



Towards the Implementation of Ship Recognition and Identification System in Coastal and River Information Services

Natalia Wawrzyniak & Tomasz Hyla

This scientific research work was supported by National Centre for Research and Development (NCBR) of Poland under grant No. LIDER/17/0098/L 8/16/NCBR/2017) in 2017-2021



Your Presenter:

Natalia Wawrzyniak, PhD

- Lider in SHREC project, Marine Technology Ltd., Poland
- Associate Professor, Maritime University of Szczecin, Poland

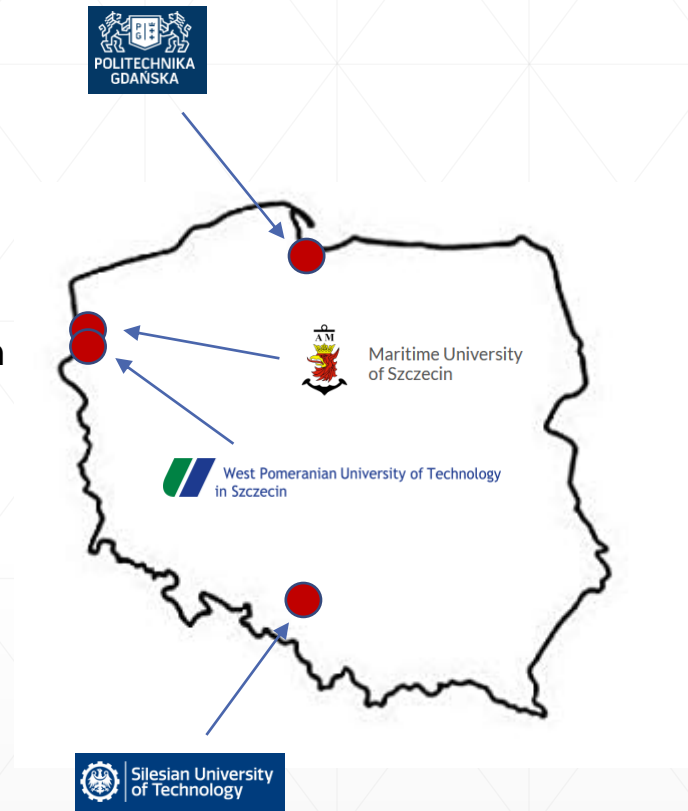
Research interest:

- Applied computer science in inland navigation
- Remote sensing, image processing
- Spatial data processing, GIS solutions
- Underwater imaging, hydrography



SHREC Project

- Project financed by National Centre for Research and Development (NCBR) of Poland from program LIDER
- LIDER is a program for young scientists focused on building and leading interdisciplinary teams of researchers focused on delivering innovative solutions
- Our teams consists of 9 young reserchers from 4 Universities in Poland
 - Maritime University of Szczecin
 - West Pomeranian University of Technology
 - Gdańsk University of Technology
 - Silesian University of Technology
- Hosted by Marine technology Ltd



