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Detection of Concept Drift in Manufacturing Data with SHAP Values to Improve Error Prediction

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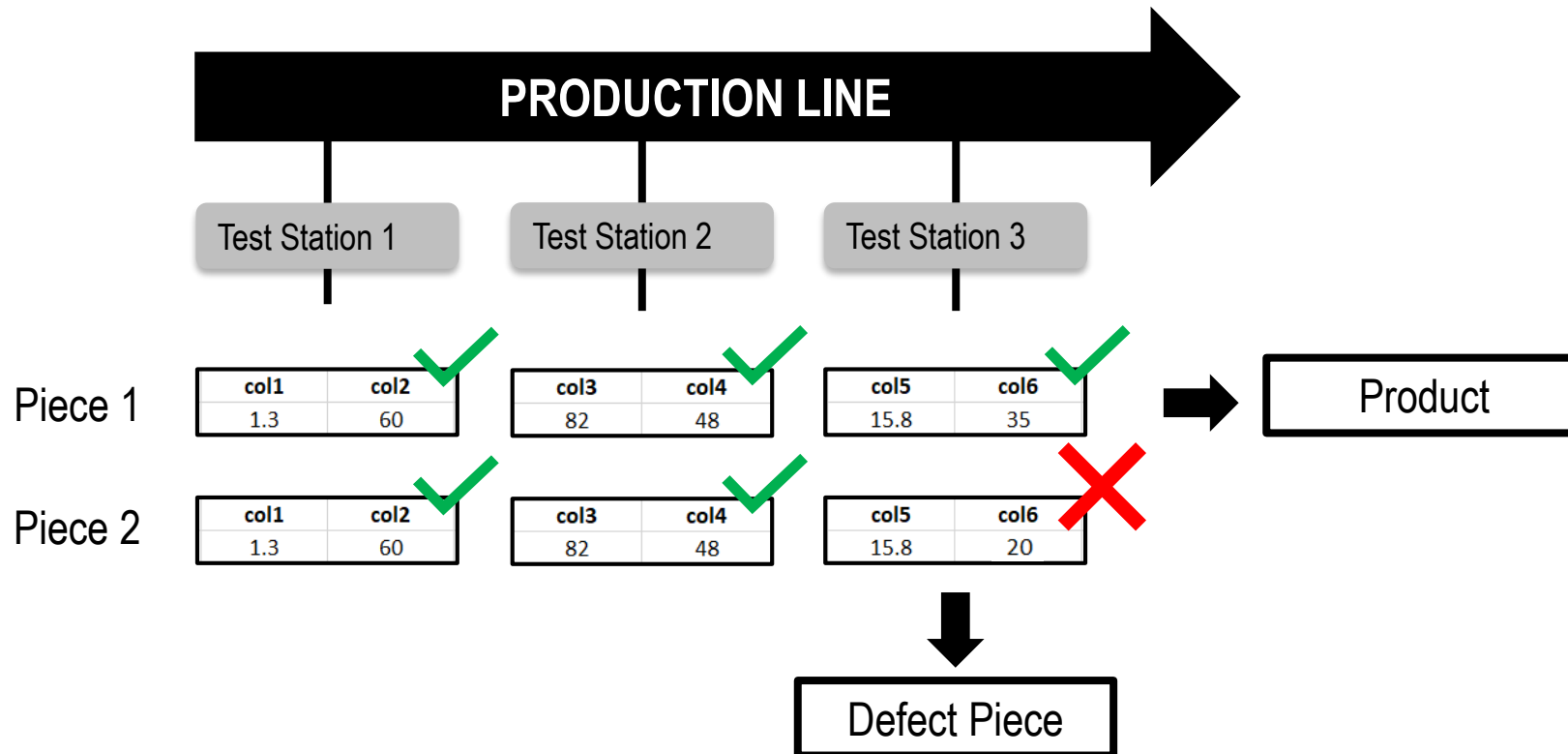


- 2019, Industrial Engineering (M.Sc.) at Karlsruhe Institute of Technology (KIT)
- Working at a research project „PREFERML“ at Furtwangen University since 2020
- Research areas:
Error prediction in manufacturing
Concept Drift in manufacturing

