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SMALL SCALE UNMANNED AIRCRAFT SYSTEM AND PHOTOGRAMMETRY APPLIED FOR 3D MODELING OF HISTORICAL BUILDINGS



Alexandre Boente. Graduated in flight mechanics by the Brazilian Air Force, member of the Brazilian Army teaching staff, He is a Teacher of Colégio Militar do Rio de Janeiro, Master's student in the Defense Engineering Program at the Military Institute of Engineering.

Thiago Baldivieso, DSc Student in the Defense Engineering Program at the Military Institute of Engineering.

Vinicius Prado da Fonseca (S`15-M`20) obtained his Ph.D. degree in electrical and computer engineering with the School of Electrical Engineering and Computer Science, University of Ottawa, Canada, and his M.Sc. degree from the Military Institute of Engineering, Rio de Janeiro, Brazil. He is currently an assistant professor in the Department of Computer Science at the Memorial University of Newfoundland. His research interests include robotic manipulation, artificial intelligence, fuzzy control, neural networks, smart homes and sensor networks.

Thiago Eustaquio Alves de Oliveira (S`15-M`17) obtained his Ph.D. degree in electrical engineering from the School of Electrical Engineering and Computer Science, University of Ottawa, Canada, and his M.Sc. degree from the Military Institute of Engineering, Rio de Janeiro, Brazil. He is currently an assistant professor in the Department of Computer Science at Lakehead University. His research interests include computational intelligence, biologically inspired computational models and sensors, and tactile and vision sensing. He also serves as Technical Committee Member for international conferences, as conference organizer and as a reviewer for several Journals and

Transactions. Dr. Alves de Oliveira is a Member of the IEEE Computer Society Technical Community on Haptics.

Paulo F. F. Rosa, has a PhD on Information Engineering (Niigata Univ - Japan), a M.Eng. in Computer Science and Systems Engineering (Kyushu Inst of Technology - Japan), and an Electronic Engineer degree (UFPE, Brazil). His main research interests is autonomous mobile robots. He is a Professor at Instituto Militar de Engenharia, in Rio de Janeiro.

• This paper presents a methodology for the 3D reconstruction of largescale cultural assets, such as buildings using photogrammetry.

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Figure 1. "Palacete da Babilônia" Mavic Air2 aerial photo

Camera Parameters

Image Width	3968	рх
Image Height	4000	рх
Sensor Width	6.3	mm
Sensor Height	4.7	mm
Focal Length	4.49	mm

Flight hight: 45 m GSD: 1.59cm/px

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Spark -DJI

data collec ©amera H	Parameters	
ata processing Image Width	4000	рх
data analysis Image Height	3000	рх
topography Sensor Width	6.3	mm
data management Sensor Height	4.7	mm
Focal Length	4.73	mm
Flight hight: 45 GSD: 1.50cm/p		



Camera Parameters

Image Width	8000	рх
Incoder III at a late		
Image Height	6000	рх
		Propell
Sensor Width	6.4	mm
Sensor Height	4.8	mm
Focal Length	4.50	mm

Flight hight: 45 m GSD: 0.80cm/px



Mavic Air2 -DJI

рх

рх

mm

mm

mm



Flight examples with the Litchi app:

> Flight examples with the Copterus app:



Orbit Mode Flight Planning



Waypoint Flight Planning

➢ Flight examples with the Dronelink



Grid Flight Planning









Mavic Pro 249 images in 16:9 format (dimension 4000 x 2250) Mavic Air 2 697 images in 4:3 format (Dimension 4000 x 3000) Mavic Air 2 with 526 images, separated by groups of object faces

Presentation of the best result with Mavic Air 2 in OpenDroneMap software: Textured Model



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The final result of the three-dimensional models generated from the historic construction had to adjust their mesh to be printed on a 3D Fused Deposition Modeling (FDM) printer.