That's us

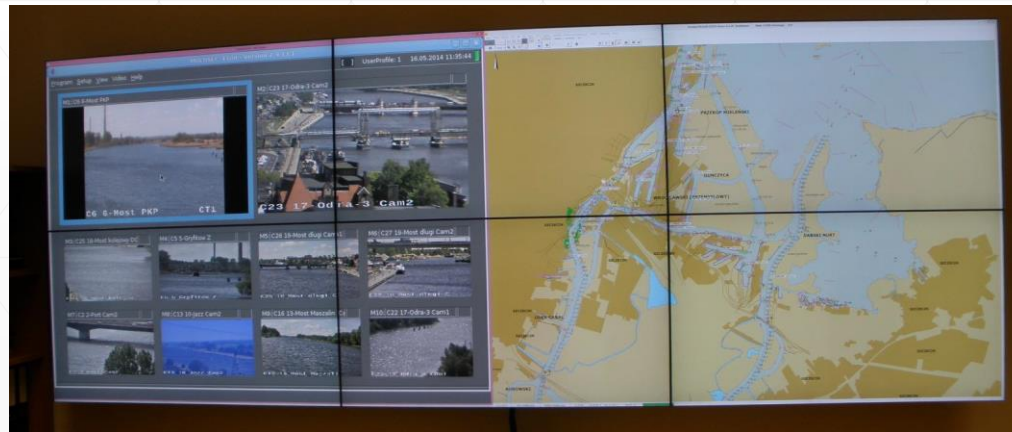


Outline

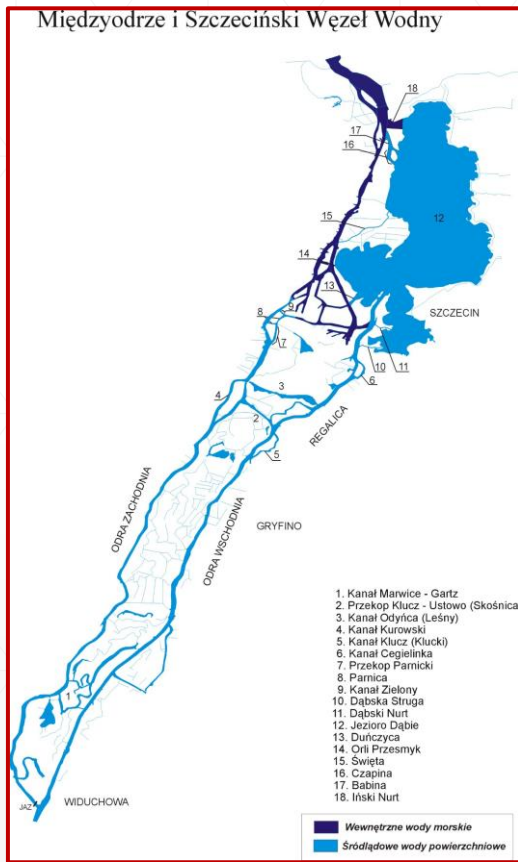
- Motivation and project objectives
- SHREC as a part of River Information Services
- General SHREC system overview
- Conclusion

Motivation

- Ships traffic monitoring is a key issue in limited areas: waterways nodes, ports, busy rivers – main reason: safety of navigation
- Such areas are usually covered by some form of vessel traffic information systems: either VTS or RIS
- Video monitoring is used as an addition to other systems (AIS/Radar) and needs an operator to monitor ships traffic



We are here... where marine and inland waters meet

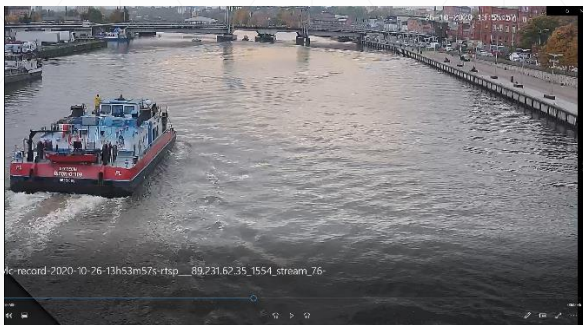


Objectives

- Vessel traffic information services have problems to detect and identify smaller craft on their waters
- Marine, international ships under SOLAS convention have to use AIS transponders, but it's a passive way of identification and ships for a variety of reasons can turn off their transponders or send false messages
- VTS and RIS systems, besides AIS (when possible) and radars (for detection and tracking), use video monitoring as a way to visually identify units.
- Contrary to data in other VTS/RIS subsystems, information on ships identification is not processed in any way, nor passed to other receivers in the system.