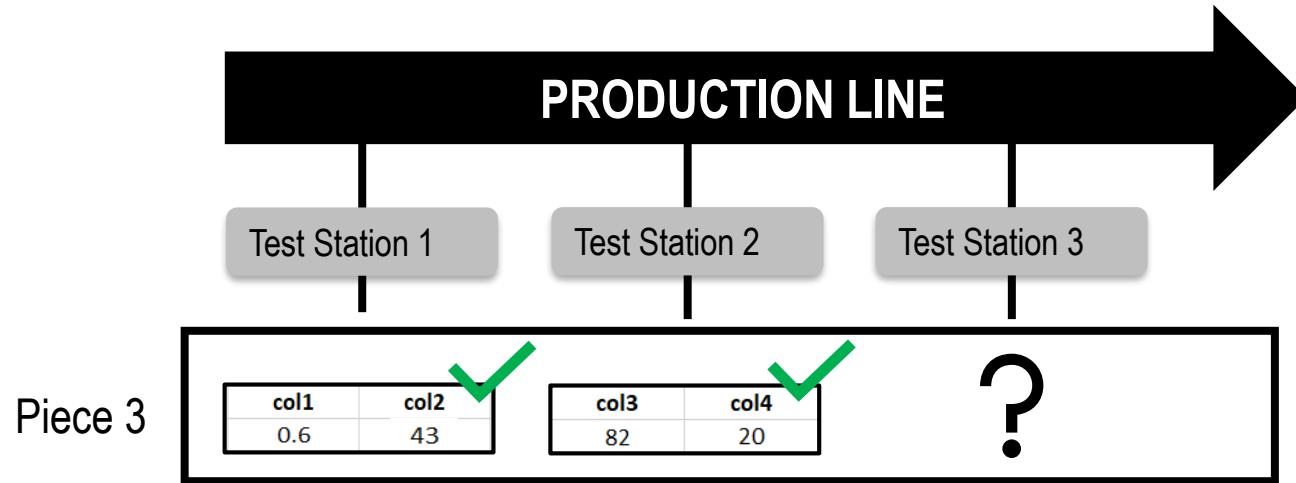
Agenda

- Introduction
- Motivation
- Approach
- Experiments
- Results
- Conclusion

Introduction: Domain



Introduction: Machine Learning in Manufacturing



- True Error Prediction:
Avoids errors at an early stage (save costs)
- False Error Prediction:
Misses profits
- Baseline: No use of ML (i.e., no predictions)

**Machine Learning
Classification Model
(learned on prior data)**

Prediction: ❌
Remove piece at
this early stage

- ➔ Economic savings depend on TP and FP:
$$Total\ savings = TP * c(TP) - FP$$
- ➔ Quality Managers: knowledge/guess of $c(TP)$
- ➔ Evaluation based on precision and critical threshold τ
(corresponding to $Total\ savings = 0$)

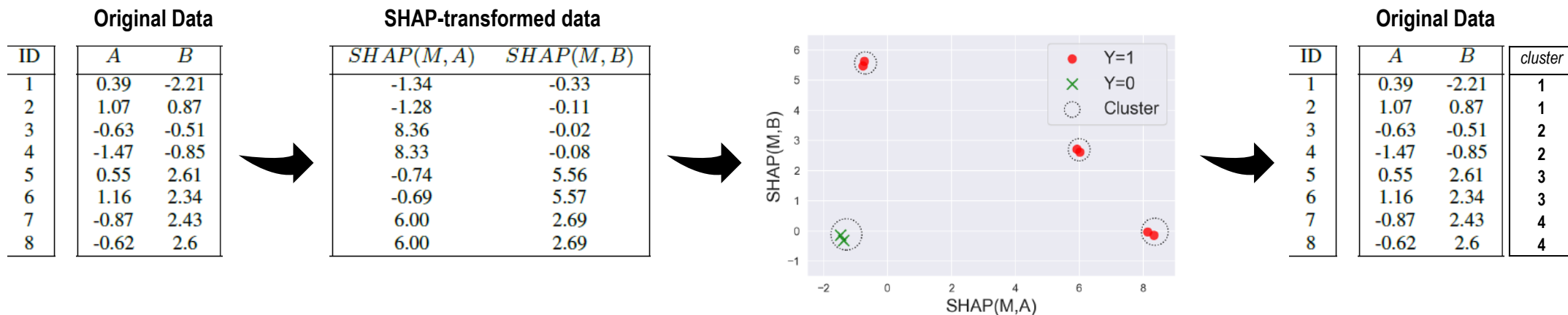
- Usually, several cause-error relationships (*Concepts*) in manufacturing
- Production processes subject to dynamic change (e.g. mechanical properties of tools)
→ Cause-error relationships are not permanent ($P_t(Y|X) \neq P_{t+1}(Y|X)$), known as *Concept Drift*
- Hypothesis: “*Adressing concept drift in manufacturing data by separating underlying concepts yields more insights than an overall analysis.*”

