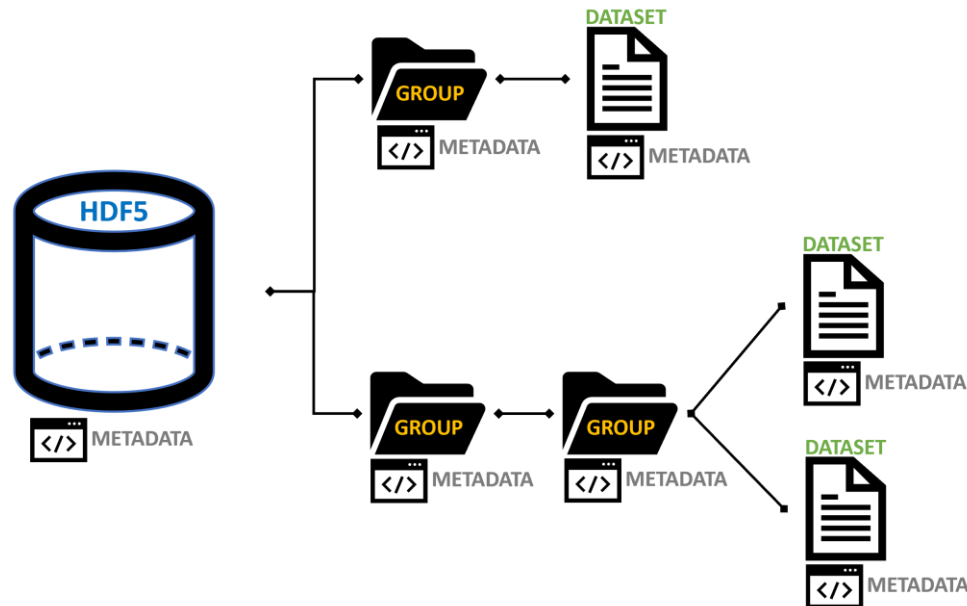
Isotta Fraschini Motori

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HDF5 has three main objects:

- **GROUPS**
 - Overarching structures aimed to collect related objects
 - Always present a *Root Group*
- **DATASETS**
 - Include a multidimensional array of elements
 - Usually stored within groups
- **ATTRIBUTES**
 - Additional user-defined metadata associated to Group or Dataset
 - Paradigm *Key-Value*



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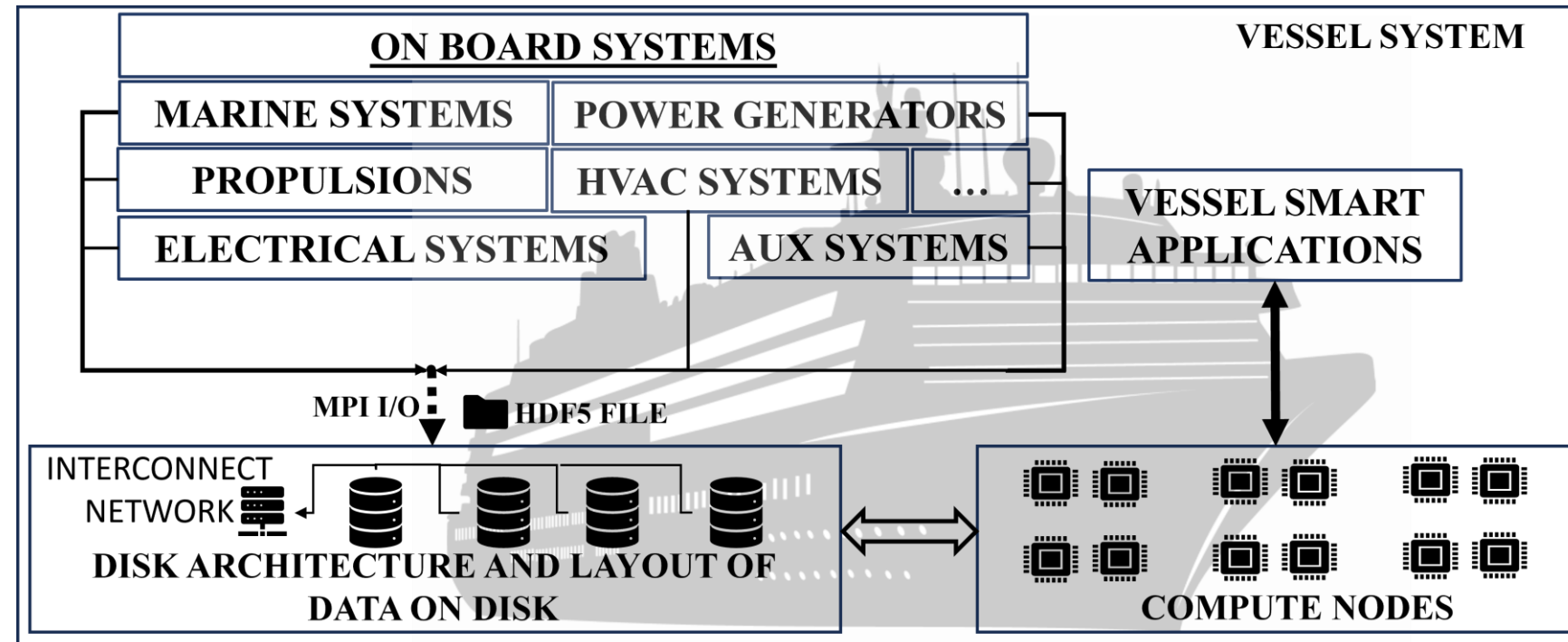
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...Why HDF5 for our purposes?

HDF5 is a great candidate for our purposes:

- Hierarchical data organization
- Attributes storage
- Compression
- Multi-dimensional capabilities
- Intuitive path-to-resource approach
- Parallel IO

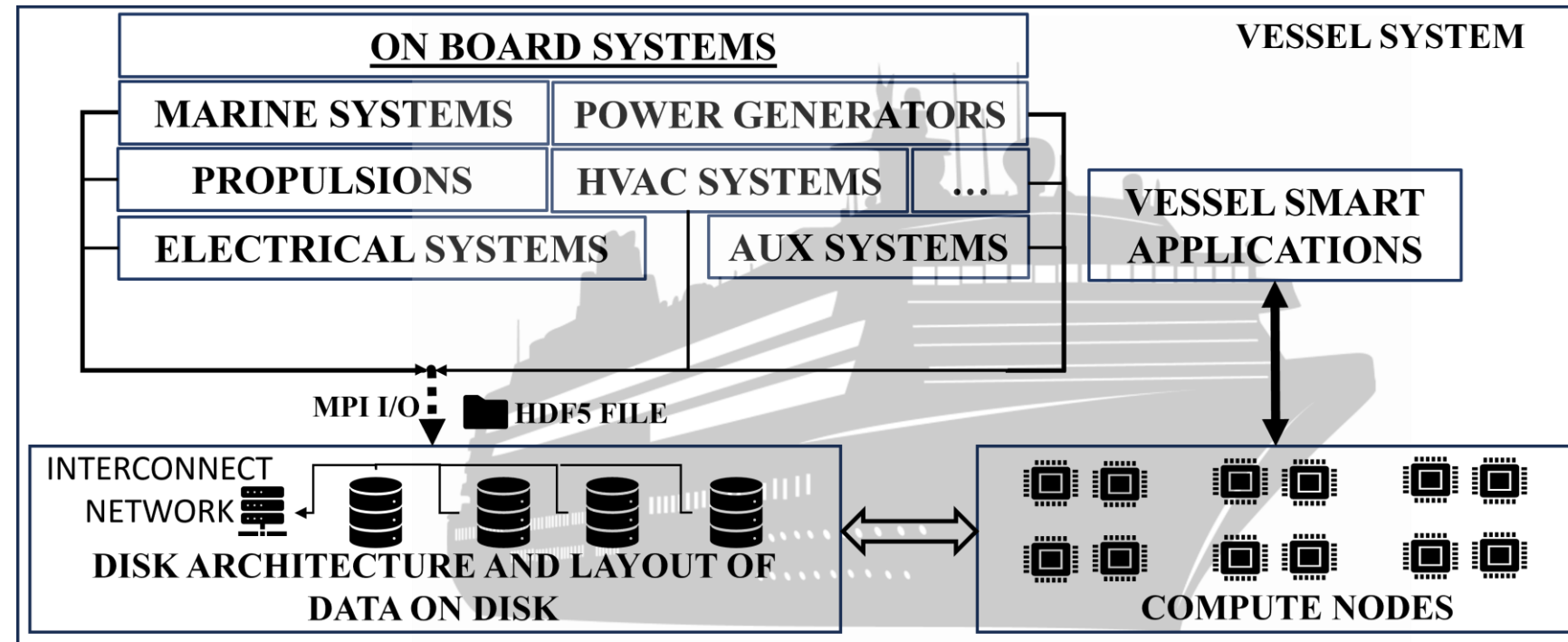
High level application developers will love it!



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High level application developers will love it!



...How do we plan to use HDF5?

