

Unmanned Aerial Vehicles as an Enabler for Next Generation Mobility

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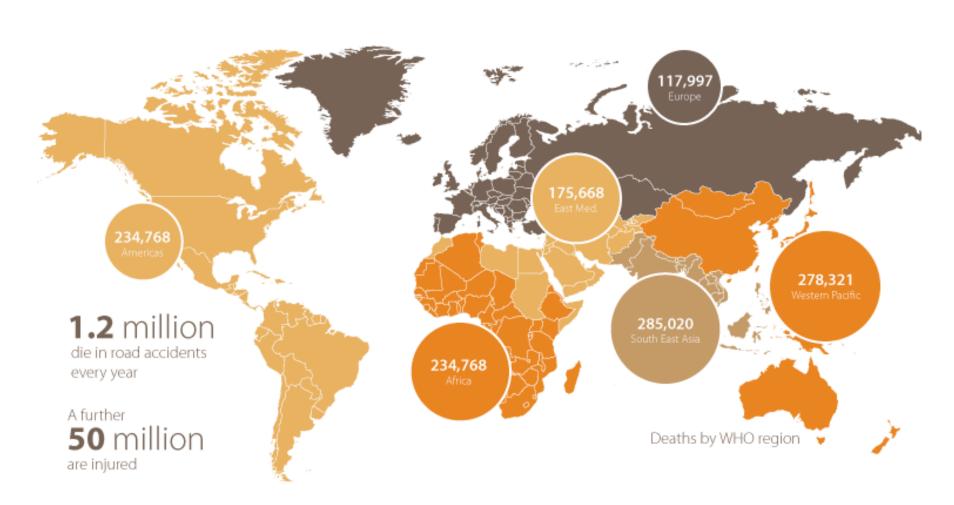
About QMIC





Road Safety a Worldwide Problem





Source: WHO this year - 2013



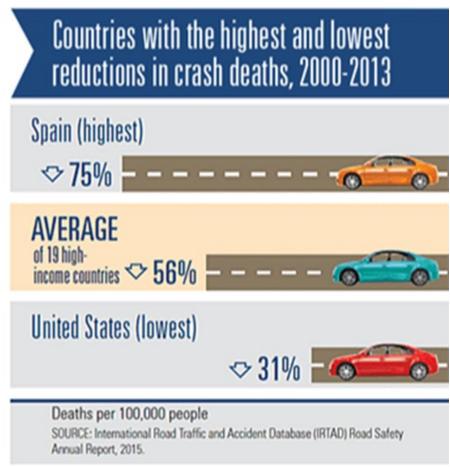
Considerable Improvements





Deaths per 100,000 people

SOURCE: WHO Global Status Report on Road Safety, 2015.





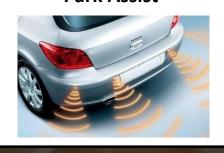


And Cars Are Safer Than They've Ever Been

Built to Crash...



Park Assist



Driver & Passenger Centric ...



Adaptive Cruise Control



Driver Assisted...



Lane Assist

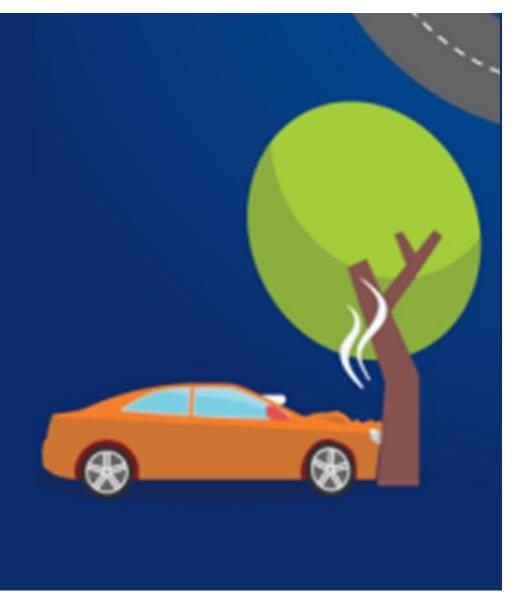


Go To Next Level...



of all crashes are due to minor mistakes such as distraction, fatigue or being slightly above the speed limit

Source: www.carrsq.qut.edu.au





Automated Driving to Eliminate Human Error!