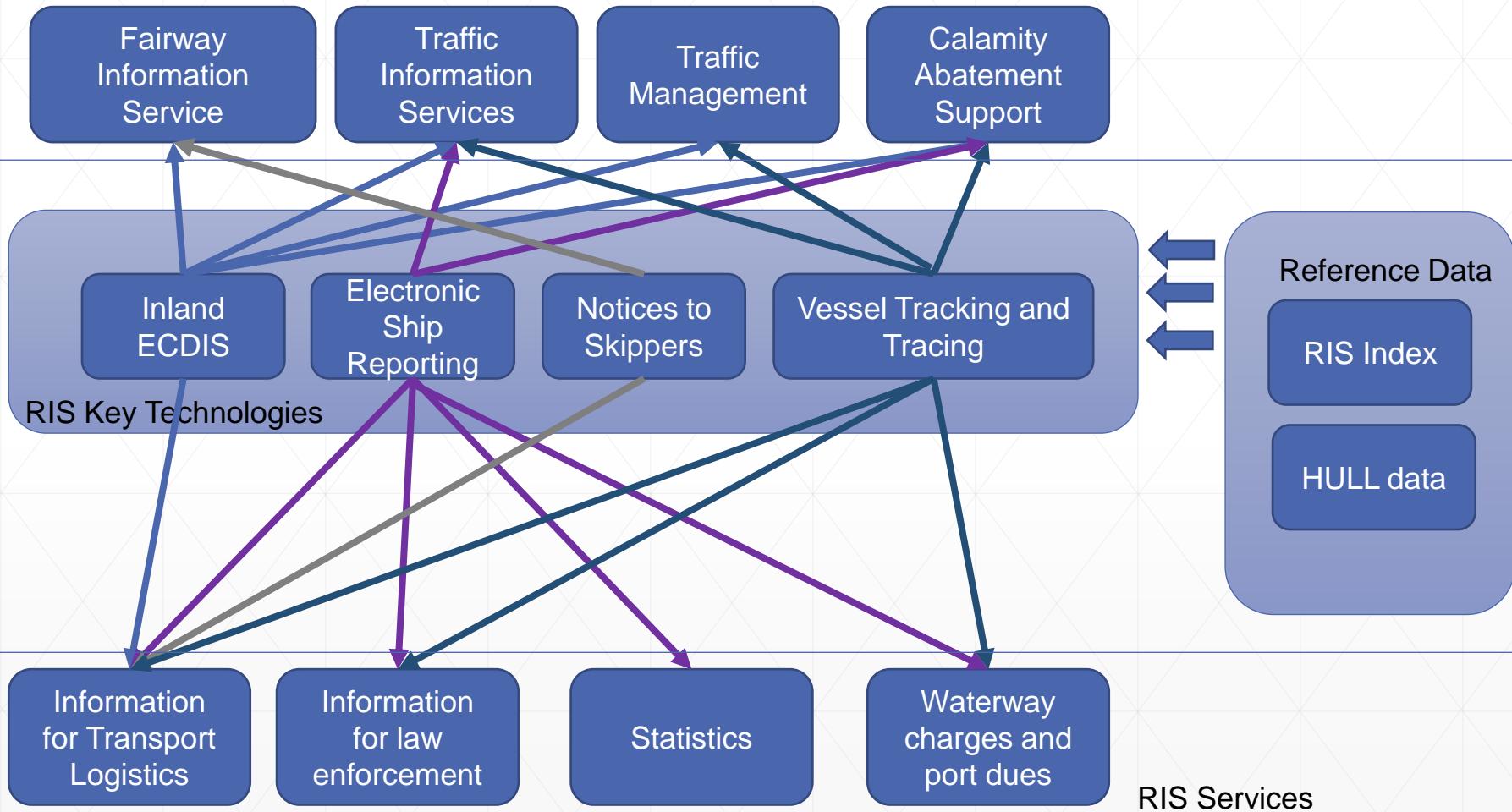
SHREC



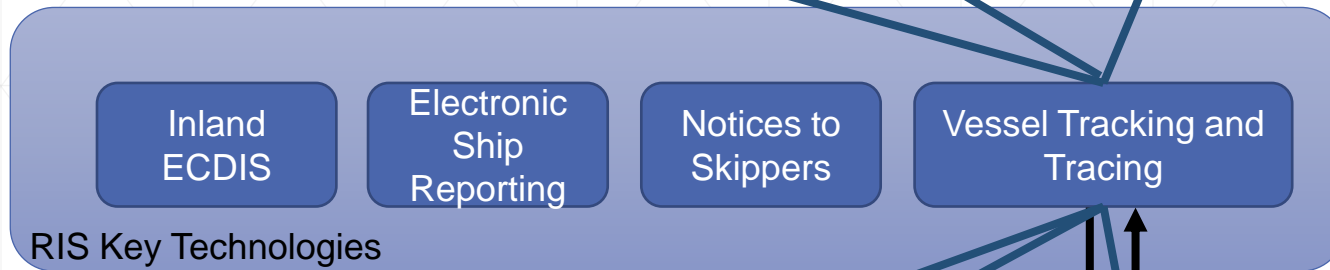
Our approach:

- uses video monitoring of any traffic monitoring systems (RIS/VTs)
- detects, clasifies and identifies ships
- uses AI and analytical techniques of image/video processing
- Modular architecture
- Designed mostly for smaler craft, not regulated under SOLAS convention