POPULAR COMMUNICATION PROTOCOLS IN MARINE ENGINE APPLICATIONS

[CAN bus...in a nutshell]

Controller Area Network (CAN) is/was/has:

- an International Standardization Organization (ISO) serial communication protocol
- Developed by BOSCH in 1991 as a multi-master broadcast system
- Max speed rate is 1 Mbps
- High Reliability

ISO/OSI LAYERS		CAN BUS STACK LAYERS	
7	APPLICATION	✓	Based on CAN version*
6	PRESENTATION	✗	
5	SESSION	✗	
4	TRANSPORT	✓	**
3	NETWORK	✓	**
2	DATA LINK	✓	ISO 11898
1	PHYSICAL	✓	ISO 11898

ISO-OSI CAN bus layers stack



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POPULAR COMMUNICATION PROTOCOLS IN MARINE ENGINE APPLICATIONS

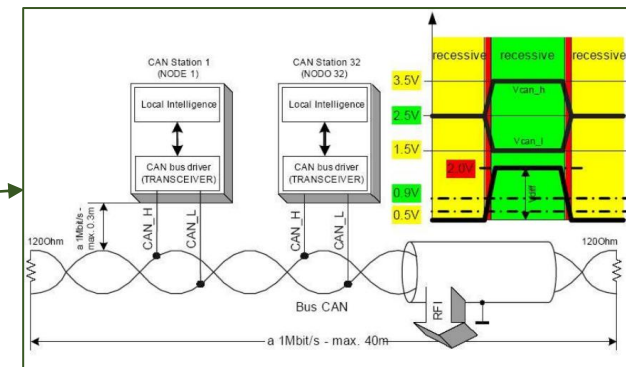
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1	PHYSICAL	✓	ISO 11898

ISO-OSI CAN bus layers stack



CAN Physical layer

- 2 wire bus
- Twisted pair cable
- Differential signal
- Strong **immunity to EM interferences**
- High resistance to transmission errors

POPULAR COMMUNICATION PROTOCOLS IN MARINE ENGINE APPLICATIONS

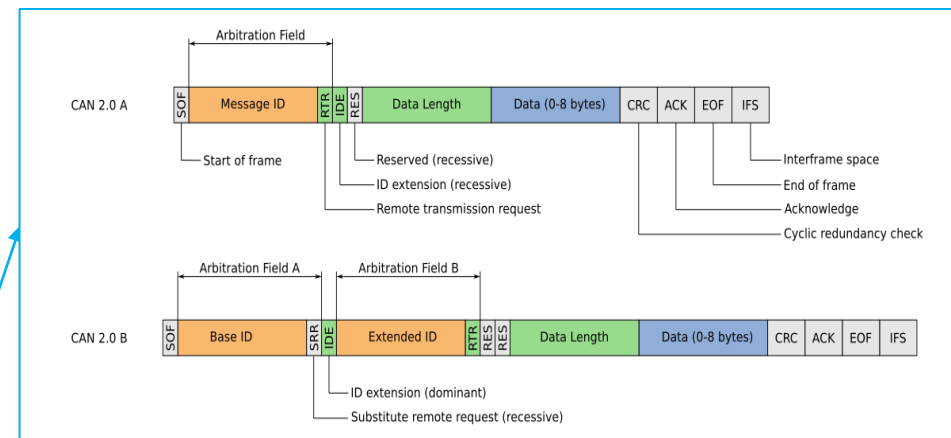
[CAN bus...in a nutshell]

Controller Area Network (CAN) is/was/has:

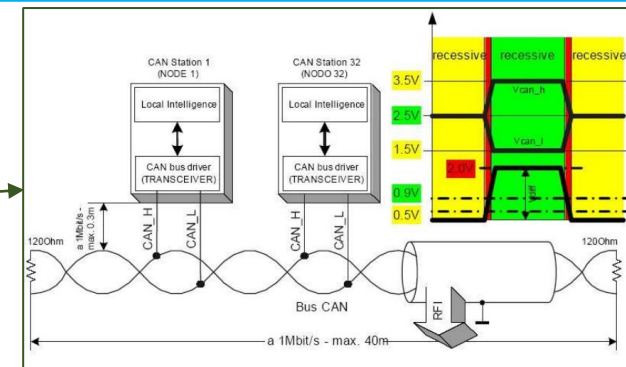
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ISO-OSI CAN bus layers stack



CAN Data Frame



CAN Physical layer

- Two *Data Frame* variant are available from standard:
 - 2.0A (11-bit identifier)
 - 2.0B (29-bit identifier)
- The CAN FD (Flexible Data Rate) variant allows to increase data length and switching between rate

- 2 wire bus
- Twisted pair cable
- Differential signal
- Strong immunity to EM interference
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POPULAR COMMUNICATION PROTOCOLS IN MARINE ENGINE APPLICATIONS

[CAN bus...in a nutshell]



Controller Area Network (CAN) is/was/has:

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- Developed by BOSCH in 1991 as a multi-master broadcast system
- Max speed rate is 1 Mbps
- High Reliability

Different application layers are available on the market, such as CANOpen and CAN-J1939. The latter was released by Society of Automotive Engineers (SAE):

- It exploit CAN protocol lower layer
- Max data rate is fixed @ 250 Kbps
- Based on CAN 2.0B where are included: Message Priority, Sender, Type of data and standardization of specific data frame with their content.

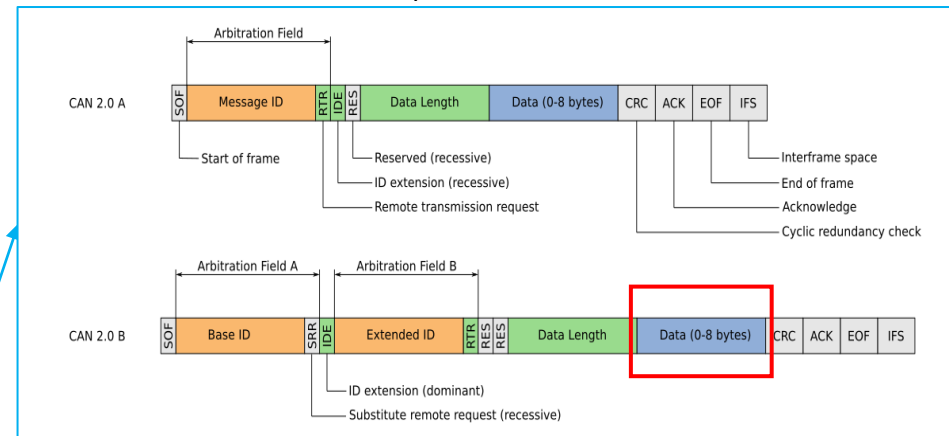
ISO/OSI LAYERS		CAN BUS STACK LAYERS	
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ISO-OSI CAN bus layers stack

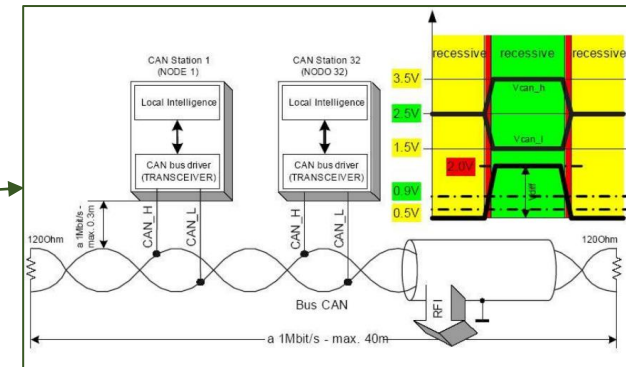
** optional for some CAN bus version



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CAN Data Frame



CAN Physical layer

- Two *Data Frame* variant are available from standard:
 - 2.0A (11-bit identifier)
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- The CAN FD (Flexible Data Rate) variant allows to increase data length and switching between rate

- 2 wire bus
- Twisted pair cable
- Differential signal
- Strong immunity to EM interference
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...We will come back on CAN bus protocol,
to see how it could work with HDF5!

POPULAR COMMUNICATION PROTOCOLS IN MARINE ENGINE APPLICATIONS

[MODBUS...in a nutshell]

MODBUS is:

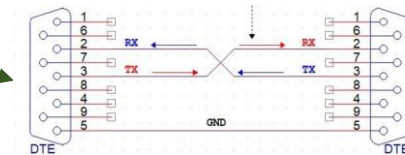
- A serial communication protocol
- Developed by Modicon in 1979 for Programmable Logic Controllers (PLC)
- A Master-Slave APPLICATION protocol
- Largely used in Industrial control systems

ISO/OSI LAYERS		MODBUS STACK LAYERS	
7	APPLICATION	✓	MODBUS APPLICATION LAYER
6	PRESENTATION	✗	
5	SESSION	✗	
4	TRANSPORT	✓	MODBUS TCP
3	NETWORK	✓	IP
2	DATA LINK	✓	ETHERNET
1	PHYSICAL	✓	ETHERNET ISO 8802-3

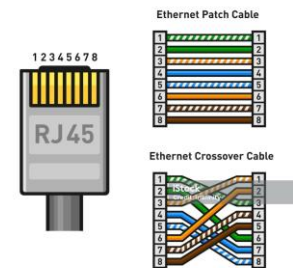
		✗	
		✗	
		✗	
		✗	
		✗	
		✓	SERIAL LINE M/S
		✓	EIA 485/232

MODBUS TCP/IP MODBUS ASCII/RTU

ISO-OSI MODBUS layers stack



Serial RS232 physical layer



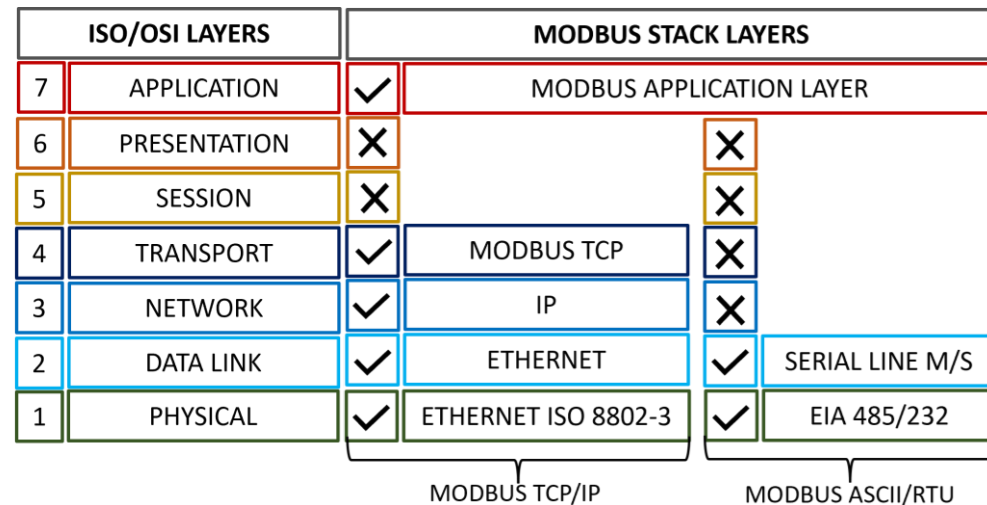
Ethernet physical layer

POPULAR COMMUNICATION PROTOCOLS IN MARINE ENGINE APPLICATIONS

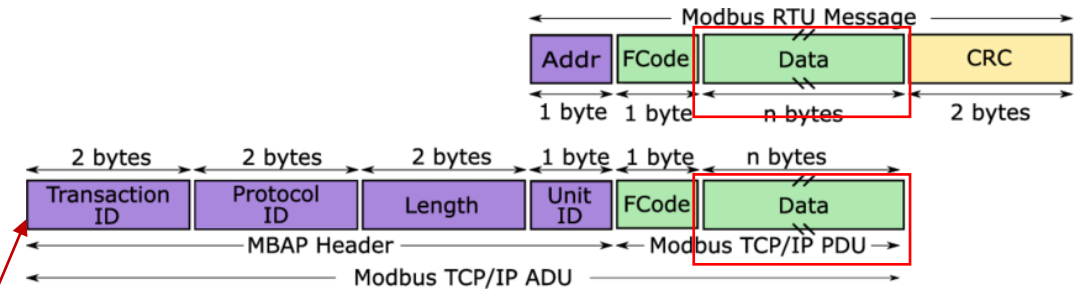
[MODBUS...in a nutshell]

