



DIPARTIMENTO DI
INFORMATICA, SISTEMISTICA E
COMUNICAZIONE

Human-Machine Interaction: EEG Electrode and Feature Selection Exploiting Evolutionary Algorithms in Motor Imagery Tasks

Aurora Saibene, Francesca Gasparini

Aurora Saibene

`a.saibene2@campus.unimib.it`

Multi Media Signal Processing Laboratory

(<https://mmsp.unimib.it/>)

Department of Informatics, Systems and Communications

University of Milano-Bicocca

October 18-22, 2020

Short Resume

PhD student in Computer Science at the University of Milano-Bicocca.

Main research interests:

- Brain-related topics, especially brain computer interfacing;
- Signal processing: from electroencephalographic signals to underwater images;
- Artificial intelligence techniques in different applications: discriminate effects on time-series, learn new features, classify memes.

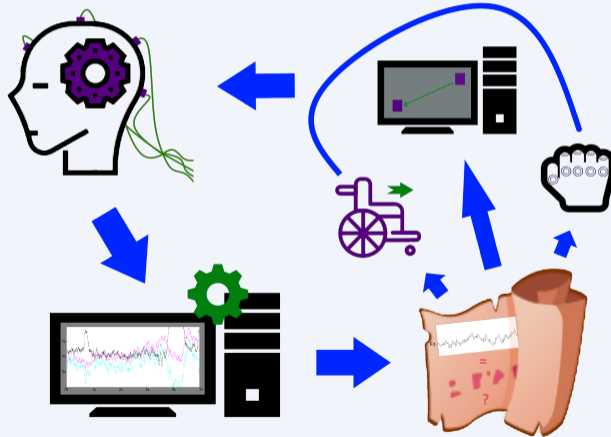
Trying to learn new things especially by interacting with other researchers and with the students I am tutoring, both in a Machine Learning course and for thesis completion.

Overview

- ① Introduction
- ② Aim
- ③ Background
- ④ Proposed Approach
- ⑤ Discussion
- ⑥ Conclusion and Future Work

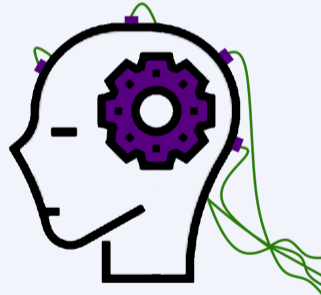
Introduction [1/4]

Human-Machine Interaction: EEG Electrode and Feature Selection Exploiting Evolutionary Algorithms in **Motor Imagery Tasks**



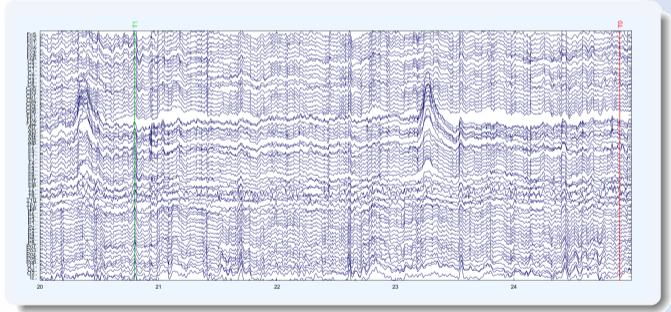
Human-Machine Interaction: EEG Electrode and Feature Selection Exploiting Evolutionary Algorithms in Motor Imagery Tasks

- is non-invasive;
- records brain activities and functions;
- is characterized by frequency bands;
- has temporal and spatial resolutions.



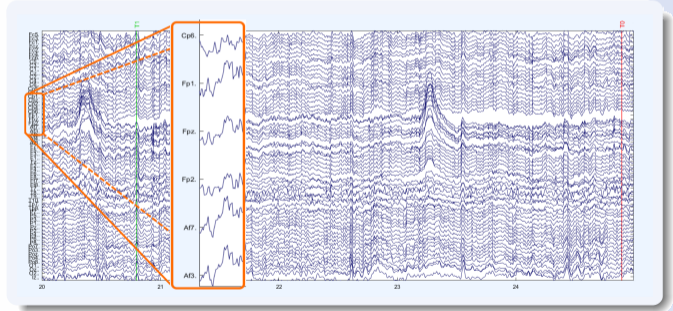
Human-Machine Interaction: EEG Electrode and Feature Selection Exploiting Evolutionary Algorithms in Motor Imagery Tasks

- is non-invasive;
- records brain activities and functions;
- is characterized by frequency bands;
- has temporal and spatial resolutions.