- transmit information about the ship to other system services and their recipients

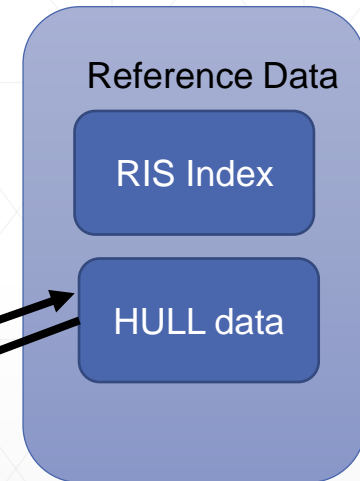
RIS Services



RIS Services



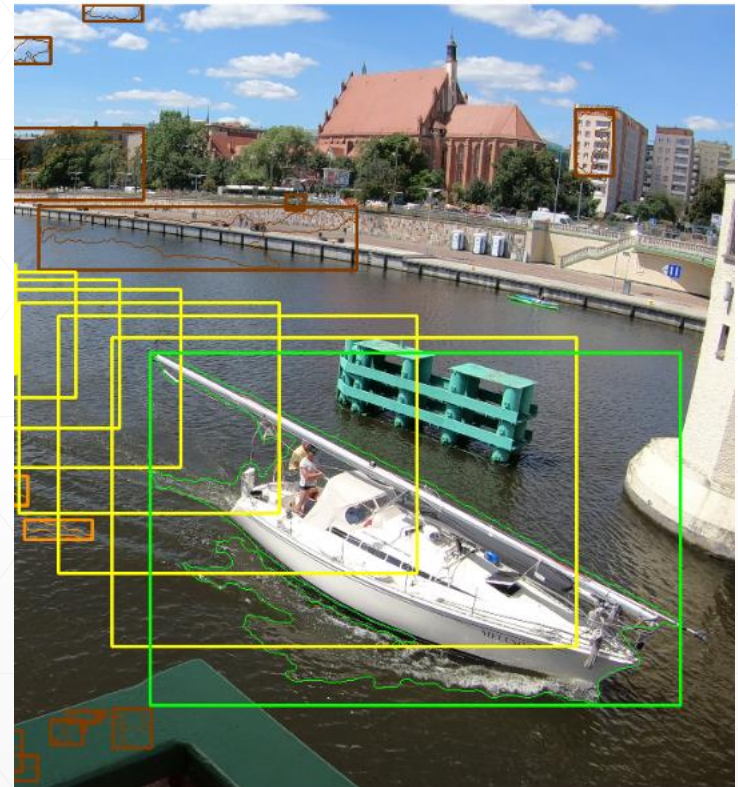
- Uses video monitoring
- Uses ships database for inscriptions matching
- Sends identification/classification results
- Updates ships databases or registeries



