



Navi Campus: Quantitative methodology for evaluating the user interface of a navigation app using eye tracker and smartphone

Jesus Zegarra Flores ; Sabine Cornus ; Emma Charbonnier ; Laurence Rasseneur

Presenter : Jesus Zegarra Flores, Capgemini Engineering jesus.zegarraflores@capgemini.com







Professional Experience:

- Research and Innovation Leader at the Capgemini Engineering.
- Research and Development Engineer at the Strasbourg University.
- Research engineer at CNRS in France.

Publications & Activities:

- In charge of research projects in the fields of Mobility, Artificial Intelligence and Internet of Things.
- Lecturer at ECAM (Engineering School) in the field of IoT.
- Catheter Tracking and data fusion for reducing the X-ray exposition in an interventional Radiology procedure (2020).
- Conception of a touchless human machine interaction system for operating rooms using deep learning (2017).
- Navi Campus : an enhanced GPS navigation app for University Campuses,» 12th ITS European Congress (2017).







Navi Campus: navigation mobile app for the Strasbourg Campus

Classic navigation apps (like Google) are not precise enough to locate buildings' entry. These apps are not updated regularly enough to consider civil work on the campus in the itineraries provided to the users. Moreover, the itineraries provided can be inaccessible to people with visual/mobility impairment.



Dijkstra algorithm draw the best path



The user is guided with a map where the person can see his/her current location and

orientation





Quantitative study to evaluate the performances of the app





Qualitative studies





Survey to collect the felling of the users. 5 levels of answers : from unsatisfied to very satisfied

Quantitative studies



Compare AssistOut vs Google Maps

- Time taken to walk to the destination.
- Does the user reached the final destination ?
- Does the user understand he/she reached the destination?
- Does the user need help to find his way after getting lost ?
- Does the user make wrong decisions ?



3 itineraries are defined across the campus, 3 subjects are asked to follow them in the same order, using the Navi Campus app. They are wearing smart glasses with several sensors. The phone used for the app is also collecting motion data.



The 3 itineraries defined across the campus

	Subject A	Subject B	Subject C
Know the campus	NO	YES	YES
Know the application	NO	NO	YES

Summary of the users' knowledge

Phone (T=20ms)

- Accelerometer
- Gyroscope
- Magnetometer
- GPS (T=1s)









Step frequency analysis Phone Steps detection to calculate the walking frequency. **Speed analysis** Accelerometer $speed = \frac{distance}{distance}$ time Use of the app Pairing the head motion and the phone detection in the camera's filed Gaze analysis In some paths, sensors couldn't record gaze data due to high brightness. Therefore, this analysis will not be conducted. no data no dat raw data data data 100 150 200 250 100 150 50 300 50 Time [s] Time [s]

Itinerary 1, Subject A

Itinerary 1, Subject C

6

200

Smart glasses Tobij

- Accelerometer
- Gyroscope
- Camera ٠
- Eye tracker ٠

- Gyroscope
- Magnetometer
- GPS



Segmentation

Automatic segmentation: detection of sharp of the sharp turn turns for each user path with an algorithm

 $\hfill >$ not robust enough to user trajectory variation and GPS noise

Semi-automatic segmentation : turns manually defined and interpolated on user trajectory







Semi-automatic path segmentation





Speed

Hypothesis : If a user who doesn't know the campus is as fast as a user who knows, the app is considered efficient.

User's speed is calculated from GPS positions : $speed = \frac{distance \ between \ consecutive \ GPS \ positions \ [6]}{elapsed \ time}$

As GPS positions can be noised, a filter delete all points with speed higher than 8km/h



Speed of the subject B on the first itinerary, for each segment







Step frequency

Hypothesis : If the user's step frequency is lower than his regular frequency, the user is doubting about the path to follow.



Algorithm to detect the low step frequency zones

To detect the user's steps, the phone's accelerometer is used rather than the glasses' accelerometer. Indeed, the subjects regularly move theirs head to look at the phone or their environment, which disturb the detection.

On the other side, the subjects naturally hold the phone in the horizontal position, which reduce perturbation, but also absorb step shock.





Use of the app

Hypothesis : If a subject looks very often at the app to know where he has to go, that could mean that the navigation information is not clear enough and the user has to look several times to understand which direction to take and what action to do.



Frame of the glasses' camera while not using the phone

Frame of the glasses' camera while using the phone





Use of the app – Head motion

When the user puts his head down (to look at the app) the glasses' gyroscope senses a rotation along the X axis and the glasses' accelerometer senses an acceleration (translation) along the Y and Z axes.