MODBUS is:

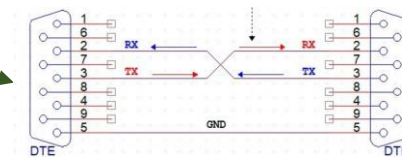
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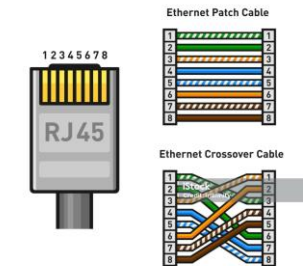
ISO-OSI MODBUS layers stack



- The Function Code determines the type of action to be performed by the receiving device:
 - Read or Write from/on Slave
 - Coils (binary variable), physical Inputs or Internal Registers (16 bits or multiple) from Slave



Serial RS232 physical layer



Ethernet physical layer

POPULAR COMMUNICATION PROTOCOLS IN MARINE ENGINE APPLICATIONS

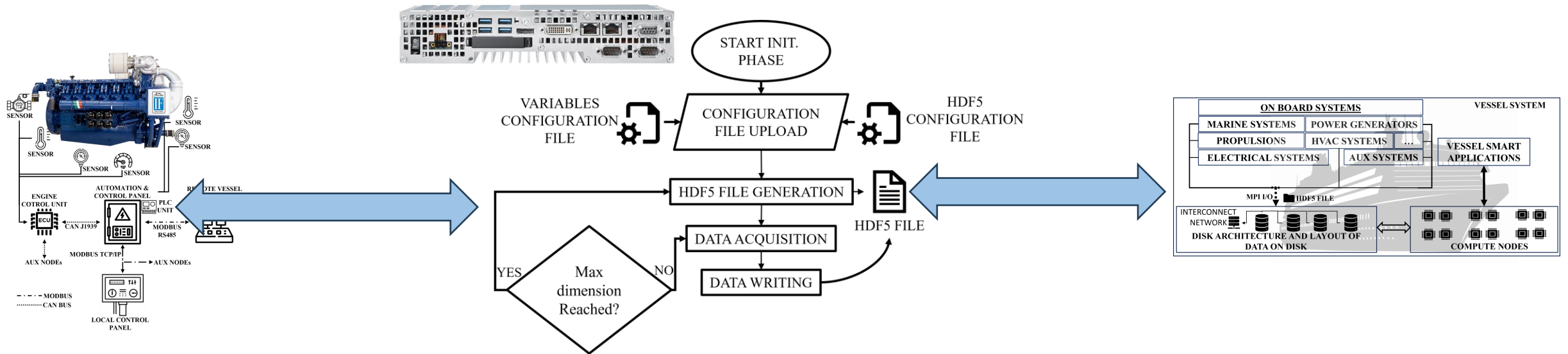
... Interesting, and where HDF5 is? 🤔



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Data Gathering System



Based on **h5py Python library** which provides a high- and low-level interface to the HDF5 library:

- A complete wrapping of the HDF5 API (low-level)
- Access to HDF5 files, datasets and groups based on NumPy usage (high-level).

HDF5 and MARINE ENGINES *[TYPICAL VARIABLE CONFIGURATION FILES]*



CAN Messages									
	Name	ID Decimal	ID HEX	PGN Decimal	PGN HEX	Frame Format	DLC	TX Node	Comment
7	EEC1	418382849	18f00401	---	----	Extended	8	IFM_Engi...	Electroni...
8	EC1	419357441	18fee301	---	----	Extended	39	IFM_Engi...	Engine_C...
9	AT1IG2	419279873	18fdb401	---	----	Extended	8	IFM_Engi...	After_Tre...
10	AT1OG2	419279617	18fdb301	---	----	Extended	8	IFM_Engi...	After_Tre...
11	AT2OG2	419278849	18fdb001	---	----	Extended	8	IFM_Engi...	After_Tre...
12	AT2IG2	419279105	18fdb101	---	----	Extended	8	IFM_Engi...	After_Tre...
13	CA	254	000000fe	0	00000	J1939PGN	8	IFM_Engi...	Commam... Ge
14	AMB	419362049	18fef501	---	----	Extended	8	IFM_Engi...	Ambient...
15	EDC1	419377153	18ff3001	---	----	Extended	8	IFM_Engi...	EDC_Stat... Ge
16	EDC2	419377409	18ff3101	---	----	Extended	8	IFM_Engi...	EDC_FFR... Ge
17	EDC3	419377665	18ff3201	---	----	Extended	8	IFM_Engi...	EDC_Curr...

< >

Signals of Selected CAN Message

	Name	Type	Byteorder	Mode	Bitpos	Length	Factor	Offset	Minimum	Maximum
1	SrcAddressOfCtrlringDvcFrEngCntl	Unsigned	Intel	Signal	40	8	1	0	0	255
2	ActEngPrcntTrqueHighResolution	Unsigned	Intel	Signal	4	4	0.125	0	0	0.875
3	EngDemandPercentTorque	Unsigned	Intel	Signal	56	8	1	-125	-125	125
4	EngStarterMode	Unsigned	Intel	Signal	48	4	1	0	0	15
5	EngSpeed	Unsigned	Intel	Signal	24	16	0.125	0	0	8031.88
6	ActualEngPercentTorque	Unsigned	Intel	Signal	16	8	1	-125	-125	125
7	DriversDemandEngPercentTorque	Unsigned	Intel	Signal	8	8	1	-125	-125	125
8	EngTorqueMode	Unsigned	Intel	Signal	0	4	1	0	0	15

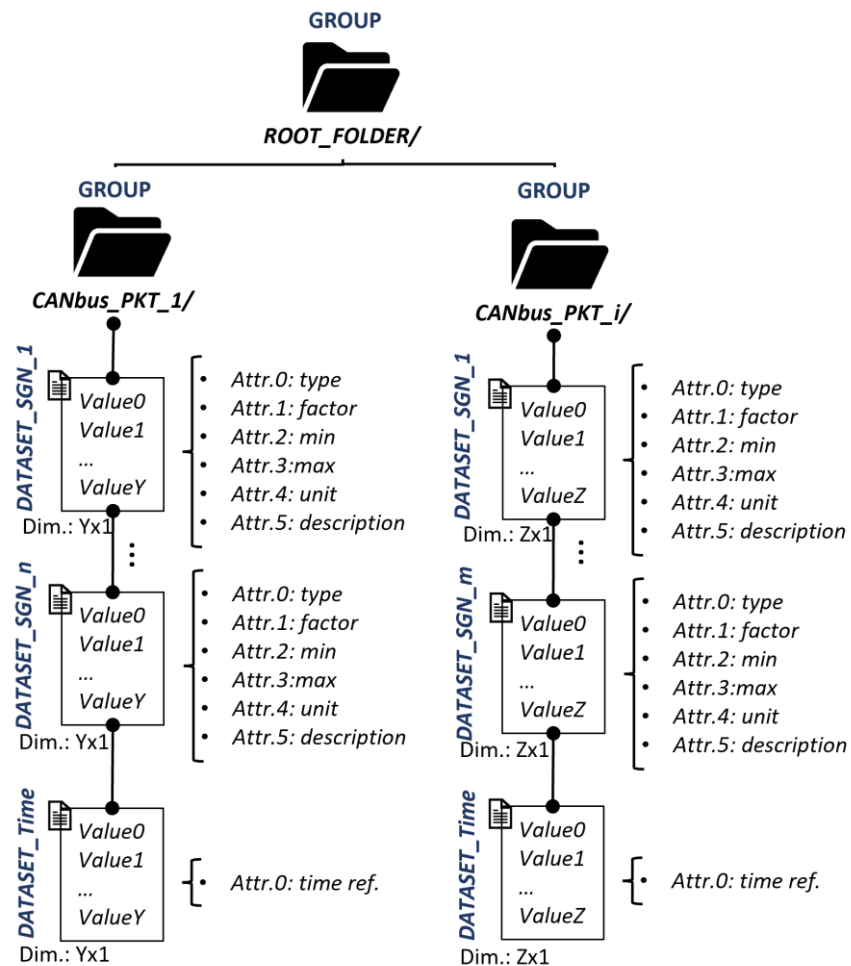
< >

MODBUS variables are usually mapped through a .csv file:



Information / Informazione						Automation / Automazione											
**DGSA Diesel Generator Set **LCPH Local Control Panel						EXCHANGE DATA / SCAMBIO DATI											
Tag/Variable	Reference/Riferimento					Type / Tipo	PLC	MODBUS	Bt	Dt	HW IN	HW OUT	MIN	MAX	MULT./ MOLT.	UNIT / UNITA'	DG CHANGE/ CAMBIO DG
DgOil In_Sump_Temp_CH_F	Channel fault or sensor faults! Avaria canale o sensore TT04.02					BOOL	%M1569	%MW1012	-	OUT							
DgOil Turbine_A_Press_CH_F	Channel fault or sensor faults! Avaria canale o sensore PT04.04					BOOL	%M1603	%MW1012	-	OUT							
DgOil Turbine_B_Press_CH_F	Channel fault or sensor faults! Avaria canale o sensore PT04.05					BOOL	%M1602	%MW1012	-	OUT							
DgOil Alarms_Summary	Oil circuit alarms summary / Cumulative alarms circuito olio motore					BOOL	%M210	%MW1012	-	OUT							
DgOil Bel_Filter_Press	PT04.02: Oil pressure before filter / Pressione olio prima del filtro					WORD	%MW1514	%MW1013	-	OUT			0	100	0.1	bar	
DgOil Afr_Filter_Press	PT04.03: Oil pressure after filter / Pressione olio dopo del filtro					WORD	%MW1513	%MW1014	-	OUT			0	100	0.1	bar	
DgOil Temp	TT04.01: Lub oil bank inlet! Pressione olio ingresso bancate					WORD	%MW1533	%MW1015	-	OUT			0	2000	0.1	°C	
DgOil In_Sump_Temp	TT04.02: Lub oil in sump temperature! Temperatura olio in coppa					WORD	%MW1534	%MW1016	-	OUT			0	2000	0.1	°C	
DgOil Turbine_A_Press	PT04.04 Turbine_A oil pressure / Pressione olio turbina bancata A					WORD	%MW1571	%MW1017	-	OUT			0	60	0.1	bar	
DgOil Turbine_B_Press	PT04.05 Turbine_B oil pressure / Pressione olio turbina bancata B					WORD	%MW1571	%MW1018	-	OUT			0	60	0.1	bar	
DgOil Crankcase_Oil_pressure	PT04.06:Crankcase oil pressure/Pressione olio carter					WORD	%MW1596	%MW1019	-	OUT			-5	20	0.01	bar	

The proposed HDF5 tree-architecture for CAN bus J1939 is the following:

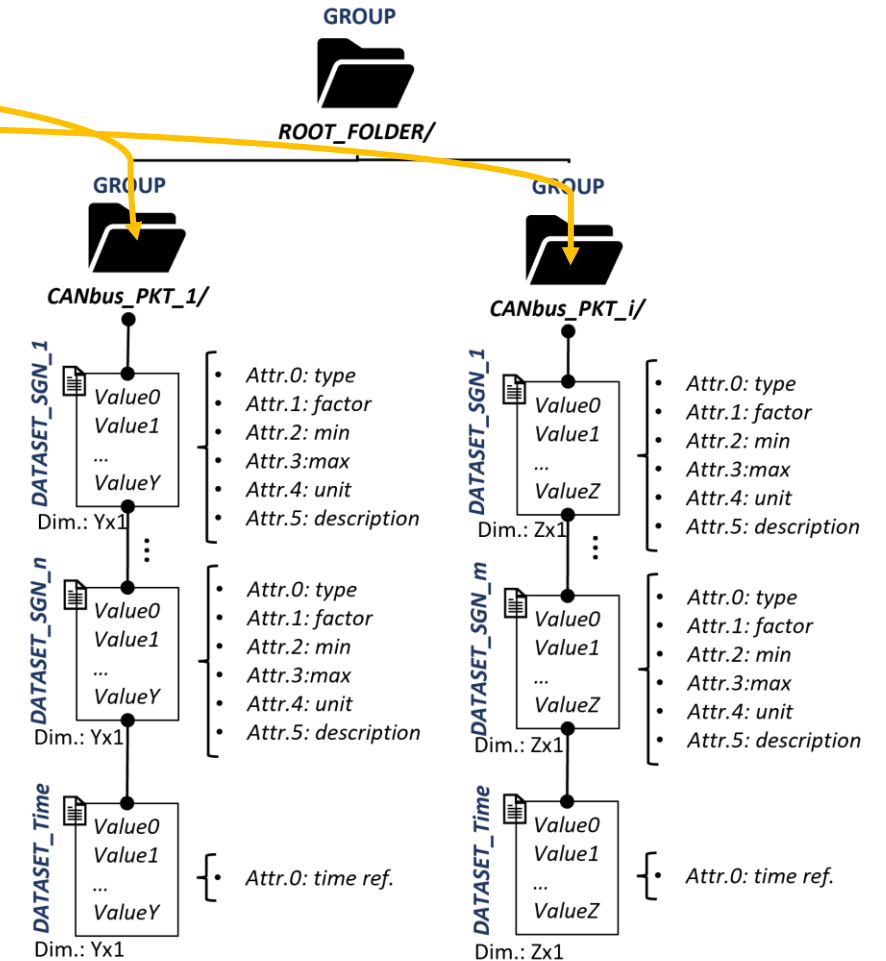


[A] Over CAN bus different frames with different frequencies can travel.

CAN Messages									
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14	AMB	419362049	18fef501	---	---	Extended	8	IFM_Engi...	Ambient...
15	EDC1	419377153	18ff3001	---	---	Extended	8	IFM_Engi...	EDC_Stat... Ge
16	EDC2	419377409	18ff3101	---	---	Extended	8	IFM_Engi...	EDC_FFR... Ge
17	EDC3	419377665	18ff3201	---	---	Extended	8	IFM_Engi...	EDC_Curr...

Signals of Selected CAN Message										
	Name	Type	Byteorder	Mode	Bitpos	Length	Factor	Offset	Minimum	Maximum
1	SrcAddrssOfCtrlngDvcfrEngCntrl	Unsigned	Intel	Signal	40	8	1	0	0	255
2	ActlEngPrcentTorqueHighResolution	Unsigned	Intel	Signal	4	4	0,125	0	0	0,875
3	EngDemandPercentTorque	Unsigned	Intel	Signal	56	8	1	-125	-125	125
4	EngStarterMode	Unsigned	Intel	Signal	48	4	1	0	0	15
5	EngSpeed	Unsigned	Intel	Signal	24	16	0,125	0	0	8031,88
6	ActualEngPercentTorque	Unsigned	Intel	Signal	16	8	1	-125	-125	125
7	DriversDemandEngPercentTorque	Unsigned	Intel	Signal	8	8	1	-125	-125	125
8	EngTorqueMode	Unsigned	Intel	Signal	0	4	1	0	0	15

CAN bus data frame composition (J1939)

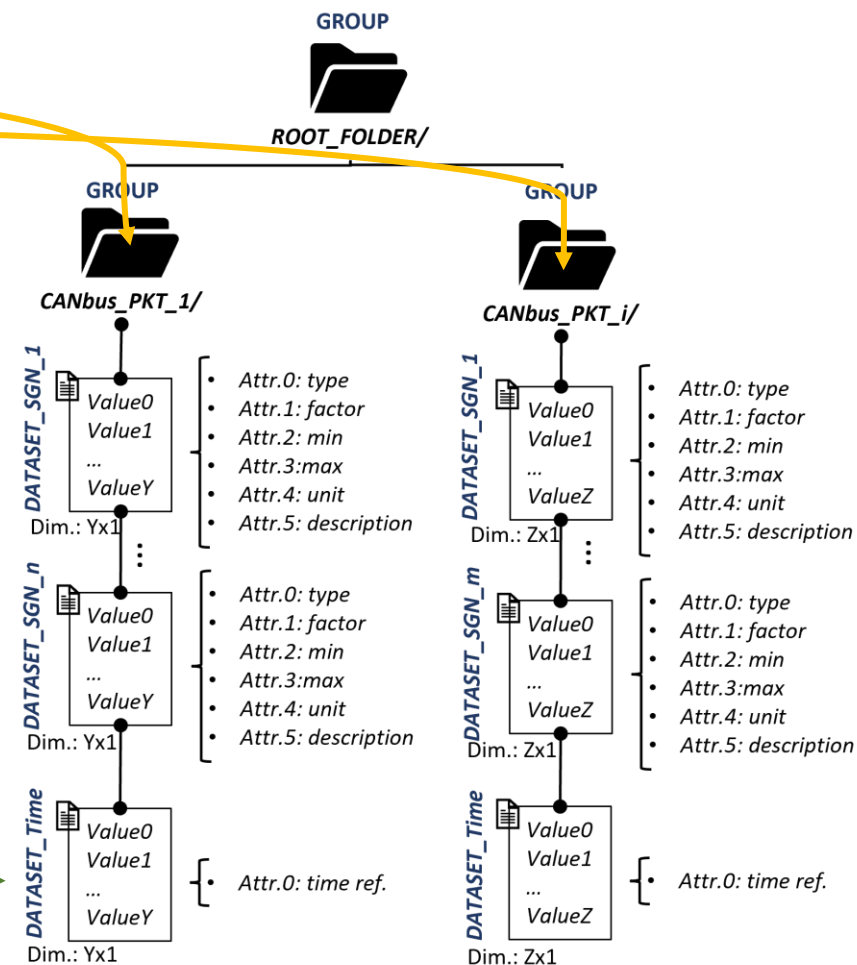


[A] Over CAN bus different frames with different frequencies can travel.

	Name	ID Decimal	ID HEX	PGN Decimal	PGN HEX	Frame Format	DLC	TX Node	Comment
7	EEC1	418382849	18f00401	---	---	Extended	8	IFM_Engi...	Ele...
8	EC1	419357441	18fee301	---	---	Extended	39	IFM_Engi...	Engine_C...
9	AT1IG2	419279873	18fdb401	---	---	Extended	8	IFM_Engi...	After_Tre...
10	AT1OG2	419279617	18fdb301	---	---	Extended	8	IFM_Engi...	After_Tre...
11	AT2OG2	419278849	18fdb001	---	---	Extended	8	IFM_Engi...	After_Tre...
12	AT2IG2	419279105	18fdb101	---	---	Extended	8	IFM_Engi...	After_Tre...
13	CA	254	000000fe	0	00000	J1939PGN	8	IFM_Engi...	Comman... Ge
14	AMB	419362049	18fef501	---	---	Extended	8	IFM_Engi...	Ambient...
15	EDC1	419377153	18ff3001	---	---	Extended	8	IFM_Engi...	EDC_Stat... Ge
16	EDC2	419377409	18ff3101	---	---	Extended	8	IFM_Engi...	EDC_FFR... Ge
17	EDC3	419377665	18ff3201	---	---	Extended	8	IFM_Engi...	EDC_Curr...