RIS Services

Detecting and tracking

- The method is designed to detect all kinds of moving vessels and to work efficiently, so it can be used to process data from multiple cameras (20 or more)
- For each camera view there is a determined detection zone that eliminates areas of the scene where either ships cannot appear (e.g., on land) or they are too far for the detection process to make sense.
- The background subtraction algorithm (GSOC) is used for each frame from a video stream to obtain foreground objects, find their contours, and to obtain bounding boxes for each detected ship



Detection and tracking

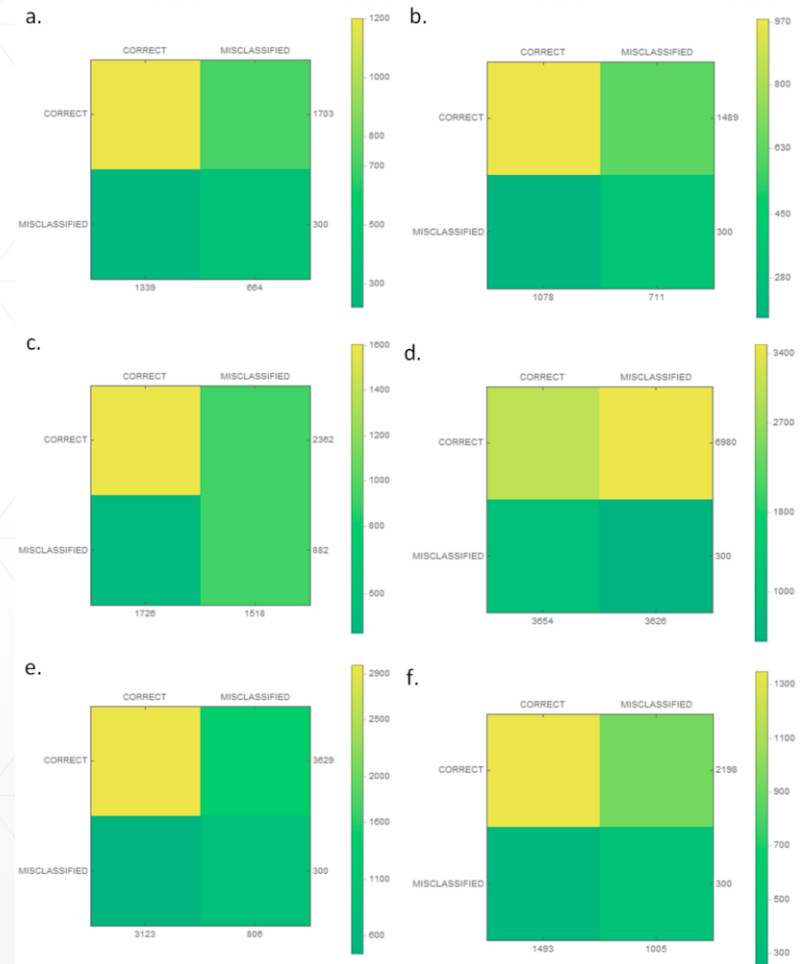
- Works in variable lightning conditions and with slight changes of the background.
- Identifies the same ship across the frames and can filter out artifacts based on a 5-frame window
- Movement direction is detected based on camera location.
- Method returned around 90% of correct detection events for test sets of good quality scenes and around 80% for test sets of streams of bad quality



N. Wawrzyniak, T. Hyla, and A. Popik, A. "Vessel Detection and Tracking Method Based on Video Surveillance". Sensors 2019, 19, 5230, pp 1-14

Ships classification

- The module has two classification algorithms implemented
- First : original CNN developed for the project
- Using only own-gathered data (recorded ships images) on 16 different architectures gave maximum ~20% efficiency during training. Training with the additional older database attached was ~41%. Finally, classification accuracy between 60 and 70% was achieved, but for only 5 classes.



M. Włodarczyk-Sielicka and D. Polap, "Automatic Classification Using Machine Learning for Non-conventional Vessels on Inland Waters", Sensors, 2019, 19(14), 3051., pp 1-17

Ships classification

- The second method was implemented using existing GoogleNet solution trained with thousands of images of non-SOLAS ships acquired during last 3 years the area cover by Lower Oder RIS System
- Many configuration was tested – different number of classes, different training sets, separate CNNs for side and out front vessels views
- It gave a classification accuracy of ~ 84% for 7 classes (barge - together with a pushed kit, motorboat, sailing yacht, kayak, service unit, passenger, and others).