Example head motion detection





Use of the app – Phone detection

To be sure whether or not the user is looking down at the phone, the glasses' camera frames are recovered to detect the phone in the user's field of view. To do so, a mask RCNN in transfer learning mode on COCO [7] is used to classified all objects in each frame. As the outside brightness is high, the phone is often miss detected and classified as other objects. A super class phone is defined, which contains the classes *cell phone*, *tie*, *knife*, *snowboard*, *skateboard*.

Percentage	Class detected					
appearance	Cell phone	Tie	Knife	Snowboard	Skateboard	
Subject A	43,98 %	25,00 %	23,49 %	3,92 %	3,61 %	
Subject B	55,63 %	17,34 %	0,45 %	18,47 %	8,11 %	
Subject C	75,82 %	0,00 %	3,30 %	8,79 %	12,09 %	

Example of phone classified as "knife"







1,8

1,6 1,4

20

15

Quantitative study validation



Mean low step frequency [step/s]

Subject ASubject BSubject CKnow the campusNOYESKnow the applicationNONOYES

Speed analysis :

Average speed around 5km/h => coherent with the average speed of a pedestrian

Step frequency analysis :

Average step frequency very different from a subject to another. A lot of low step frequency zones detected => subjects doubt a lot

\approx

Use of the phone analysis :

Subject B

Subject C

Triple sources (gyroscope, accelerometer, camera) =>robust to perturbations









Evaluation of the performances of the app



- On the 2nd itinerary, the destination announcement appears in front of the entry of another building. Using the frequency step analysis, subjects A and B who do not know the app are walking at lower step frequency. This pop-up introduces doubt for the users.
- The glasses' microphone recorded subjects impressions as they were walking : the Dijkstra algorithm could be improved, one of the users who knows the campus has mentioned that he could have used another path.





- Most of the available data were used to analyse the users' behaviour. Unfortunately
 the eye tracker data were not exploitable.
- The speed analysis and the use of the phone analysis are robust to several users' behaviour. Indeed, despite the GPS noise, the subjects speed is coherent. Moreover, as 3 sources (glasses' gyroscope, glasses' accelerometer and glasses' camera) are use in addition to the use of the phone analysis, this study seems to be robust for perturbation.
- The user who knows the app and the campus was generally the fastest in all the paths.
- More tests are necessary in order to validate our approach.
- This first study has highlighted some development ideas to improve the app.





Quantitative study :

- the step frequency analysis can be improved by coupled it with the user speed to calculate the step length of the subject in order to be more precise. Sensors could also be added to measure the steps' shock in the users knees in order to have two different sources of information
- The phone detection in the camera's field should also be improved to be more robust to outdoor brightness

Experiment :

- A questionary should be submitted to the subjects before the experiment to adapt the analysis to their usual behaviour. For example, if a subject looks often at the app to have information about the path to follow, that's because either the app is not efficient and he has to look several times to understand the information or the user could have problems to focus and to remember the information.
- The experiment should also be done at the end of the day or on cloudy days as the outdoor brightness disturbed the eye tracker and the phone detection. In that way, the eye tracker data can be use to study where on the interface is the user looking for navigation information.





[1] J. Zegarra Flores, F. Pereme, J.-P. Radoux and L. Rasseneur, «Navi Campus : an enhanced GPS navigation app for University Campuses,» 12th ITS European Congress, abstract TP0815, Strasbourg, June 2017a.

[2] R. Fryers, T. Holzer Saad and J. Dinsmore, "Report Defining The Needs of Stakeholders For a Wayfinding Platform For Individuals With Intellectual Disabilities and Their Carers," Trinity College Dublin, Trinity College Dublin, March 2018, pp. 1-29.

[3] A. Arenghi, S. Belometti, F. Brignoli, D. Fogli, F. Gentilin and N. Plebani, «UniBS4All a mobile application for accessible wayfinding and navigation in an urban university campus,» chez In International Conference on Smart Objects and Technologies for Social Good (Goodtechs '18), Bologna, Italy, 2018.

[4] J. Gomez, G. Montoro, J. C. Torrado and A. Plaza, «An Adapted Wayfinding System for Pedestrians with Cognitive Disabilities,» *Mobile Information Systems*, vol. 2015, n° %1Article ID 520572, p. 11, 2015.

[5] AB, «Tobii Pro Glasses 2,» [Online]. Available: https://www.tobiipro.com/product-listing/tobiipro-glasses-2/. [access 2. August 2021].

[6] K. Gade, «A non-singular horizontal position representation,» chez Journal of navigation, 2012, pp. 63(3), 395-417.

[7] T. AB, User's manual Tobii Pro Lab, Version 1.130, 12/2019.

[8] K. He, G. Gkioxari, P. Dollàr and R. B. Girshick, «Mask RCNN,» IEEE International conference on computer vision ICCV, pp. 2980-2988, 2017.