	Name	Type	Byteorder	Mode	Bitpos	Length	Factor	Offset	Minimum	Maximum
1	SrcAddrssOfCtrlngDvcfrEngCntrl	Unsigned	Intel	Signal	40	8	1	0	0	255
2	ActlEngPrcentTorqueHighResolution	Unsigned	Intel	Signal	4	4	0,125	0	0	0,875
3	EngDemandPercentTorque	Unsigned	Intel	Signal	56	8	1	-125	-125	125
4	EngStarterMode	Unsigned	Intel	Signal	48	4	1	0	0	15
5	EngSpeed	Unsigned	Intel	Signal	24	16	0,125	0	0	8031,88
6	ActualEngPercentTorque	Unsigned	Intel	Signal	16	8	1	-125	-125	125
7	DriversDemandEngPercentTorque	Unsigned	Intel	Signal	8	8	1	-125	-125	125
8	EngTorqueMode	Unsigned	Intel	Signal	0	4	1	0	0	15

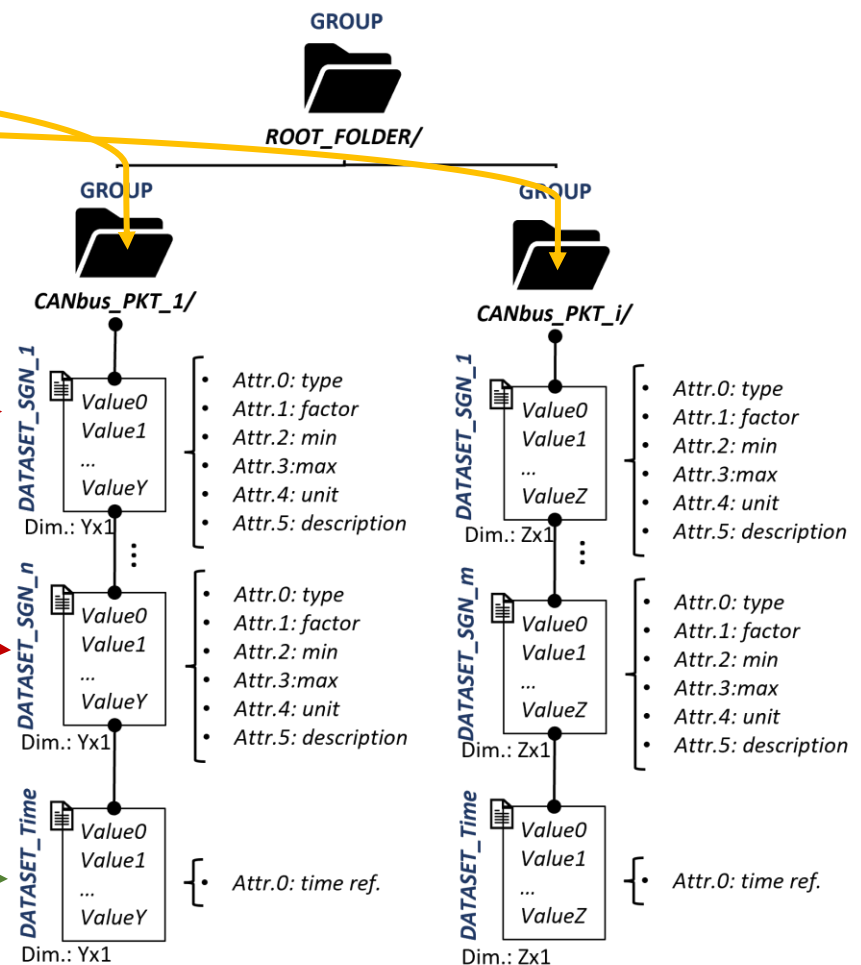
CAN bus data frame composition (J1939)



[HDF5 CAN bus TREE-ARCHITECTURE]

[B] Each CAN frame is filled with its own Data (called in J1939: SIGNALS)

CAN bus data frame composition (J1939)



[A] Over CAN bus different frames with different frequencies can travel.

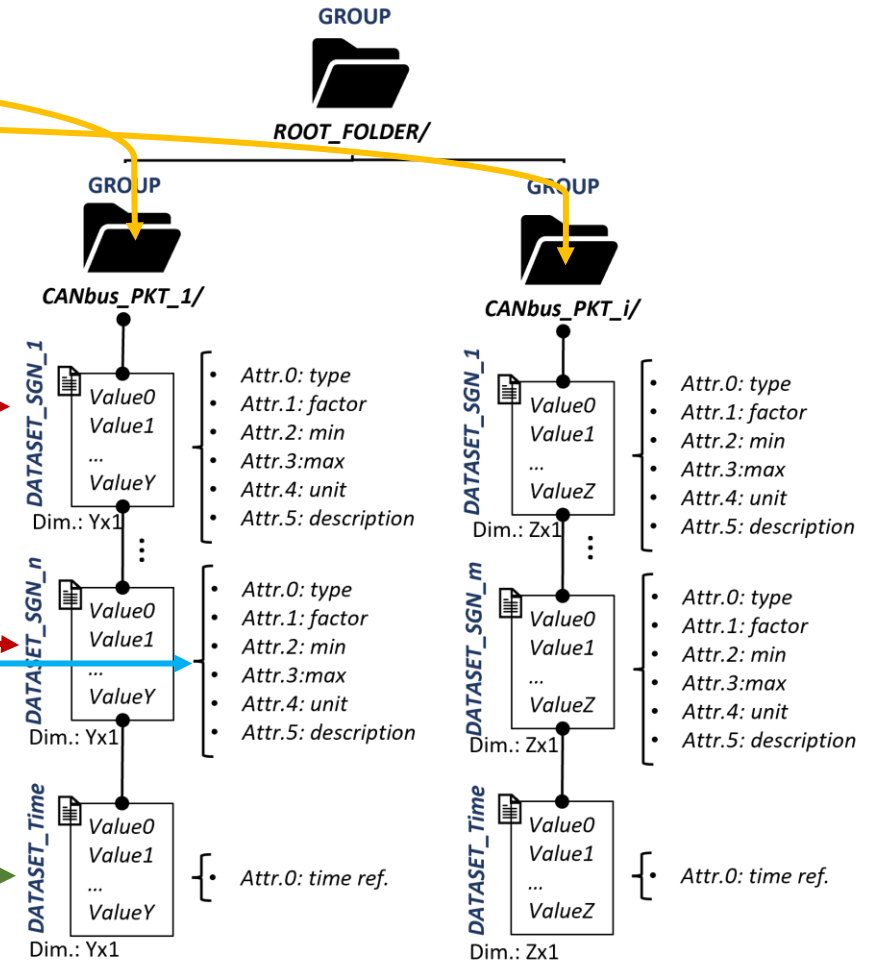
[B] Each CAN frame is filled with its own Data (called in J1939: SIGNALS)

Name	ID Decimal	ID HEX	BCN Decimal	BCN HEX	Frame Format	DLC	TX Node	Comment
7 EEC1	418382849	18f00401	---	---	Extended	8	IFM_Eng...	Electroni...
8 EC1	419357441	18f0e301	---	---	Extended	30	IFM_Eng...	Engine C...
9 AT1G2	419329873	18f0b401	---	---	Extended	8	IFM_Eng...	After Tre...
10 AT1OG2	419279617	18f0b301	---	---	Extended	8	IFM_Eng...	After Tre...
11 AT2OG2	419278849	18f0b001	---	---	Extended	8	IFM_Eng...	After Tre...
12 AT2IG2	419279105	18f0b101	---	---	Extended	8	IFM_Eng...	After Tre...
13 CA	254	000000fe	0	00000	J1939PGN	8	IFM_Eng...	Commant...
14 AMB	419362049	18f0f501	---	---	Extended	8	IFM_Eng...	Ambient...
15 EDC1	419377153	18f03001	---	---	Extended	8	IFM_Eng...	EDC_Stat...
16 EDC2	419377409	18f03101	---	---	Extended	8	IFM_Eng...	EDC_FFR...
17 EDC3	419377665	18f03201	---	---	Extended	8	IFM_Eng...	EDC_Curr...

Name	Type	Byteorder	Mode	Bitpos	Length	Factor	Offset	Minimum	Maximum
1 SrcAddressOfCtrlngDvcFrEngCntrl	Unsigned	Intel	Signal	40	8	1	0	0	255
2 ActEngPrntTrqueHighResolution	Unsigned	Intel	Signal	4	4	0,125	0	0	0,875
3 EngDemandPercentTorque	Unsigned	Intel	Signal	56	8	1	-125	-125	125
4 EngStarterMode	Unsigned	Intel	Signal	48	4	1	0	0	15
5 EngSpeed	Unsigned	Intel	Signal	24	16	0,125	0	0	8031,88
6 ActualEngPercentTorque	Unsigned	Intel	Signal	16	8	1	-125	-125	125
7 DriversDemandEngPercentTorque	Unsigned	Intel	Signal	8	8	1	-125	-125	125
8 EngTorqueMode	Unsigned	Intel	Signal	0	4	1	0	0	15

CAN bus data frame composition (J1939)

[C] Each signal has its own properties that can be stored as ATTRIBUTES within HDF5 file.