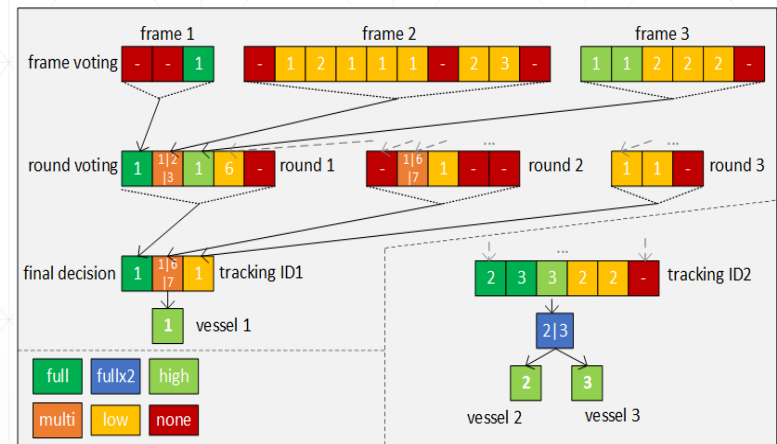
Confusion Matrix

Output Class	barka	inne	jednostka_luzb	kajak	motorowka	pasazerskie	yacht	
barka	115 5.2%	2 0.1%	0 0.0%	3 0.1%	1 0.0%	0 0.0%	0 0.0%	95.0% 5.0%
inne	6 0.3%	195 8.8%	3 0.1%	0 0.0%	17 0.8%	1 0.0%	4 0.2%	86.3% 13.7%
jednostka_luzb	0 0.0%	0 0.0%	231 10.5%	46 2.1%	0 0.0%	0 0.0%	1 0.0%	83.1% 16.9%
kajak	0 0.0%	0 0.0%	1 0.0%	40 1.8%	6 0.3%	0 0.0%	0 0.0%	85.1% 14.9%
motorowka	0 0.0%	0 0.0%	62 2.8%	0 0.0%	789 35.8%	0 0.0%	25 1.1%	90.1% 9.9%
pasazerskie	0 0.0%	0 0.0%	0 0.0%	0 0.0%	5 0.2%	503 22.8%	0 0.0%	99.0% 1.0%
yacht	0 0.0%	0 0.0%	0 0.0%	0 0.0%	50 2.3%	2 0.1%	98 4.4%	65.3% 34.7%
	95.0% 5.0%	99.0% 1.0%	77.8% 22.2%	44.9% 55.1%	90.9% 9.1%	99.4% 0.6%	76.6% 23.4%	89.3% 10.7%
	barka	inne	jednostka_luzb	kajak	motorowka	pasazerskie	yacht	Target Class

K. Bobkowska and I. Bodus-Olkowska, "Potential and use of the GogleNet Ann for the purposes of Inland Water Ship Classification," Polish Maritime Research, vol. 4 (108), vol. 27, pp.170-178, 2020,

Identification

- Vessel identification is based on the location and recognition of the hull inscriptions of the detected ship by the detection module
- Our hybrid approach uses three text localization methods (CCA [5], MSER [6], EAST [7]) and Tesseract OCR to recognize inscriptions
- The module uses its own ship registry (that can be fed from ships data bases from external services) and compares the found inscriptions with its records.
- It runs in near real time, in 5-second-rounds.
- The degree of correct identification is determined depending on the degree of text matching.
- Results of conducted tests : 69% full matches, 25% high matches, 3% low matches, 3% multiple matches (matched simultaneously with more than one ship), and 9% of vessels were not identified.