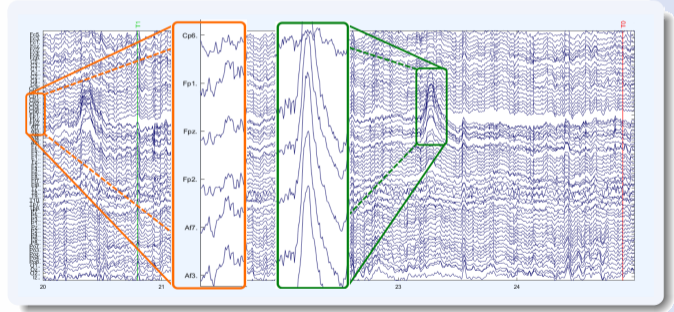
Human-Machine Interaction: EEG Electrode and Feature Selection Exploiting Evolutionary Algorithms in Motor Imagery Tasks

- is non-invasive;
- records brain activities and functions;
- is characterized by frequency bands;
- has temporal and spatial resolutions.

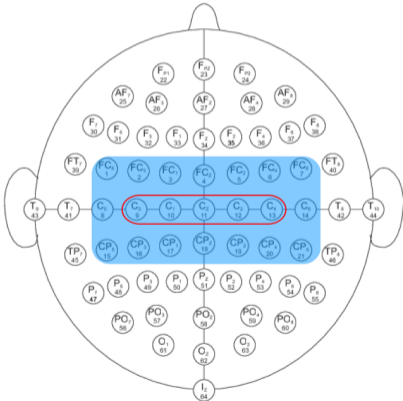


Human-Machine Interaction: EEG Electrode and Feature Selection Exploiting Evolutionary Algorithms in Motor Imagery Tasks

- is easily affected by noise;
- is heterogeneous.



Human-Machine Interaction: EEG Electrode and Feature Selection Exploiting Evolutionary Algorithms in Motor Imagery Tasks



Features

- Type: limited;
- Selection/Extraction: a priori, dimensionality reduction, ignores spatial and type contributions;
- Purpose: improve performance.

Human-Machine Interaction: EEG Electrode and Feature Selection Exploiting Evolutionary Algorithms in Motor Imagery Tasks

Literature

- Type: limited;
- Selection/Extraction: a priori, dimensionality reduction, ignores spatial and type contributions;
- Purpose: improve performance.

Proposed

- Type: combinations of heterogeneous features;
- Selection: ignores a priori knowledge;
- Purpose: access spatial and type contributions.

Provide a benchmark to highlight spatial and feature type contributions

Contributions

- ① Population-based approach;
- ② Heterogeneous features;
- ③ Evolutionary Feature Selection (EFS);
- ④ Analyses of electrodes and feature type contributions.

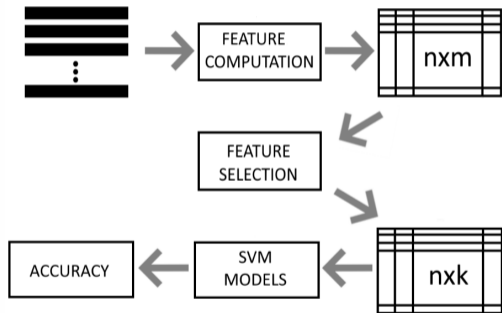
- **Core:** EFS → minimum number of features, maximum classification accuracy;
- **Advantages:** no field knowledge, different solutions with single execution.
- **Literature:** electrode set reduction, subject-based approach, poor number of instances [1][2][3].

- **Core:** EFS → minimum number of features, maximum classification accuracy;
- **Advantages:** no field knowledge, different solutions with single execution.
- **Literature:** electrode set reduction, subject-based approach, poor number of instances [1][2][3].

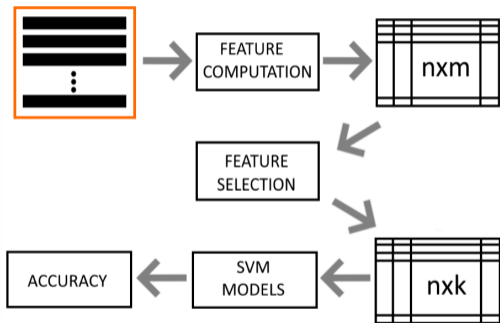
Dataset: EEG Motor Movement/Imagery Dataset [4][5]

- Subjects: 109;
- Instances for motor movement task: $4924 = 2469 \text{ LH} + 2455 \text{ RH}$;
- Instances for motor imagery task: $4915 = 2479 \text{ LH} + 2436 \text{ RH}$;
- Sampling rate: 160 Hz;
- Normalization: min-max, Z-score.