How the HDF5 CAN bus file appears within HDFView (open-source software)

ROOT GROUP ←

ATTRIBUTES ←

GROUP ←

DATASET ←

HDFView 3.1.4
File Window Tools Help

Recent Files

000103 CAN 2023-02-15-13-56-49.hdf5

- Root_Can
 - AMB
 - AT1IG2
 - AT1OG2
 - AT2IG2
 - AT2OG2
 - CA
 - EC1
 - EDC1
 - EDC10
 - EDC2
 - EDC3
 - EDC4
 - EDC5
 - EDC6
 - EDC7
 - EDC8
 - EDC9
 - EEC1
 - ActlEngPrctTrqueHighResolution
 - ActualEngPercentTorque
 - DriversDemandEngPercentTorque
 - EngDemandPercentTorque
 - EngSpeed
 - EngStarterMode
 - EngTorqueMode
 - SrcAddrssOfCtrlngDvcFrEngCntrl

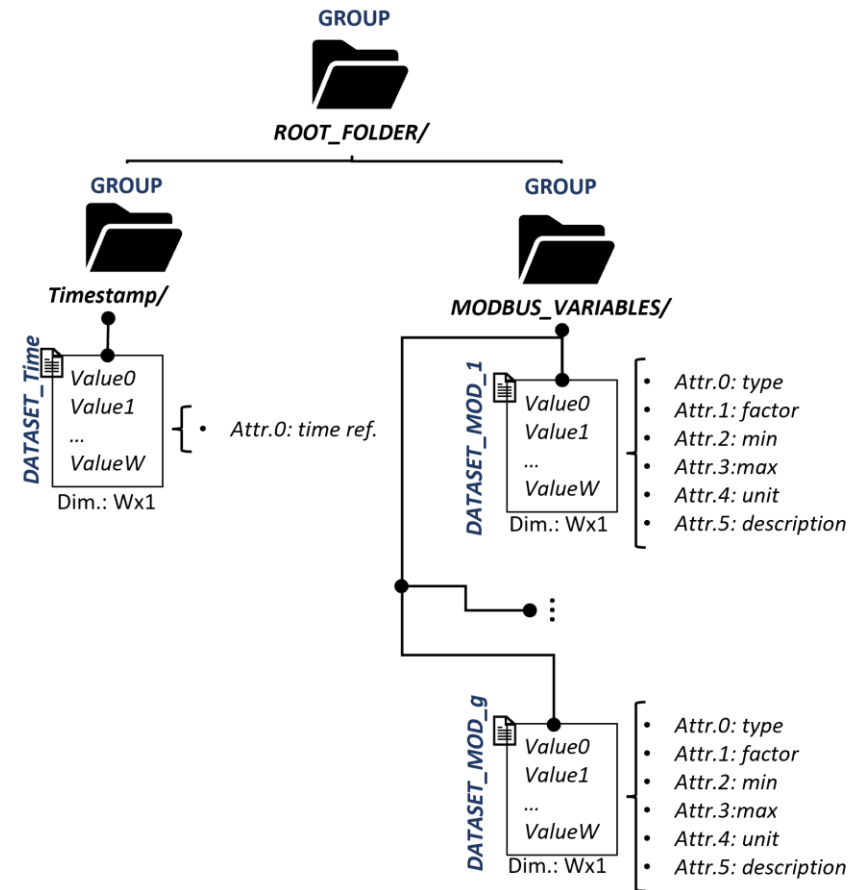
Object Attribute Info General Object Info

Attribute Creation Order: Creation Order NOT Tracked

Number of attributes = 5

Name	Type	Array Size	Value[50](...)
MAX	String, length = variable,...	Scalar	8031.875
MIN	String, length = variable,...	Scalar	0.0
MOLT	String, length = variable,...	Scalar	0.125
OFFS	String, length = variable,...	Scalar	0.0
UNIT	String, length = variable,...	Scalar	rpm

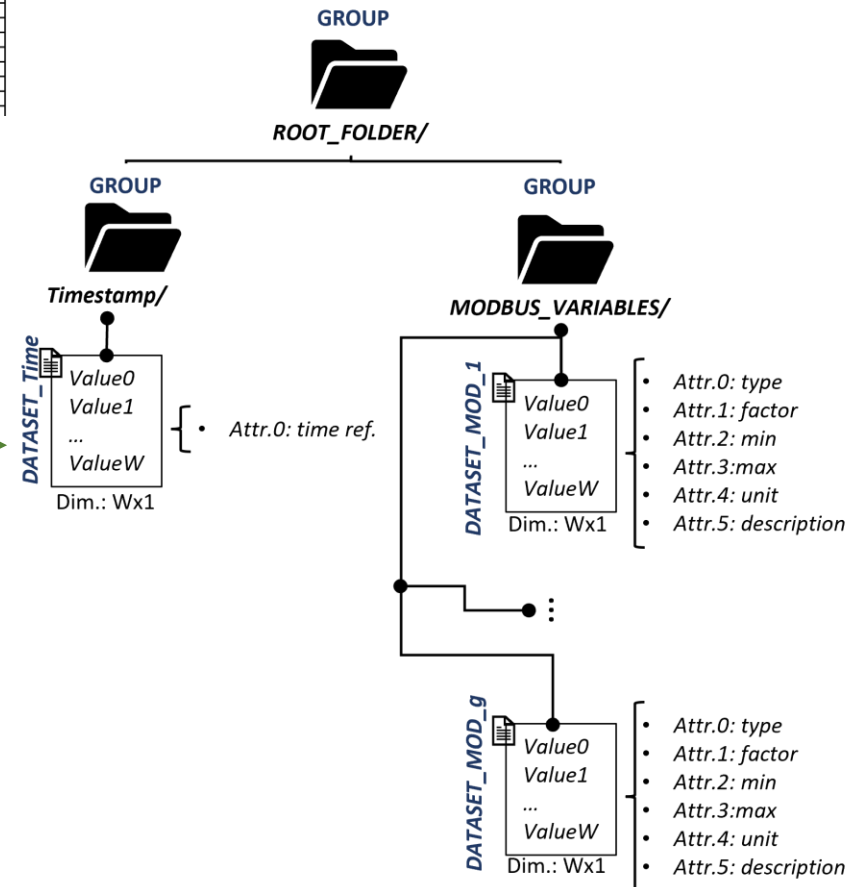
The proposed HDF5 tree-architecture for MODBUS is the following:



Information / Informazione		Automation / Automazione											
Tag/Variable		EXCHANGE DATA / SCAMBIO DATI											
Reference/Riferimento		Type / Tipo	PLC	MODBUS	Bit	DIR	HW IN	HW OUT	MIN	MAX	MULT. / MOLT.	UNIT / UNITA'	DG CHANGE/ CAMBIO DG
DGxOil_In_Sump_Temp_CH_F	Channel fault or sensor fault/ Avaria canale o sensore TT04.02	BOOL	%M1589	%MW1012	12	OUT							
DGxOil_Turbine_A_Press_CH_F	Channel fault or sensor fault/ Avaria canale o sensore PT04.04	BOOL	%M1603	%MW1012	13	OUT							
DGxOil_Turbine_B_Press_CH_F	Channel fault or sensor fault/ Avaria canale o sensore PT04.05	BOOL	%M1602	%MW1012	14	OUT							
DGxOil Alarms Summary	Oil circuit alarms summary / Cumulativo allarmi circuito olio motore	BOOL	%M210	%MW1012	15	OUT							
DGxOil_Bef_Filter_Press	PT04.02: Oil pressure before filter / Pressione olio prima del filtro	WORD	%MW1514	%MW1013	-	OUT			0	100	0.1	bar	
DGxOil_Alt_Filter_Press	PT04.03: Oil pressure After filter / Pressione olio dopo del filtro	WORD	%MW1513	%MW1014	-	OUT			0	100	0.1	bar	
DGxOil_Temp	TT04.01: Lub oil bank inlet/ Pressione olio ingresso bancate	WORD	%MW1533	%MW1015	-	OUT			0	2000	0.1	°C	
DGxOil_In_Sump_Temp	TT04.02: Lub oil in sump temperature/ Temperatura olio in coppa	WORD	%MW1534	%MW1016	-	OUT			0	2000	0.1	°C	
DGxOil_Turbine_A_Press	PT04.04 Turbine A oil pressure / Pressione olio turbina bancata A	WORD	%MW1517	%MW1017	-	OUT			0	60	0.1	bar	
DGxOil_Turbine_B_Press	PT04.05 Turbine B oil pressure / Pressione olio turbina bancata B	WORD	%MW1571	%MW1018	-	OUT			0	60	0.1	bar	
DGxOil_Crankcase_Oil_pressure	PT04.06: Crankcase oil pressure/ Pressione olio carter	WORD	%MW1596	%MW1019	-	OUT			-5	20	0.01	bar	

MODBUS variables list

[A] All MODBUS memory is read at the same time so just one time reference sample is needed to be stored.

