

The Privacy Funnel from the viewpoint of Local Differential Privacy

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Protecting Privacy in Open (& Big) Data Settings



- future: Postdoc, formal methods & tools, Twente
- **2018–present: Postdoc, security group, Eindhoven**
- 2014–2018: PhD, algebraic geometry, Nijmegen



Interests:

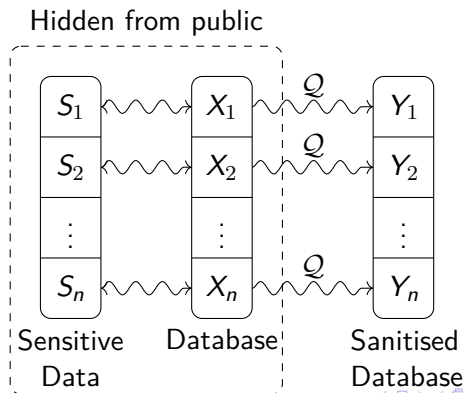
- Data sanitisation
- Differential privacy
- Privacy and utility metrics
- Information-theoretical properties of metrics

Current projects:

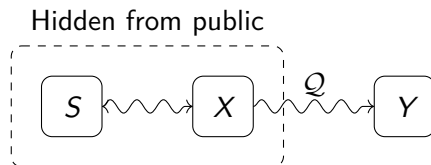
- Robust privacy metrics for Privacy Funnel
- Differentially private classifier learning
- Fisher information in private distribution estimation

Privacy Funnel setting

- Database \vec{X} consisting of rows X_1, \dots, X_n .
- Each entry X_i is correlated to secret information S_i .
- Goal: output sanitised database \vec{Y} that does not leak about \vec{S} .
- Method: *probabilistic* protocol Q operating on rows individually.
- Assumption: (S_i, X_i) discrete random variables, joint distr. known.



Privacy Funnel setting



- Goal: Y contains lot of info about X , little info about S . *How do we measure these?*
- Typically: Find Q that maximises $I(X; Y)$ while $I(S; Y) \leq L$ for a given L .
- Problems:
 - ▶ $I(S; Y)$ is *average* leakage, some rows may be more compromised
 - ▶ Current methods only give local optima

Definition

Let $\varepsilon > 0$.

- 1 Q satisfies ε -LDP (w.r.t. S) if for all $s, s' \in \mathcal{S}$ and all $y \in \mathcal{Y}$:

$$\frac{\mathbb{P}(Q(X) = y | S = s)}{\mathbb{P}(Q(X) = y | S = s')} \leq e^\varepsilon$$

- 2 Q satisfies ε -LIP (w.r.t. S) if for all $s \in \mathcal{S}$ and all $y \in \mathcal{Y}$:

$$e^{-\varepsilon} \leq \frac{\mathbb{P}(Q(X) = y | S = s)}{\mathbb{P}(Q(X) = y)} \leq e^\varepsilon$$

Privacy depends on ε ; typically $\varepsilon \approx 1$.

Local Differential Privacy & Local Information Privacy

Properties:

- Worst-case metrics
- LDP stricter than LIP
- both depend on $p_{S,X}$
- $\frac{p_{y|s}}{p_y} = \frac{p_{s|y}}{p_s}$, so LIP bounds difference between prior and posterior
- LDP does so even when p_S is unknown
- *but we assume it is known*

Conclusion: LIP more sensible metric than LDP

Definition

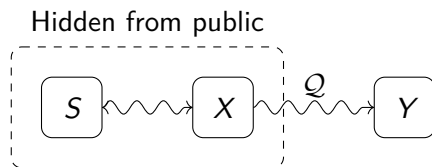
ϵ -LDP: $\forall y, s, s' :$

$$\frac{p_{y|s}}{p_{y|s'}} \leq e^\epsilon$$

ϵ -LIP: $\forall y, s :$

$$e^{-\epsilon} \leq \frac{p_{y|s}}{p_y} \leq e^\epsilon$$

Problems



Problem

Given ε , find Q that maximises $I(X; Y)$ s.t. Q satisfies ε -LDP/LIP.

I will show:

- We can find the optimal Q ;
- This is (computationally) easier for LIP than for LDP.

Optimal ε -LDP protocol

Let $a = |\mathcal{X}|$, $b = |\mathcal{Y}|$.

- \mathcal{Q} is given by $G := p_{Y|X} \in \mathbb{R}^{b \times a}$.
- Theorem: $b = a$ for optimal protocol.
- $\{\varepsilon$ -LDP protocols $\} = \Delta$ where

$$\Delta = \left\{ G \in \mathbb{R}^{b \times a} : \begin{array}{l} \forall x: \sum_y G_{y|x} = 1, \\ \forall x, y: G_{y|x} \geq 0, \\ \forall s \neq s', y: \sum_x G_{y|x} p_{x|s} \leq e^\varepsilon \sum_x G_{y|x} p_{x|s'} \end{array} \right\}$$

This is a polyhedron of dimension $a^2 - a$.

- To do: maximise $I(X; Y) = \sum_{x,y} p_x G_{y|x} \log \frac{G_{y|x}}{\sum_{x'} p_{x'} G_{y|x'}} =: f(G)$ over Δ .
- f is convex, so maximum is obtained in vertex.
- **Find vertices of $\Delta \Rightarrow$ find optimal ε -LDP protocol**

Optimal ε -LIP protocol

Let $a = |\mathcal{X}|$, $b = |\mathcal{Y}|$.

- \mathcal{Q} is given by $J := p_{X|Y} \in \mathbb{R}^{a \times b}$ and $\vec{\theta} = p_Y \in \mathbb{R}^b$ with $J \cdot \vec{\theta} = p_X$.
- $\forall y: J_y \in \Gamma$ where

$$\Gamma = \left\{ R \in \mathbb{R}^a : \begin{array}{l} \sum_x R_x = 1, \\ \forall x: R_x \geq 0, \\ \forall s: e^{-\varepsilon} p_s \leq \sum_x p_{s|x} R_x \leq e^\varepsilon p_s \end{array} \right\}$$

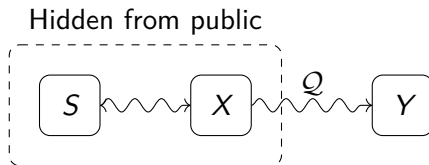
This is a polyhedron of dimension $a - 1$.

- Theorem: optimal \mathcal{Q} has J_y vertex of Γ for all y .
- Theorem: if we know vertices of Γ we can find $\vec{\theta}$ via linear optimisation problem.
- **Find vertices of $\Gamma \Rightarrow$ find optimal ε -LIP protocol**

Let $a = |\mathcal{X}|$, $c = |\mathcal{S}|$

- Complexity vertex enumeration: $\mathcal{O}(ndv)$, with $(n, d, v) = (\text{dimension, inequalities, vertices})$.
- LDP: $n = a^2 - a$, $d = a^2 + c^2 - c$
- LIP: $n = a - 1$, $d = a + 2c$
- v unknown, generally $v \leq \binom{n}{d}$
- So: LIP faster! (about $5000\times$ for $c = 2$, $a = 5$)
- Both methods computationally infeasible for large a, c

Conclusion



We have solved:

Problem

Given ϵ , find Q that maximises $I(X; Y)$ s.t. Q satisfies ϵ -LDP/LIP.

- Better privacy guarantees than original Privacy Funnel, with optimal utility
- LIP faster to optimise, more sensible than LDP
- Optimisation hard for large spaces