Automatic generation method for geographically accurate bus route maps from bus stops

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YAMAMOTO LABORATORY

Resume of the presenter



• Sogo Mizutani

– Career

>April 2017 : Entered Nagoya Institute of Technology

- >April 2020 : Assigned to Yamamoto Laboratory
- >April 2020 : Entered graduate school at Nagoya Institute of Technology
- Research
 - Research is being conducted on the automatic generation of route maps.

Background (1/2)

- Dissemination of web map services
 - Such as Google Maps, OpenStreetMap.
 - Possible to draw a route map superimposed on it.



Dissemination of 「General Transit Feed Specification (GTFS) standard」

- Unified format for subways and local buses.
- Data of timetable, coordinates of bus stops and connection relationships between routes.
- Promoting the use of public transportation data and its multifaceted application.

• Automatic generation of bus route maps

- Fewer studies on automatic generation of geographically accurate route maps compared to deformed route maps.
- Geographically accurate route maps are drawn by hand, taking into account the order of placement that does not cause extra crossings.
- A lot of time and effort is required to redraw every time a line is changed or discontinued.



deformed route map



geographically accurate route map

Purpose

- Estimates route routing from stop coordinates and system data included in the GTFS.
- Automatic generation of highly visible and geographically accurate bus route maps from estimation results.

lssue

- Route estimation requires linking stops to the road network.
 - Latitude and longitude coordinates of bus stops in the GTFS indicate boarding and alighting points, whereas the road network consists of intersections and roads.
- To improve the visibility of the route map, it is necessary to find the order of routes that minimizes intersections between routes.
 - It is time consuming to do a brute force calculation for each road link.

Route generation function

- Automatically estimates bus routes from the road network and the latitude and longitude coordinates of bus stops, then generates route data for bus routes.
- At this time, routes are generated by avoiding expressways and other roads due to the characteristics of bus routes.

• Bus stroke / Bus stroke fragment generation function

- Generate bus strokes that summarize the bus route in stroke (along the way) units.
- Generate bus stroke fragments with multiple route overlap section information added to the bus stroke.

• Route placement function / Drawing function

- Dynamically determine the order of placement of overlapping sections from bus stroke fragments to reduce the number of intersections between routes.
- Shift overlapping sections based on the obtained placement order and draw them on the web map.



• Estimates bus routes from the coordinate series of bus stops

- Generate a bus stop node at the point on the road closest to the coordinates of the bus stop.

>At this time, the type of road should be other than an expressway or a connecting road to an expressway.

• Route estimation is performed between bus stop nodes by

way-first search based on stop order data.



- The stroke is a set of road networks grouped according to cognitive psychology.
 - The stroke consists of a list of road links.



Bus Stroke (BS) · Bus Stroke Fragment (BSF) generation function

Bus Stroke (BS)

- BS indicates the section of a stroke that a route passes through on a single route.
- \Rightarrow By using strokes, fewer bus routes can be represented than by using link series.

Bus Stroke Fragment (BSF)

- BSF indicates a section of a stroke that contains information on the overlap of multiple routes.
- The BSF is generated by splitting the BS between overlapping and non-overlapping segments.
- \Rightarrow Minimize the number of combinations when determining the placement order.





• Two rules are applied to determine the placement order.

- 1. The placement order is determined based on the angle with the previous BSF.
- 2. If the angle is the same as that of one previous BSF, go back to a BSF with a different angle.

• Leaflet are used for drawing functions.

- The BSF is shifted using Leaflet Polyline Offset based on the obtained placement order, and the route map is drawn.



東越町 愛知町

松葉町在屋街道

辻畑町 南脇町

押元町

宫脑町

小本本町

松ノ木町

上流町

(陈语

良町

TRACE

名古國一宮國

万町

2

C. Barris

的場町

中

20.42

五月南通

四女子町

德原橋通

三ツ屋町

丸米町

中京南通

富船町

上脇町 清川町

中川運河

舟戸町

横堀町

石場町

八熊通

法履伤了

荒江日

गटाका

NO BT

広川町 前並町

八幡本通

八神町

成仁町

丹後町

- 本宗

二女子町

山王道

尾頭

南方

千代田町

比々對

中出町

|並可

F-#2/11

▶ 古渡町

全山

A REA

花町

五本松町

~ 夜寒町

富士見町

大井町

支寄町 桜田町

十届日

尺下町 港内町 高辻町

须田町



東部山橋町線

村雲町

円上町 滝子町

太田町

雁道町

平細町

魚城町

阿由知通

広池町

桜見

駒場町

高田町

北原町

川澄町

東栄町

昭和区

初日日

大殿町

五軒家

汐見町

五軒家町 隼人町 4

南山

春山町

彌富町

南山町

山香町

高針荒田

59

一座町

萩岡町

八事富士見 天白町大字。

事業面

八幡山

意识的意义

事山

音開

串

八雲町

八事本町

八事天道

亲圈町

川名山町

滝川町

広路町

BIDA

自町大字植

名古原西道2号東山

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Purpose

- Verify the accuracy of route estimation using stop coordinates and road networks.

Method

- Verify the estimation accuracy of the proposed method
- Comparison of 40 Nagoya City bus routes using Nagoya City Transportation Bureau Open Data.

• Evaluation measure

- Agreement between actual route map and generated routes.

$$M = \frac{Number of muched routes}{Number of actual routes} \times 100$$

Results

• Estimation accuracy

- Estimation accuracy of the proposed method : 93.2%



Proposed method



Actual routes

• Summary

- Estimates route routing from stop coordinates and system data included in the GTFS.
- Drawing a bus route map with road strokes to account for intersections of multiple routes.
- Verified the accuracy of route estimation with the proposed method.

Future Issues

- To improve the visibility of route maps in drawing multiple routes.
- To enhance drawing of bus terminals and sections where many lines overlap.
- Acceleration algorithm for drawing all lines.