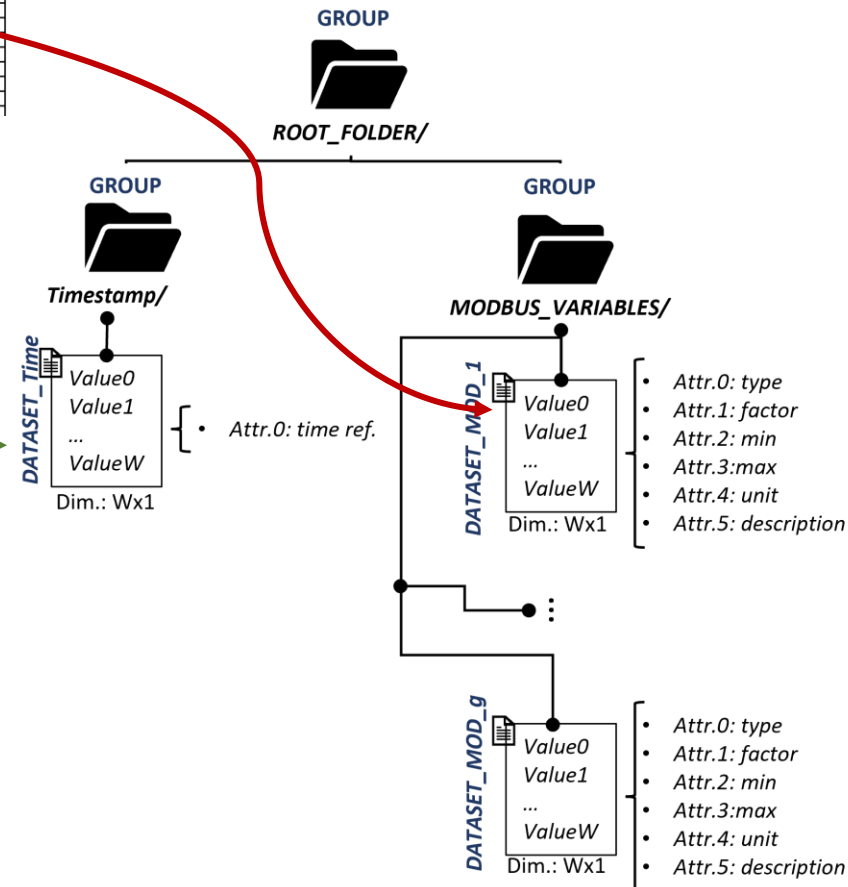


Information / Informazione		Automation / Automazione											
Tag/Variable		EXCHANGE DATA / SCAMBIO DATI											
Reference/Riferimento		Type / Tipo	PLC	MODBUS	Bit	DIR	HW IN	HW OUT	MIN	MAX	MULT. / MOLT.	UNIT / UNITA'	DG CHANGE/ CAMBIO DG
DGxOil_In_Sump_Temp_CH_F	Channel fault or sensor fault/ Avaria canale o sensore TT04.02	BOOL	%M1589	%MW1012	12	OUT							
DGxOil_Turbine_A_Press_CH_F	Channel fault or sensor fault/ Avaria canale o sensore PT04.04	BOOL	%M1603	%MW1012	13	OUT							
DGxOil_Turbine_B_Press_CH_F	Channel fault or sensor fault/ Avaria canale o sensore PT04.05	BOOL	%M1602	%MW1012	14	OUT							
DGxOil Alarms Summary	Oil circuit alarms summary / Cumulativo allarmi circuito olio motore	BOOL	%M210	%MW1012	15	OUT							
DGxOil_Bef_Filter_Press	PT04.02: Oil pressure before filter / Pressione olio prima del filtro	WORD	%MW1514	%MW1013	-	OUT			0	100	0.1	bar	
DGxOil_Aft_Filter_Press	PT04.03: Oil pressure After filter / Pressione olio dopo del filtro	WORD	%MW1513	%MW1014	-	OUT			0	100	0.1	bar	
DGxOil_Temp	TT04.01: Lub oil bank inlet/ Pressione olio ingresso bancate	WORD	%MW1533	%MW1015	-	OUT			0	2000	0.1	°C	
DGxOil_In_Sump_Temp	TT04.02: Lub oil in sump temperature/ Temperatura olio in coppa	WORD	%MW1534	%MW1016	-	OUT			0	2000	0.1	°C	
DGxOil_Turbine_A_Press	PT04.04 Turbine A oil pressure / Pressione olio turbina bancata A	WORD	%MW1517	%MW1017	-	OUT			0	60	0.1	bar	
DGxOil_Turbine_B_Press	PT04.05 Turbine B oil pressure / Pressione olio turbina bancata B	WORD	%MW1571	%MW1018	-	OUT			0	60	0.1	bar	
DGxOil_Crankcase_Oil_pressure	PT04.06:Crankcase oil pressure/Pressione olio carter	WORD	%MW1596	%MW1019	-	OUT			-5	20	0.01	bar	

MODBUS variables list

[A] All MODBUS memory are read at the same time so just one time reference sample is needed to be stored.

[B] Each variable has its own DATASET inside the same GROUP.



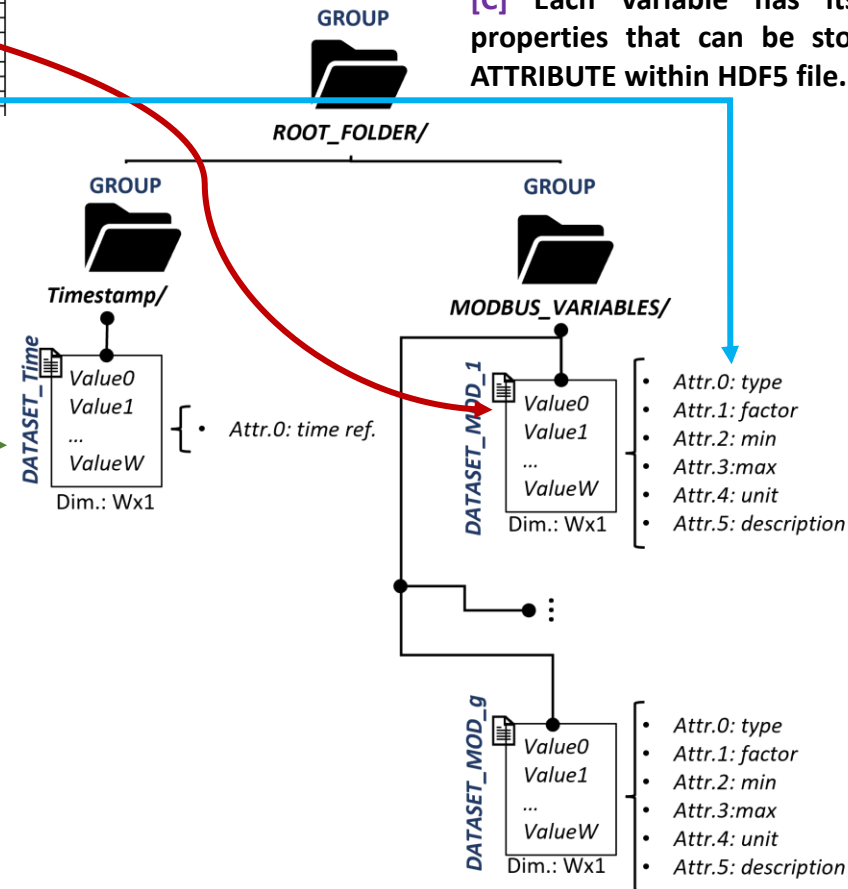
Information / Informazione		Automation / Automazione											
Tag/Variable		EXCHANGE DATA / SCAMBIO DATI											
Reference/Riferimento		Type / Tipo	PLC	MODBUS	Bit	DIR	HW IN	HW OUT	MIN	MAX	MULT. / MOLT.	UNIT / UNITA'	DG CHANGE/ CAMBIO DG
DGxOil_In_Sump_Temp_CH_F	Channel fault or sensor fault/ Avaria canale o sensore TT04.02	BOOL	%M1589	%MW1012	12	OUT							
DGxOil_Turbine_A_Press_CH_F	Channel fault or sensor fault/ Avaria canale o sensore PT04.04	BOOL	%M1603	%MW1012	13	OUT							
DGxOil_Turbine_B_Press_CH_F	Channel fault or sensor fault/ Avaria canale o sensore PT04.05	BOOL	%M1602	%MW1012	14	OUT							
DGxOil_Alarms_Summary	Oil circuit alarms summary / Cumulativo allarmi circuito olio motore	BOOL	%M210	%MW1012	15	OUT							
DGxOil_Bef_Filter_Press	PT04.02: Oil pressure before filter / Pressione olio prima del filtro	WORD	%MW1514	%MW1013	-	OUT			0	100	0.1	bar	
DGxOil_Aft_Filter_Press	PT04.03: Oil pressure After filter / Pressione olio dopo del filtro	WORD	%MW1513	%MW1014	-	OUT			0	100	0.1	bar	
DGxOil_Temp	TT04.01: Lub oil bank inlet/ Pressione olio ingresso bancate	WORD	%MW1533	%MW1015	-	OUT			0	2000	0.1	°C	
DGxOil_In_Sump_Temp	TT04.02: Lub oil in sump temperature/ Temperatura olio in coppa	WORD	%MW1534	%MW1016	-	OUT			0	2000	0.1	°C	
DGxOil_Turbine_A_Press	PT04.04 Turbine A oil pressure / Pressione olio turbina bancata A	WORD	%MW1517	%MW1017	-	OUT			0	60	0.1	bar	
DGxOil_Turbine_B_Press	PT04.05 Turbine B oil pressure / Pressione olio turbina bancata B	WORD	%MW1571	%MW1018	-	OUT			0	60	0.1	bar	
DGxOil_Crankcase_Oil_pressure	PT04.06:Crankcase oil pressure/Pressione olio carter	WORD	%MW1596	%MW1019	-	OUT			-5	20	0.01	bar	

MODBUS variables list

[A] All MODBUS memory are read at the same time so just one time reference sample is needed to be stored.

[B] Each variable has its own DATASET inside the same GROUP.

[C] Each variable has its own properties that can be stored as ATTRIBUTE within HDF5 file.



How the HDF5 MODBUS file appears within HDFView (open-source software)

ROOT GROUP

GROUP

ATTRIBUTES

DATASET

HDFView 3.1.4

File Window Tools Help

Recent Files

000072_TCPIP_2023-02-14-14-54-41.hdf5

- Root_Group
- Timestamp
- Variables
- DGxAlarms_Summary
- DGxAlt_ABHT
- DGxAlt_ABVHT
- DGxAlt_AWHT
- DGxAlt_AWVHT
- DGxAlt_Air_Intake_HL_Temp
- DGxAlt_Air_Intake_Temp
- DGxAlt_Air_Intake_Temp_CH_F
- DGxAlt_Air_Out_HL_Temp
- DGxAlt_Air_Out_Temp
- DGxAlt_Air_Out_Temp_CH_F
- DGxAlt_Alarms_Summary
- DGxAlt_Antisludge_ON_HW
- DGxAlt_Bearing_DS_HL_Temp
- DGxAlt_Bearing_DS_Temp
- DGxAlt_Bearing_DS_Temp_CH_F
- DGxAlt_Bearing_DS_VHL_Temp
- DGxAlt_Bearing_NDS_HL_Temp
- DGxAlt_Bearing_NDS_Temp
- DGxAlt_Bearing_NDS_Temp_CH_F
- DGxAlt_Bearing_NDS_VHL_Temp
- DGxAlt_Breaker_Closed
- DGxAlt_Cos_Fi
- DGxAlt_Current

