

Unmanned Aerial Vehicles as an Enabler for Next Generation Mobility

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InfoWare 2019, July 4th, 2019, Rome, Italy

About QMIC





Qatar Mobility Innovations Center (QMIC)



Road Safety a Worldwide Problem



Source: WHO this year - 2013

And Old Problem...

Considerable Improvements



Motor vehicle crash deaths in 10 comparison high-income countries, 2013 **United States** 0.3 HIGHEST New Zealand 56 Canada 5.1 France 4.5 Japan Germany 3.6 Spain Switzerland 3.3 United Kingdom 2.8 Sweden

Deaths per 100,000 people SOURCE: WHO Global Status Report on Road Safety, 2015.



SOURCE: International Road Traffic and Accident Database (IRTAD) Road Safety Annual Report, 2015.



Roads Are Safer Than They've Ever Been



Go To Next Level...



APROX

of all crashes are due to minor mistakes such as distraction, fatigue or being slightly above the speed limit

Source: www.carrsq.qut.edu.au





Automated Driving to Eliminate Human Error!

Accidents

Cut Road

by 90%

McKinsey & Co.



CITIES ARE **DESIGNED FOR CARS**

30-35% Land used for streets



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Source: https://nextcity.org/daily/entry/how-much-public-space-does-a-city-need-UN-Habitat-joan-clos-50-percent



Parked



of the time

WASTED SPACE & MONEY

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Ausgang Rathaus/. Münsterpla times as many parking spaces as cars in America.

There are

of our downtown 🕶 commercial 📲 cores are devoted to parking.



Source: http://www.motherjones.com/environment/2016/01/future-parking-self-driving-cars

WASTED SPACE & MONEY



PAST

FUTURE

DIFFERENT EXPECTATIONS



THERE IS ONE trend of mobility that young people have embraced, though:

MOBILITY AS A SERVICE





Car Pooling

Milton Keynes Arena

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Fleet of Taxi **ROBOTS**





Automation is the Next Provide of Transportation

gmic

Levels of Automation



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What about road maintenance?





What about road assistance?





What about road surveillance?



What about road assistance?





Drone-aided Platform for Enabling **Next Generation ITS**

NPRP9-257-1-056 | www.DroneITS.com



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UAVs Applications ... A Reality!





Special Issue Magazine



ENABLING MOBILE AND WIRELESS TECHNOLOGIES FOR SMART CITIES

UAV-Enabled Intelligent Transportation Systems for the Smart City: Applications and Challenges

Hamid Menouar, Ismail Güvenc, Kemal Akkaya, A. Selcuk Uluagac, Abdullah Kadri, and Adem Tuncer

Due to their mobility, autonomous operation, and communication/ processing capabilities, UAVs are envisaged in many ITS application domains. The authors describe the possible ITS applications that can use

Abstract

There could be no smart city without a reliable and efficient transportation system. This necessity makes the ITS a key component of any smart city concept. While legacy ITS technologies are deployed worldwide in smart cities, enabling the next generation of ITS relies on effective integration of connected and autonomous vehicles, the two technologies that are under wide field testing in many cities around the world. Even though com/b?node=8037720011). Similarly, DHL of Germany and China's largest mailing company have started their experiments with a fleet of UAVs that could deliver around 500 parcels every day. Use of UAVs for daily consumer-oriented services is expanding and becoming a reality.

Automation of the overall transportation system cannot be achieved through only automating the vehicles. Indeed, other components of the road and the end-to-end transportation system, such as the field support team, traffic police, road

Hamid Menouar, Ismail Guven, Kemal Akkaya, A. Selcuk Uluagac, Abdullah Kadri, Adem Tuncer, "<u>UAV-Enabled Intelligent</u> <u>Transportation Systems for the Smart City: Applications and Challenges</u>", <u>IEEE Communication Magazine</u> – Special Issue "Enabling Mobile and Wireless Technologies for Smart Cities, March 2017.

Placement of the UAV Docking Stations



Hakim Ghazzai, Hamid Menouar, Abdullah Kadri, "<u>On the Placement of UAV Docking Stations for Future</u> <u>Intelligent Transportation Systems</u>", <u>the 2017 IEEE 85th Vehicular Technology Conference (VTC)</u>, 4–7 June 2017 in Sydney, Australia.

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UAV Missions Scheduling





Hakim Ghazzai, Hamid Menouar, Abdullah Kadri, Yehia Massoud, "<u>Future UAV-based ITS: A Comprehensive</u> <u>Scheduling Framework</u>", to appear in IEEE Access. June 2019, pages 1-18, Print ISSN: 2169-3536, Online ISSN: 2169-3536, DOI: 10.1109/ACCESS.2019.2921269.

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Flying IoT Gateway





Video link: <u>https://www.youtube.</u> <u>com/watch?v=jmxxL9</u> <u>Gzo-M</u>

Hamidullah Binol, Eyuphan Bulut, Kemal Akkaya, Ismail Guvenc, "<u>Time Optimal Multi-UAV Path Planning for</u>
<u>Gathering ITS Data from Roadside Units</u>", In Proc of 2018 IEEE 88th Vehicular Technology Conference: VTC2018 Full, 27–30 August 2018, Chicago, USA.
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Qatar V2X Pilot - Architecture





Qatar V2X Pilot - Architecture







Unmanned Areal Vehicles (UAVs) Drones for ITS

Flaying V2X Road-Side Unit





Video link: <u>https://www.youtube.</u> <u>com/watch?v=eJ_JUj</u> <u>mgLOQ</u>

Nico Saputro, Kemal Akkaya, Ramazan Algin, and Selcuk Uluagac, "<u>Drone-assisted Multi-purpose Roadside Units for Intelligent</u> <u>Transportation Systems</u>", In Proc of 2018 IEEE 88th Vehicular Technology Conference: VTC2018-Full, 27–30 August 2018, Chicago, USA.

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3D Space Navigation





3D Space Navigation





Xiangpeng Wan, Hakim Ghazzai, Yehia Massoud, Hamid Menouar, "**Optimal Collision-free Navigation for Multi-Rotor UAV Swarms in Urban Areas**", In Proc of 2019 IEEE 89th Vehicular Technology Conference: VTC2019-Spring, 28 April – 1 May 2019, Kuala Lumpur, Malaysia.

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UAVs Applications ... A Reality!









16 km max

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amazon PrimeAir

amazon PrimeAir

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What if we let the UAV ride the bus?



Noureddine Lasla, Hakim Ghazzai, Hamid Menouar, Yehia Massoud, "**Exploiting Land Transport to Improve the UAV's Performances for Longer Mission Coverage in Smart Cities**", In Proc of 2019 IEEE 89th Vehicular Technology Conference: VTC2019-Spring, 28 April – 1 May 2019, Kuala Lumpur, Malaysia.

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Exploiting the Existing Land Transport! **QMIC**



Others already doing it...





Automated Landing





Video link: <u>https://www.youtube.</u> <u>com/watch?v=iUO39s</u> <u>-Zj08</u>









Thank You!

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