Goal:

- Detect *Concept Drift* efficiently
- Handle *Concept Drift* individually

Approach – Key Idea

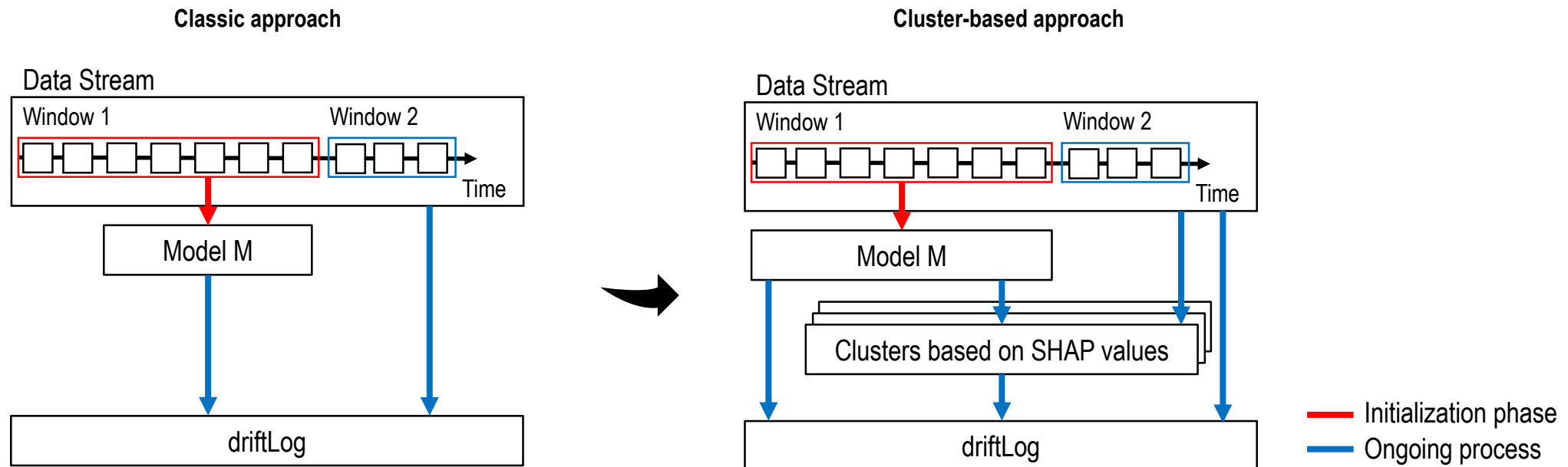
- Cluster data based on corresponding SHAP values¹ – “supervised clustering”
 - SHAP value: contribution of a single feature to model output (predicted value)
 - Clustering: similar instances with regards to how the model computes predictions for them
- ➔ cluster correspond to underlying concepts the model learned



¹ S. M. Lundberg and S.-I. Lee, “A unified approach to interpreting model predictions,” in Advances in Neural Information Processing Systems, I. Guyon et al., Eds., vol. 30. Curran Associates, Inc., 2017.



Approach – Procedure



- Dividing total data into clusters based on their SHAP values
- driftLog: includes relevant information for drift handling

- Different clusters yield separate data streams
- Target variable: sliding window of precision over the last n positive predictions
- Decision to be made based on current precision:
Ignore the next positive prediction or trust it?