T. Hyla and N.Wawrzyniak, "Identification of Vessels on Inland Waters Using Low-Quality Video Streams", Proceedings of the 54th Hawaii International Conference on System Sciences, 2021

Identification

- The method works well identifying commercial vessels, as their inscriptions are placed according to the binding rules.
- With the recreational craft situation varies
- When the visible inscription exceeds 10-12 pixels in height, the OCR returns satisfying results.
- Usually, the module analyses 10 to 20 vessels frames per vessel passage in front of the camera,



Summary

- The system is able to recognize and identify all kinds of ships using only video surveillances that are part of many already existing vessel monitoring systems
- In a case when the identification is impossible, it classifies passing vessels into one of determined categories
- The system detects vessels in less than a second with the background model updating 3 times per second during that process
- Pre-identification is performed once per five-second round and the final identification outcome is given after the ships pass (after a round where tracking ID of the passing ship is lost).



The screenshot displays the SH REC software interface, which is divided into several functional areas:

- External system simulator v1.0 based on Detection control:** This panel includes fields for System Core IP address (192.168.1.10) and System Core Port (8888), along with a 'Send Test ECHO' button. It features three modes (Mode 1, Mode 2, Mode 3) for sending frames, each with a 'Send Frames from video file' button and a 'Stop' button.
- Mode 4 - Test stream:** This panel allows for sending frames from a video stream, with fields for Camera Stream Address (http://192.168.1.1:8080/media.ang) and Camera view (From Bridge Center To Down River). It includes a 'Start Stream Preview' button and a 'Start Stream Playback' button.
- System Core v1.2:** This panel contains 'Start', 'Stop', 'Test', 'Export data', and 'Operator console' buttons.
- Settings:** This section includes 'Network Settings' with fields for frame detection, identification results, and classification results output ports, and 'System Core Settings' with fields for identification service addresses.
- Vessel Data:** A small window showing a 3D model of a vessel.
- Vessel Statistics:** A table showing statistics for two cameras, including the number of vessels, total ID, and classification ID.
- Event Stream:** A log of system events with columns for Time, Type, and Message.
- Vessel History:** A detailed table of vessel movements.

Camera	No. of vessels	Total ID	Classification ID
Camera 1	No. of vessels	Identified 888	Classified 777
Camera 2	No. of vessels	Identified 880	Classified 770

Time	Type	Message
2021-01-08 18:3	open - initialization	Detection data received
2021-01-08 17:8	output - decision	Vessel ID was identified
2021-01-08 17:8	input - identification	identification data received

Registration	Name	Date	Location	Type
88478023	Stavros	2019-07-08 18:45:32	Wady Chirango	buha
08702683	Stavros	2019-07-08 18:45:32	Mali Ship	jaris
08702683	Stavros	2019-07-08 18:45:38	Mali Ship	jaris
08702683	Stavros	2019-07-08 17:45:32	Mali Ship	malis pasantini
08702683	Stavros	2019-07-08 17:45:32	Mali Ship	malis pasantini
08702683	Stavros	2019-07-08 18:46:32	Mali Ship	malis pasantini
08702683	Stavros	2019-07-08 18:46:32	Mali Ship	malis pasantini
522-01-22	Stavros	2019-07-08 18:45:54	Mali Ship	jaris
522-01-22	Stavros	2019-07-08 18:45:54	Mali Ship	jaris
522-01-22	Stavros	2019-07-08 18:45:54	Mali Ship	malis pasantini

Summary

- Deployment of proposed solution enables for automatization of operators work in monitoring centres and significantly reduces its cost.
- This system is a smart management system for port and costal traffic services. The approach is in line with current trends for digitization, data sharing, and the development of the information society
- By connecting to other river information technologies (especially vessel tracking and tracing service) it can push information on identified vessels to traffic/transport management services, costal and port charges, customs or law enforcement etc.
- Classification module can be used for statistics purposes.
- Currently talks on implementing SHREC solution are ongoing with Szczecin Inland Navigation Office

Thank you for your attention

- **Towards the Implementation of Ship Recognition and Identification System in Coastal and River Information Services**
- Contact: n.wawrzyniak@marinetechology.pl