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Optimal and Almost Optimal Strategies for Rational Agents in a Smart Grid

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- *2016-2018*: Software Developer for BMW Group and
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- *2008-2016*: B.Sc and M.Sc. in Computer Science at
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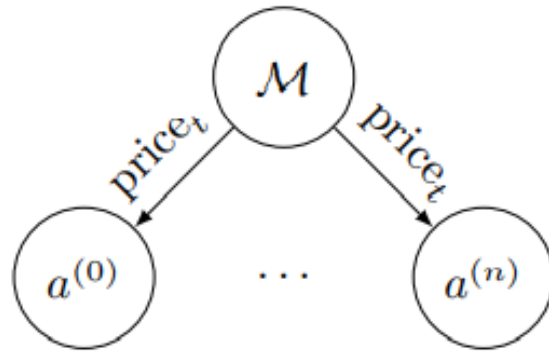
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- Electrical grids are evolving from **centrally managed** critical infrastructure to **distributedly managed** Smart Grids.
- Also the **consumer** within a power grid is evolving to so-called **prosumers**:



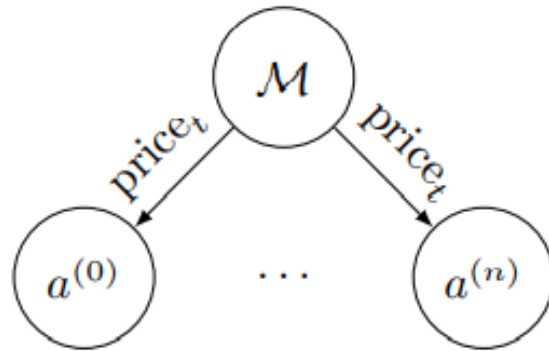
- **Problem:** More uncertainty is added into the power grid.
 ➔ To handle this, the interaction between **independent rational actors** needs to be studied.
- **Approach:** This falls within the domain of **Game Theory** (GT).

- We propose a **game G** to analyze the interactions between **prosumers** and an **electricity market M** .
 - **Prosumers:** set of rational **agents A** .
 - **Electricity Market:** provide price per kWh for **buying** and **selling** electricity.



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- Possible market structures: **Time-Of-Use**, **Demand-Offer** and **Hybrid**.





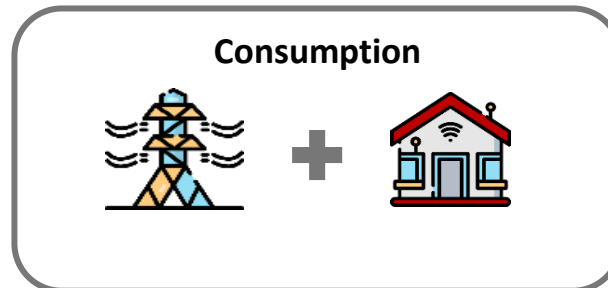
Prosumers as Rational Agents

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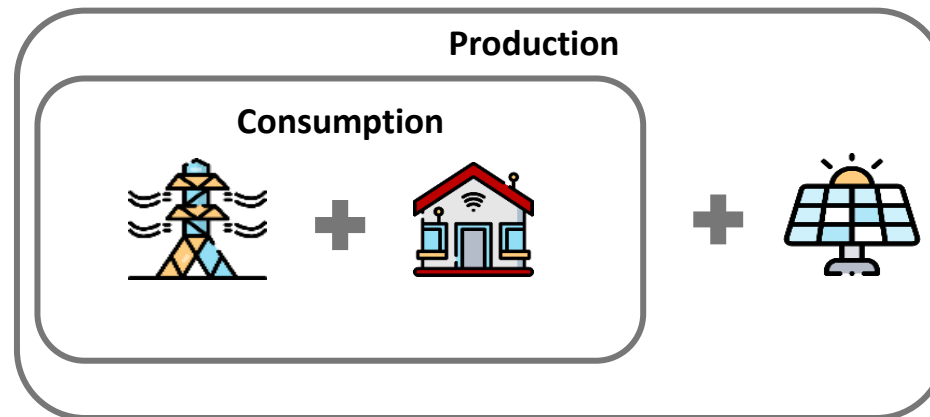


- In our game, prosumers are represented as **rational agents**.
- We categorize the agents based on available **production**, **consumption** and **storage** capacities:

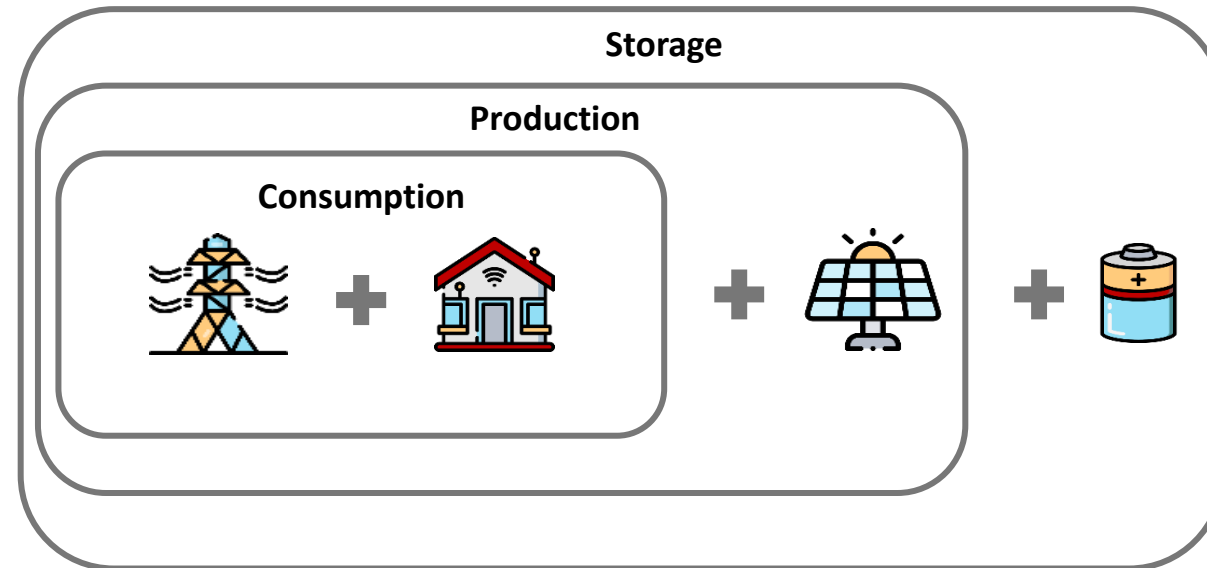
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- In our game, prosumers are represented as **rational agents**.
- We categorize the agents based on available **production**, **consumption** and **storage** capacities:



- Production units can be, e.g., photovoltaic, wind turbine, diesel generator.
- Storage units can be, e.g., batteries or electric vehicles.

- Based on the available **properties**, agents are able to perform different **actions** per time step:

Agent	Property			Action	
	Consumption	Production	Storage	Market	Storage
a_C	√	×	×	√	×
a_{C+}	√	×	√	√	√
a_P	×	√	×	√	×
a_{P+}	×	√	√	√	√
a_S	×	×	√	√	√
a_{CP}	√	√	×	√	×
a_{CP+}	√	√	√	√	√

➔ However, not every action is allowed.

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a_{P+}	×	√	√	√	√
a_S	×	×	√	√	√
a_{CP}	√	√	×	√	×
a_{CP+}	√	√	√	√	√

➔ However, not every action is allowed. **Some constraints need to be defined!**

- At every time step an agents' consumption $\ell_{C,t}^{(a)}$ needs to be covered:

$$\ell_{C,t}^{(a)} = \ell_{P,t}^{(a)} + \ell_{S,t}^{(a)} + \ell_{M,t}^{(a)}$$

Either by production $\ell_{P,t}^{(a)}$, storage $\ell_{S,t}^{(a)}$ or power grid $\ell_{M,t}^{(a)}$.

- Furthermore, the storage and production units have some boundaries:

$$\begin{aligned} -P_{max}^{(a)} &\leq \ell_{P,t}^{(a)} \leq 0 \\ 0 &\leq SOC_t^{(a)} \leq SOC_{max}^{(a)} \\ \ell_{discharge,t}^{(a)} &\leq \ell_{S,t}^{(a)} \leq \ell_{charge,t}^{(a)} \end{aligned}$$

- We **define** power flow to the agent as negativ values, e.g., produced electricity by PV panel.

- Every day an agent choose a **storage control strategy** σ from a given **strategy space** S .
- We define two simple strategies with different behaviour.
 1. **Spillover: Priorities the storage**. Overproduced electricity is used to charge the storage. If storage discharge is available, it is used to cover the household consumption.
 2. **PriceDepending: Priorities the market price**. If the price for buying electricity is below a given threshold, always consume from the power grid. Or feed-in if the selling price is above the threshold.