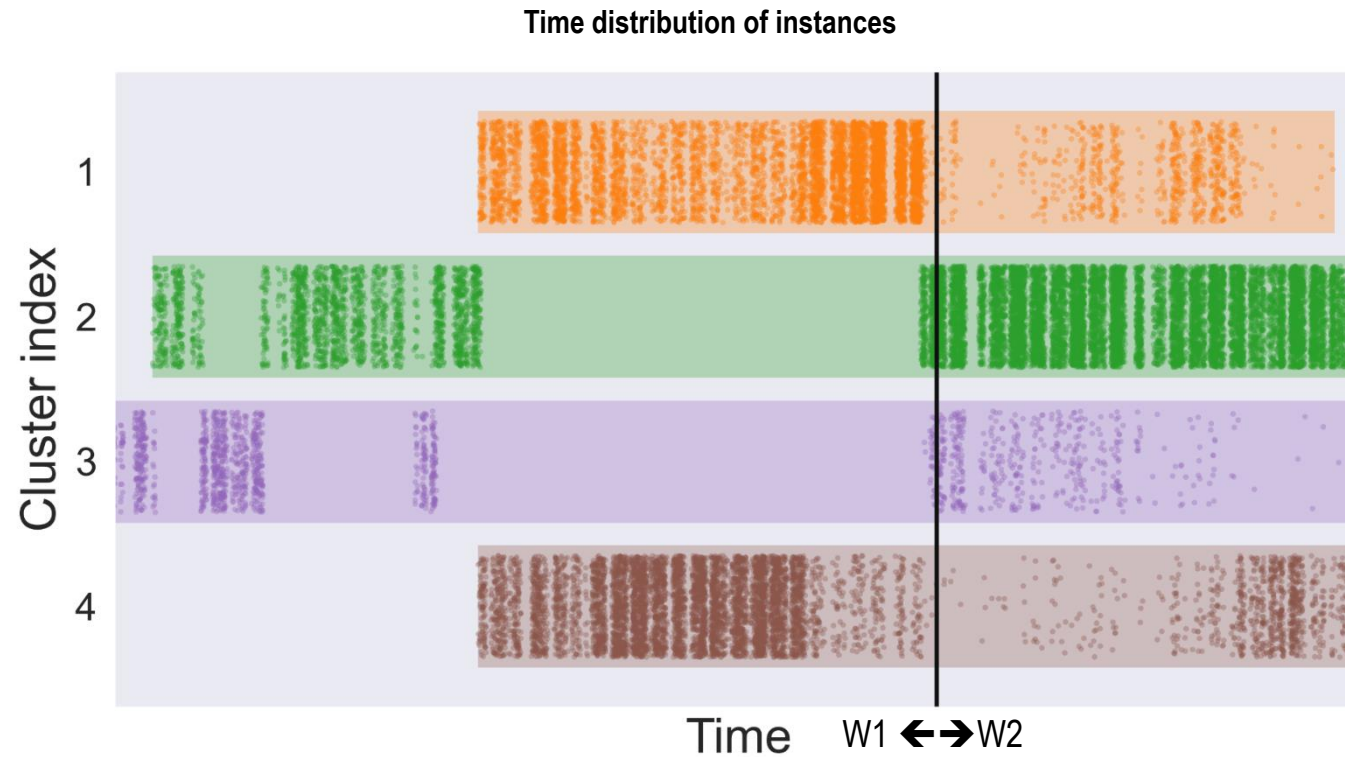
$$precision = \frac{TP}{TP+FP}$$

Two alternative strategies:

- *handle drift based on current precision only:*
if precision < critical threshold τ , the next positive prediction is ignored, otherwise not
- *handle drift based on current precision and established drift detectors (e.g. Page-Hinkley test):*
if precision < τ and drift is detected at the current instance, the following positive predictions are ignored until precision > τ

- Real manufacturing data of our industry partner SICK AG
- Data: six production lines, covering about a year
- Each experiment: any type of error at a specific test station, previous features serve as input
 - ➔ 30 Experiments, conducted retrospectively, simulation under real-time conditions
- Data containing 67% of errors served as train data, other instances part of window W2
- Classifier: Xgboost with tree booster
Clustering: k-means (elbow method)
Drift detector: Page-Hinkley test
- Pretest: suitable parameters (e.g., sliding window size $n=100$).

Results – Use Case



- Heterogeneous distribution
- Periods where no data is assigned to specific cluster
- Only little data of Cluster 1 in W2
- Data of W2 mostly in Cluster 2

Classification results for W2 – basic ML without handling drift

Data	Instances	Errors	TP	FP	TS
Cluster 1	778	16	1	0	10
Cluster 2	11094	301	139	3994	-2604
Cluster 3	479	15	15	463	-313
Cluster 4	993	34	6	0	60
$\sum_{clusters}$	13344	366	161	4457	-2847
Total data	13344	366	161	4457	-2847

- Bad performance in Cluster 2 and Cluster 3
- Cluster 2 affects overall performance due to its size

Handle drift based on current precision only

Data	Instances	Errors	TP	FP	TS
Cluster 1	778	16	1	0	10
Cluster 2	11094	301	22	195	25
Cluster 3	479	15	9	91	-1
Cluster 4	993	34	6	0	60
$\sum_{clusters}$	13344	366	38	286	94
Total Data	13344	366	31	307	3