Proposed Approach



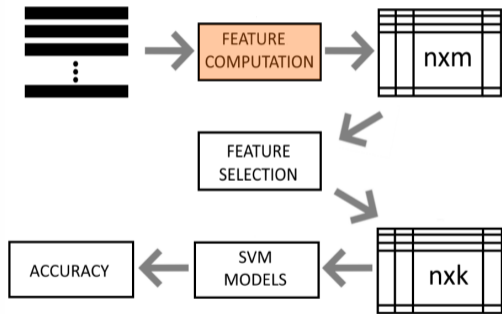
Proposed Approach



Pre-processing and tests

- 1 Notch filter: 50 Hz;
- 2 FIR filter: 7 - 31 Hz;
- 3 Test on non-normalized (NN-DS), min-max normalized (MM-DS) and z-score normalized (ZS-DS) data.

Proposed Approach

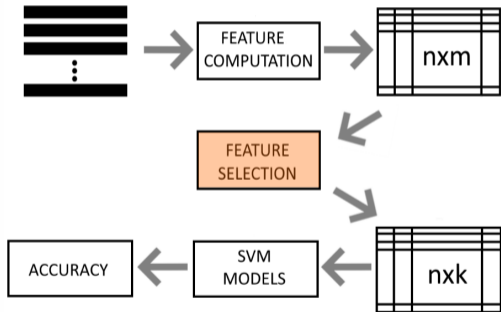


Feature Computation

1280 features = 64 electrodes \times [3 Hjorth params + 2 frequency bands \times (PSD through Welch + 3 modalities \times PSD through Morlet) + statistical measures].

- Time-domain: Hjorth parameters [6];
- Frequency-domain: PSD estimation through Welch's method [7];
- Time-frequency domain: PSD extraction through Morlet wavelet convolution [8].

Proposed Approach



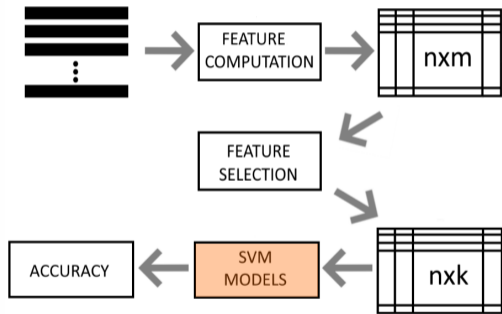
Feature Selection

- Benchmark: principal component analysis and a priori selection;
- EFS techniques: genetic algorithm, particle swarm optimization, simulated annealing
 - wrapper approach \rightarrow SVM with radial basis and scaled gamma;
 - objective functions: performance only, performance/number of features [9]

$$f(x) = \alpha(1 - acc) + (1 - \alpha) \left(1 - \frac{N_{sf}}{N_{if}} \right)$$

- Output: binary vector.

Proposed Approach



Classifiers

- Binary classification of LH/RH movement/imagination;
- Models: Linear, Quadratic, Cubic, Fine/Medium/Coarse Gaussian SVM models (5-fold cross validation);
- Dataset: (1) all the features; (2) a priori selected; (3) PCA dimensions; (4) EFS selected;
- Total number of tests: 11.

Discussion [1/3]

Table: Best results obtained in each test on motor left/right hand movement¹

<i>Test</i>	<i>SVM model</i>	<i>Dataset</i>	<i># features</i>	<i>Accuracy (%)</i>
all features	cubic	ZS-DS	1280	67.8
a priori	mean Gaussian	ZS-DS	100	62.7
PCA	quadratic	MM-DS	43	62.3
GA accuracy	cubic	ZS-DS	662	67.2
GA trade-off	cubic	ZS-DS	646	67.8
PSO accuracy	cubic	ZS-DS	620	67.3
PSO trade-off	quadratic	ZS-DS	675	68.0
SA accuracy	cubic	ZS-DS	1117	68.3
SA trade-off	cubic	ZS-DS	1116	67.8
agreement accuracy	quadratic	ZS-DS	264	66.4
agreement trade-off	cubic	ZS-DS	308	67.5

¹NN-DS = non-normalized, MM-DS = min-max normalized, ZS-DS normalized data.