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- **How can we evaluate the different strategies?**

We define an utility function based on the total amount of money payed or earned c_t by an agent:

$$\pi_{\sigma}^{(a)} = \sum_t^T \ell_{M,t}^{(a)} \times c_t.$$

➔ An rational agent tries to maximize this utility.

- **Nash Equilibrium:** No agent can increase their utility by unilateral strategy change.
- We define the optimal strategies for all agents when the game reaches its Nash Equilibrium.
- To find this equilibrium state, an **iterative approach** is used:

Algorithm 3 Iterative Nash calculation

Input: Agents \mathcal{A} , Strategies \mathcal{S} , Iterations i

```
1: procedure NASH( $\mathcal{A}, \mathcal{S}, i$ )
2:   Initialize Agents  $A$  with random Strategy from  $S$ 
3:   count  $\leftarrow 0$ 
4:   while count  $< i$  do
5:     for all  $a \in A$  do
6:        $P$  empty list of length  $|S|$ 
7:       for all  $\sigma \in S$  do
8:          $\pi(\sigma) \leftarrow \text{CALCULATEPAYOFF}(a, \sigma)$ 
9:          $P \leftarrow P + \pi(\sigma)$   $\triangleright$  Append  $\pi$  and  $\sigma$  to list
10:      end for
11:       $\sigma_{\max} \leftarrow \max(P)$   $\triangleright$  Strategy with max. payoff
12:       $a(\sigma) \leftarrow \sigma_{\max}$   $\triangleright$  Set  $\sigma_{\max}$  as agent's strategy
13:    end for
14:    count  $\leftarrow$  count +1
15:  end while
16: end procedure
```



Price of not knowing the Future

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- Based on the previous determined **optimal strategy**, we calculate the **Price of not knowing the Future**.
- This is the **utility difference** between optimal strategy and another strategy – an almost optimal one.
Other strategy selection methods: *Yesterday's best*, *Steady* (always the same), *No Battery Usage*.

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- This is the **utility difference** between optimal strategy and another strategy – an almost optimal one.
Other strategy selection methods: *Yesterday's best*, *Steady* (always the same), *No Battery Usage*.
- Results of our game with three agents for the different market types over a **whole week MON-SUN**:

Agent	Equipment	Strategy Selection	Market			Price of not knowing the future		
			Demand-Offer	Time-of-Use	Hybrid	Demand-Offer	Time-of-Use	Hybrid
$a^{(0)}$	$C = 290.87 \text{ kW}$	Optimal	-29.45	-30, 49	-28, 28	-	-	-
	$P = -73.17 \text{ kW}$	Yesterday	-29.55	-30, 49	-28.36	0.10	0	0.08
	$P_{\max} = 1.7 \text{ kW}_p$	Steady	-29.54	-30.49	-28.34	0.09	0	0.06
	$\text{SOC}_{\max} = 2 \text{ kW h}$	No Battery	-29.82	-30.86	-28.63	0.37	0.37	0.35
$a^{(1)}$	$C = 151.05 \text{ kW}$	Optimal	-11.19	-11.76	-10.88	-	-	-
	$P = -63.83 \text{ kW}$	Yesterday	-11.43	-11.92	-11.11	0.24	0.16	0.23
	$P_{\max} = 1.36 \text{ kW}_p$	Steady	-11.20	-11.97	-10.90	0.01	0.21	0.02
	$\text{SOC}_{\max} = 2 \text{ kW h}$	No Battery	-12.73	-13.17	-12.25	1.59	1.41	1.37
$a^{(2)}$	$C = 170.74 \text{ kW}$	Optimal	-14.32	-14.44	-13.57	-	-	-
	$P = -68.73 \text{ kW}$	Yesterday	-14.46	-14.44	-13.70	0.14	0	0.23
	$P_{\max} = 1.48 \text{ kW}_p$	Steady	-14.37	-14.44	-13.61	0.05	0	0.04
	$\text{SOC}_{\max} = 2 \text{ kW h}$	No Battery	-15.56	-15.68	-14.80	1.24	1.24	1.23

- A **game of prosumers** represented as **rational agents** is defined.
- These agents are **classified** based on their **properties** that lead to certain **actions**.
- Two basic **strategies** with different utilization goals are given.
- An **optimal strategy** for an agent within this game is determined by calculating the **Nash Equilibrium**.
- Three other strategy selection methods are presented.
The utility difference is defined as the **Price of not knowing the Future**.

- **Future Work:**
 - Further developments and improvements for optimization process.
 - Definition and implementation of broader strategy space.
 - Simulation different game settings with more agents and/or whole real-world grid structures.
 - Long-term analyses in terms of grid stabilization and reliability.

Thank you very much!