← Best result

Handle drift based on current precision and drift detector

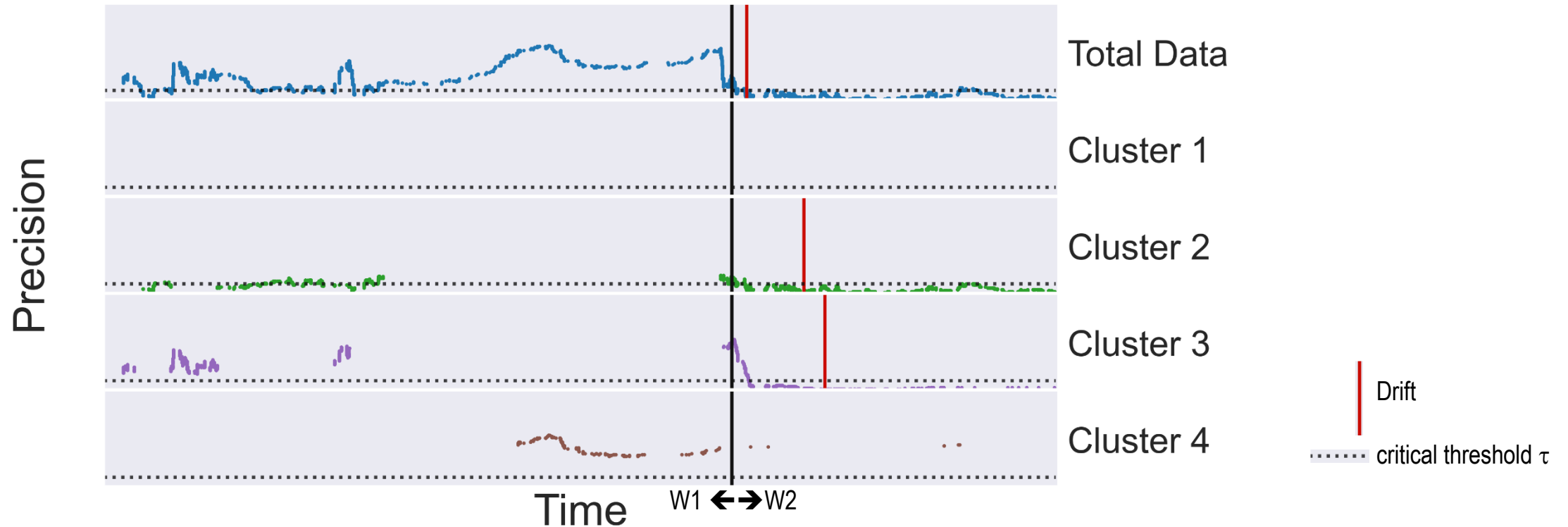
Data	Instances	Errors	TP	FP	TS
Cluster 1	778	16	1	0	10
Cluster 2	11094	301	29	272	18
Cluster 3	479	15	10	99	1
Cluster 4	993	34	6	0	60
$\sum_{clusters}$	13344	366	46	372	89
Total Data	13344	366	47	560	-113

- Performance of Cluster 2 turned into benefit
- Cluster-specific approach outperforms classical approach

- Performance of all clusters turned into benefit
- Cluster-specific approach outperforms classical approach

Results – Use Case

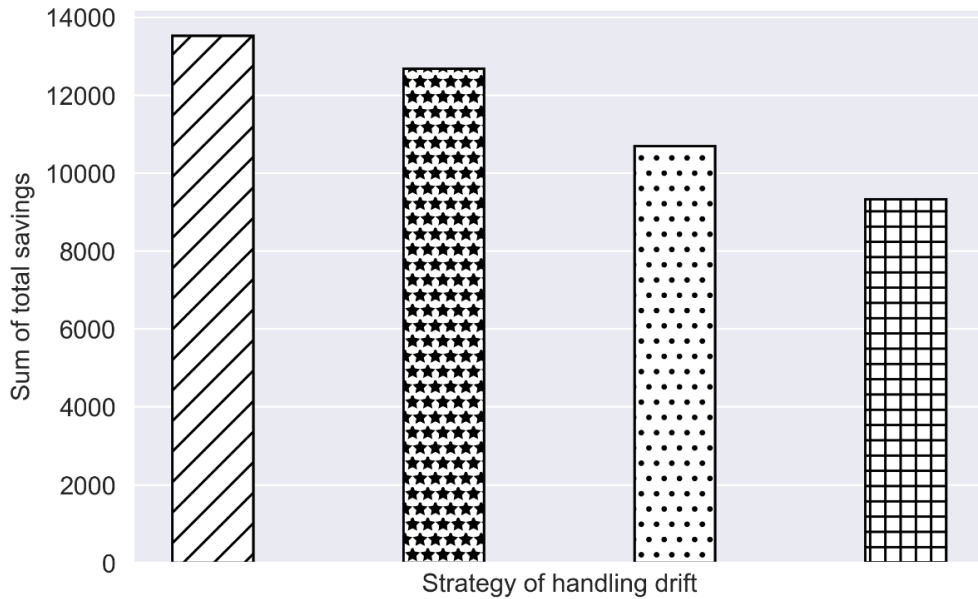
Cluster specific precision within a sliding window (n=100) over positive predictions