Discussion [2/3]

Table: Best results obtained in each test on motor left/right hand imagination²

<i>Test</i>	<i>SVM model</i>	<i>Dataset</i>	<i># features</i>	<i>Accuracy (%)</i>
all features	linear	NN-DS	1280	64.3
a priori	linear	ZS-DS	100	59.7
PCA	quadratic	MM-DS	41	59.5
GA accuracy	cubic	ZS-DS	641	63.8
GA trade-off	quadratic	ZS-DS	608	63.7
PSO accuracy	cubic	MM-DS	622	61.7
PSO trade-off	quadratic	ZS-DS	714	64.0
SA accuracy	cubic	ZS-DS	1114	63.6
SA trade-off	cubic	ZS-DS	1117	63.8
agreement accuracy	cubic	ZS-DS	272	62.4
agreement trade-off	quadratic	ZS-DS	313	63.3

²NN-DS = non-normalized, MM-DS = min-max normalized, ZS-DS normalized data.

Electrodes agreement

- Left/right hand movement: a priori electrodes selected + frontal, parietal and occipital electrodes;
- Left/right hand imagination: a priori electrodes selected + fronto-central, parietal and occipital electrodes;

Feature types

- Left/right hand movement: great influence of statistical measures;
- Left/right hand imagination: great contribution from Hjorth activity parameter;
- Both tasks: presence of time-frequency related features;

Conclusion and Future Work

- ✓ Dataset: EEG Motor Movement/Imagery Dataset;
- ✓ Better results on: z-score normalized dataset → heterogeneity mitigation;
- ✓ Different feature types → broaden the analysis;
- ✓ The EFS techniques contributes in the feature selection without the influence of expert knowledge;
- ✓ Different contributions of the brain areas and feature types;
- Test with different fitness functions and on different datasets;
- Define experimental protocol considering ergonomic issues.

Thank you

Bibliography

- 1 A. Atyabi, M. Luerssen, S. Fitzgibbon, and D. M. Powers, "Evolutionary feature selection and electrode reduction for EEG classification," in 2012 IEEE congress on evolutionary computation. IEEE, 2012, pp. 1–8.
- 2 K. Amarasinghe, P. Sivils, and M. Manic, "EEG feature selection for thought driven robots using evolutionary algorithms," in 2016 9th International Conference on Human System Interactions (HSI). IEEE, 2016, pp. 355–361.
- 3 K. Amarasinghe, P. Sivils, and M. Manic, "EEG feature selection for thought driven robots using evolutionary algorithms," in 2016 9th International Conference on Human System Interactions (HSI). IEEE, 2016, pp. 355–361.
- 4 A. L. Goldberger, L. A. Amaral, L. Glass, J. M. Hausdorff, P. C. Ivanov, R. G. Mark, J. E. Mietus, G. B. Moody, C.-K. Peng, and H. E. Stanley, "PhysioBank, PhysioToolkit, and PhysioNet: components of a new research resource for complex physiologic signals," *circulation*, vol. 101, no. 23, 2000, pp. e215–e220.
- 5 G. Schalk, D. J. McFarland, T. Hinterberger, N. Birbaumer, and J. R. Wolpaw, "BCI2000: a general-purpose brain-computer interface (BCI) system," *IEEE Transactions on biomedical engineering*, vol. 51, no. 6, 2004, pp. 1034–1043.
- 6 S.-H. Oh, Y.-R. Lee, and H.-N. Kim, "A novel EEG feature extraction method using Hjorth parameter," *International Journal of Electronics and Electrical Engineering*, vol. 2, no. 2, 2014, pp. 106–110.
- 7 P. Welch, "The use of fast Fourier transform for the estimation of power spectra: a method based on time averaging over short, modified periodograms," *IEEE Transactions on audio and electroacoustics*, vol. 15, no. 2, 1967, pp. 70–73.
- 8 M. X. Cohen, "A better way to define and describe Morlet wavelets for time-frequency analysis," *NeuroImage*, vol. 199, 2019, pp. 81–86.
- 9 S. M. Vieira, L. F. Mendonca, G. J. Farinha, and J. M. Sousa, "Modified binary PSO for feature selection using SVM applied to mortality prediction of septic patients," *Applied Soft Computing*, vol. 13, no. 8, 2013, pp. 3494–3504.

The End