Object Attribute Info General Object Info

Attribute Creation Order: Creation Order NOT Tracked

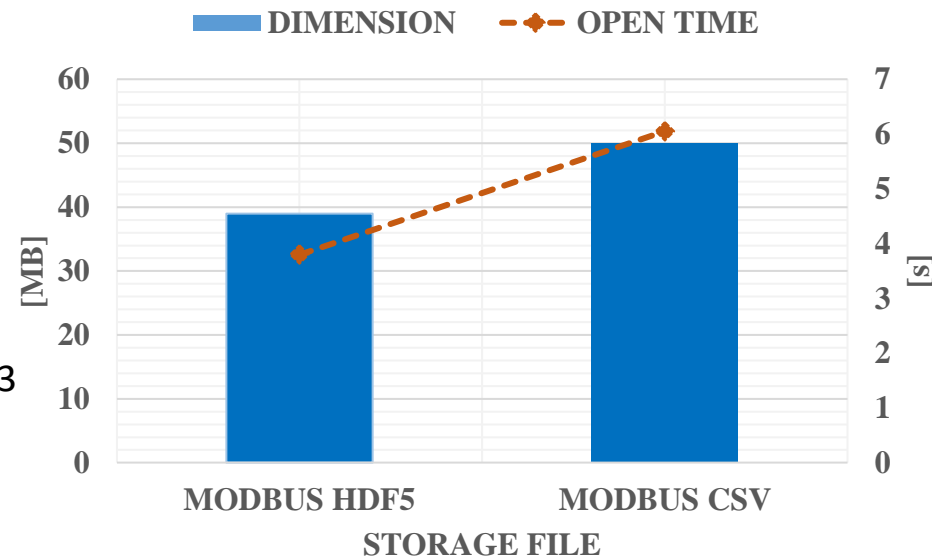
Number of attributes = 6

Name	Type	Array Size	Value[50](...)
DESCRIPTION	String, length...	Scalar	TT23.02 : Air coole...
MAX	String, length...	Scalar	1200
MIN	String, length...	Scalar	0
MOLT	String, length...	Scalar	0.1
SECTION DESCRIPTION	String, length...	Scalar	generator
UNIT	String, length...	Scalar	°C



Conditions*:

- Protocol: MODBUS TCP/IP
- # of variables: 457
- Sample rate: 3.5 sec
- # of attributes per variables: 6
- # of samples stored per variable: 17043
- Acquisition duration: 16 hours



Results:

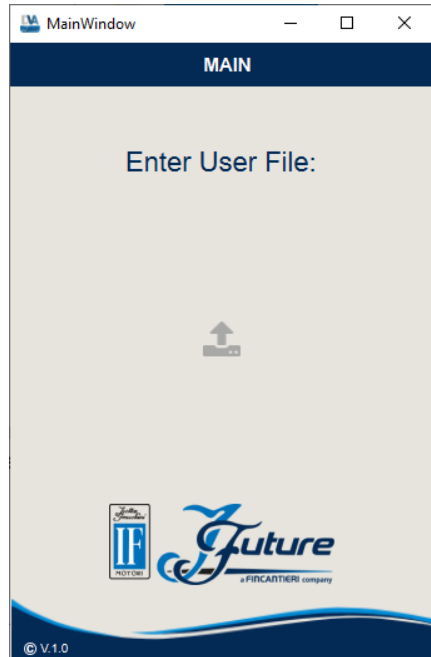
- ↓ HDF5 File dimension: 20% less 🐼
- ↓ HDF5 File opening time: about 2 seconds less

*Data acquired on a real asset (engine on board vessel) and considering some disconnection of the remote source node (PLC unit).

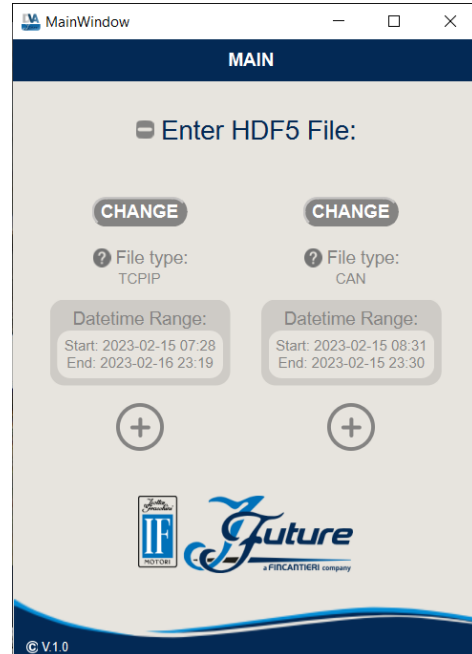
HDF5 VISUALIZATION TOOL

[IFM development]

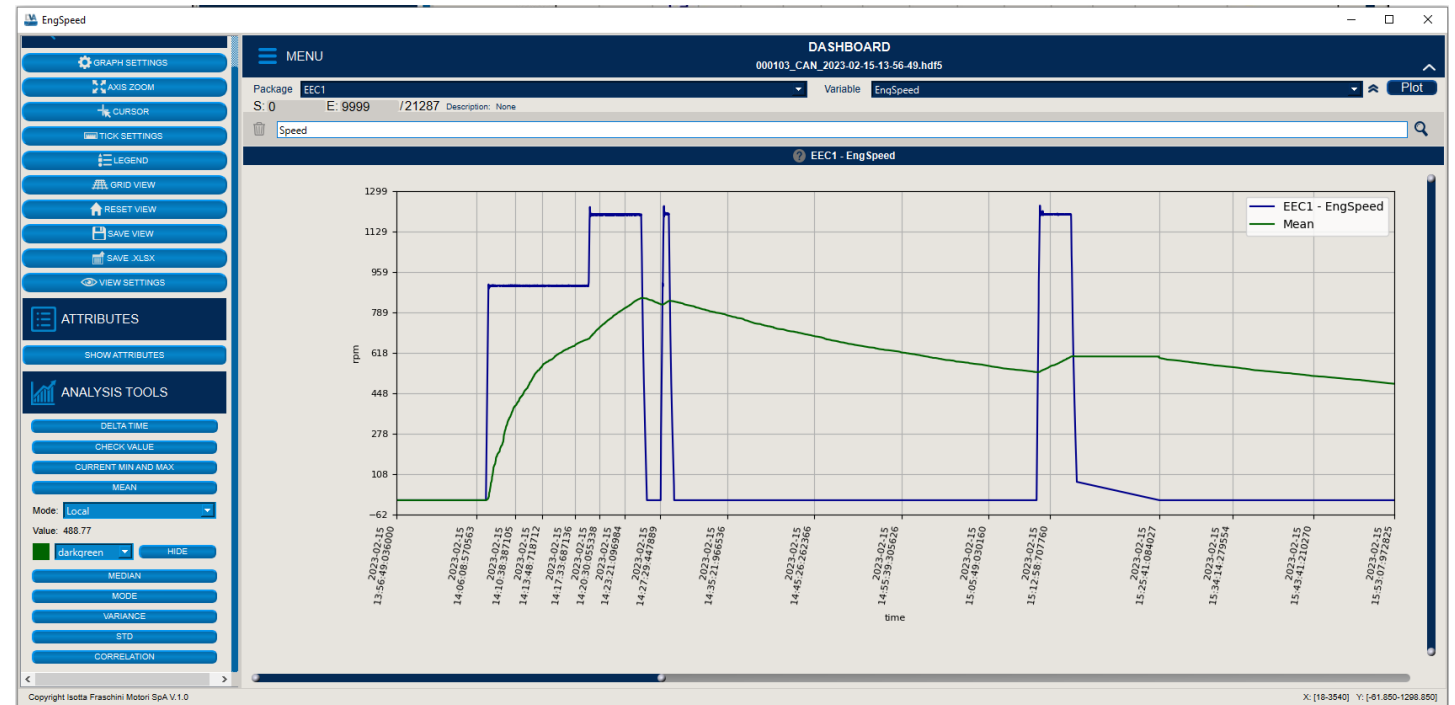
IFM has developed a diagnostic SW tool for Visualization and Analysis of data stored within HDF5 files.



- A single-user file is required to start the SW tool. The user file is crypted and is filled with configuration secure information.



- More than one file can be uploaded simultaneously.
- The SW tool can understand autonomously the communication protocol of the specific HDF5.



- More than one variable per single file can be uploaded simultaneously and compared with other variables of the same HDF5 file or another file.
- The SW tool upload all attributes to make easier the file reading.



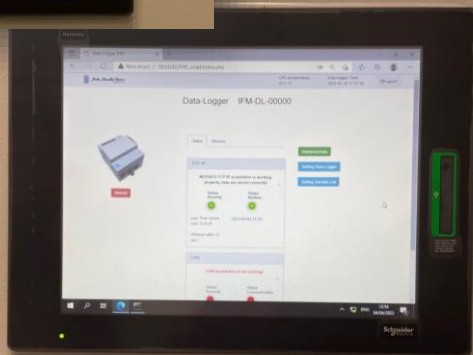
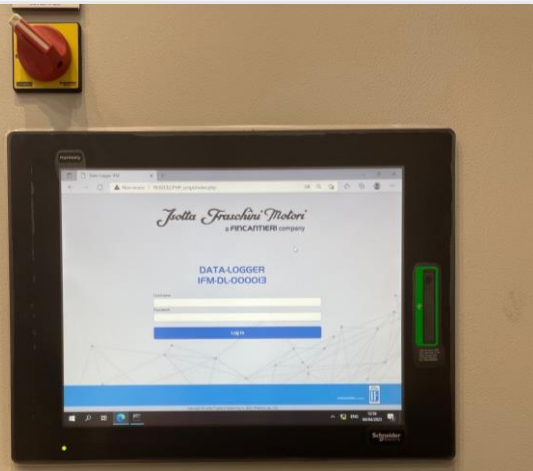
Isotta Fraschini Motori

a FINCANTIERI Company

HDF5 VISUALIZATION TOOL

[IFM development]

A real application of the SW tool based on HDF5 file usage is here reported:



Connection to the local device where HDF5 are stored by means of the HMI.



Running the SW tool for uploading the retrieved HDF5 files.



Start the Visualization and Analysis of the data.



Ifoata Frascchini Motori

a FINCANTIERI Company

CONCLUSIONS AND FUTURE WORK

- We have proposed an approach to **standardize** the storage of data acquired over simple or complex systems where single or multiple communication protocols are involved
- We believe that this approach can help to **democratize** the data usability among different vessel subsystem providers
- The approach could be extended to **other contexts** far from marine engines as automotive and micro-mobility.
- Main **HDF5 advantages**:
 - Capability to organize data in user-friendly architecture (path-to-resource)
 - Data storage optimization
 - Parallel IO
 - Capable to handle multi-dimensional arrays
- **Extended on-field tests** will be executed to evaluate the impact of HDF5 file format on large scale.

Thanks for your time



Isotta Fraschini Motori

a **FINCANTIERI** Company