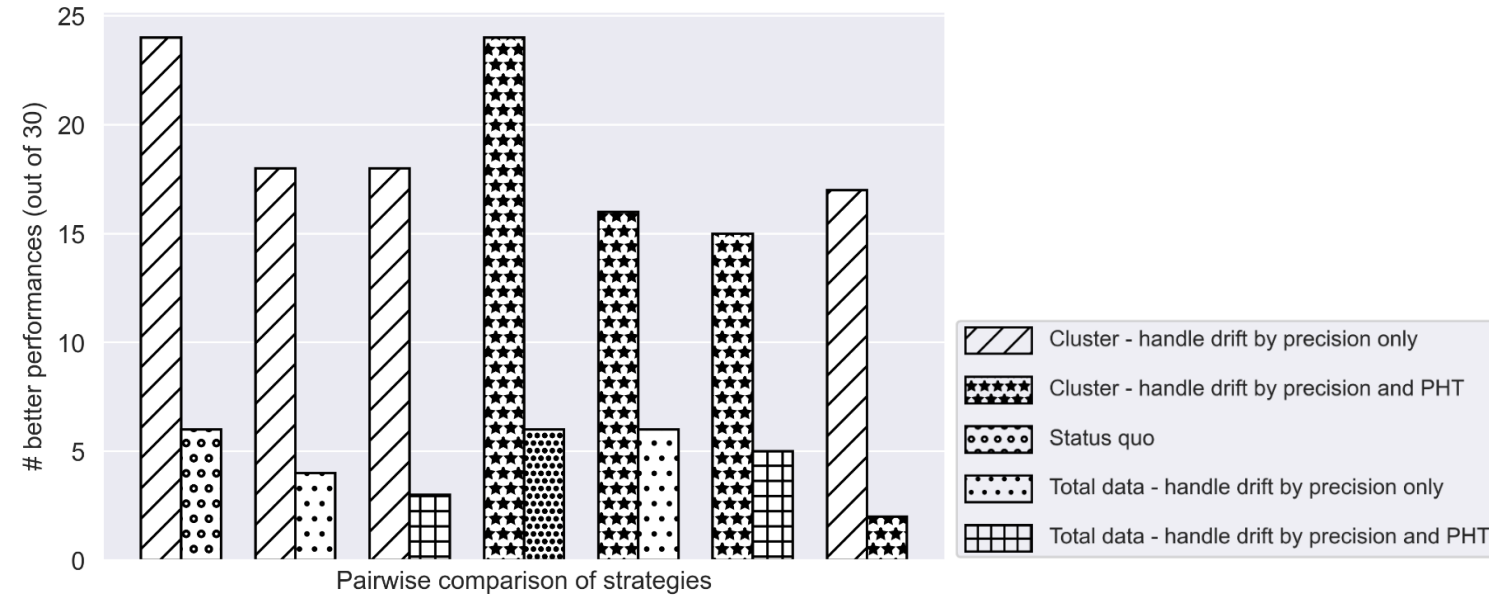
- (Too) little data for Cluster 1, good performance of Cluster 4
- Cluster 3: deterioration at the beginning of W2
- Usually no lasting improvement after deterioration below τ

Results – General View

Sum of total savings over all experiments



Pairwise comparison of strategies to handle drift



- Cluster-specific approach outperforms classical approach
- Handle drift by precision only seems more promising

- Method that uses SHAP values to assign the learned concepts to clusters so that they can be examined individually
- Cluster specific assessment in combination with two strategies for handling drift
- Clustering based assessment outperformed approaches without clustering
(for both strategies of handling drift)