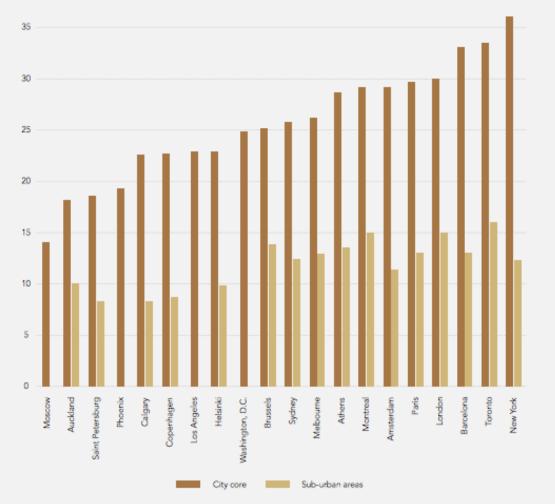




CITIES ARE **DESIGNED FOR CARS**

30-35%

Land used for streets





There are times as many parking spaces as cars in America.

of our downtown **=** commercial cores are devoted to parking.



Source: http://www.motherjones.com/environment/2016/01/future-parking-self-driving-cars

WASTED SPACE & MONEY

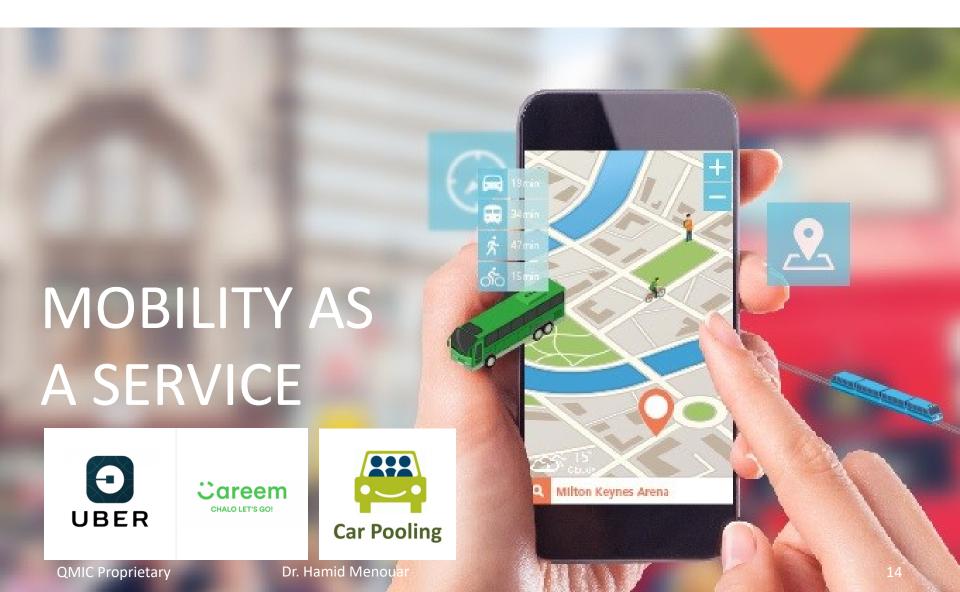




DIFFERENT EXPECTATIONS



THERE IS ONE trend of mobility that young people have embraced, though:

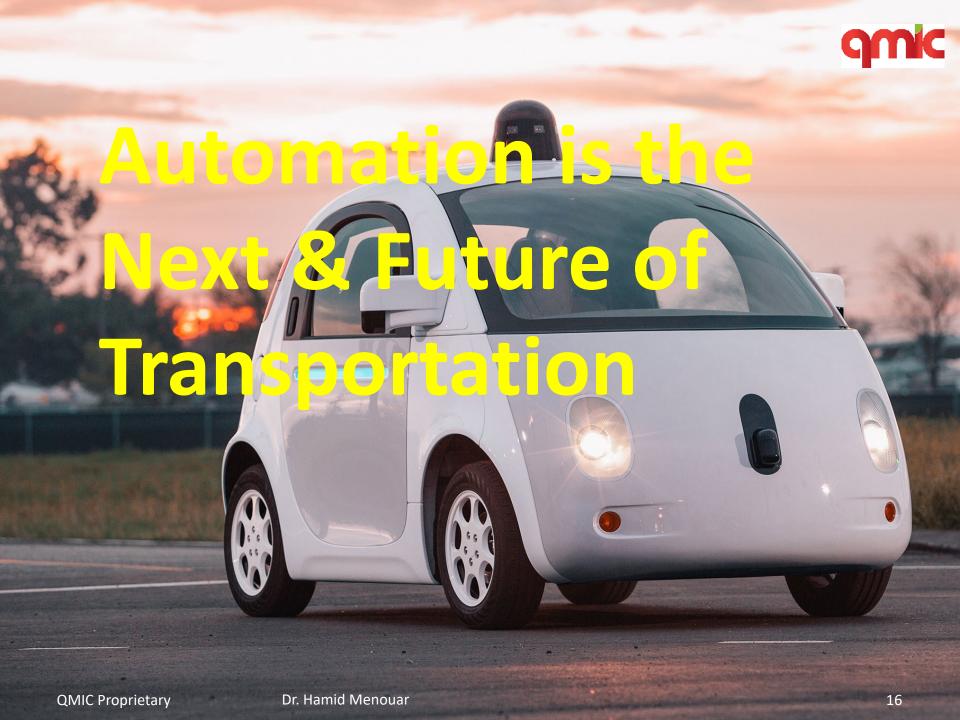




Fleet of Taxi

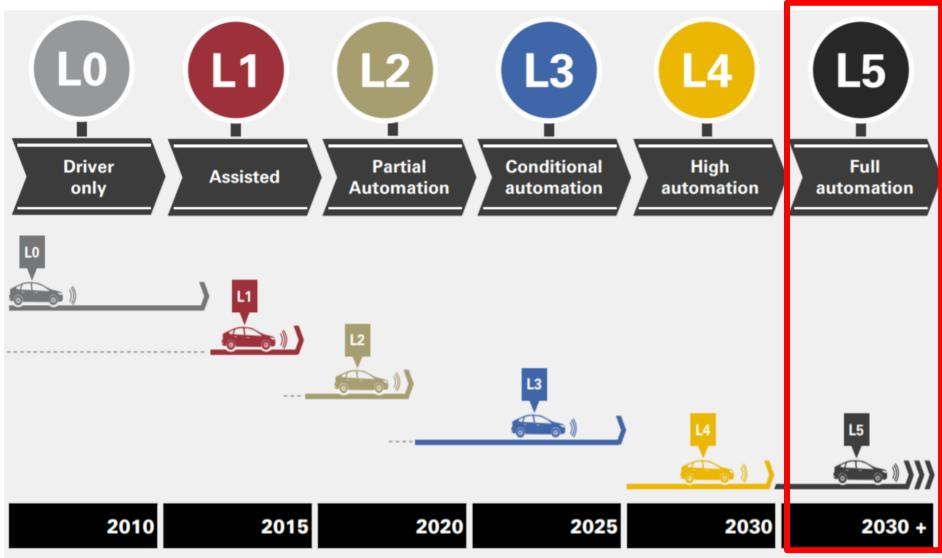
ROBOTS











Source: KPMG: CAV – the UK Economic Opportunity, March 2015

QMIC Proprietary Dr. Hamid Menouar

What about road maintenance?





What about road assistance?





What about road surveillance?





What about road assistance?





Drone-aided Platform for Enabling Next Generation ITS

DröneITS

NPRP9-257-1-056 | www.DronelTS.com



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UAVs Applications ... A Reality!















Special Issue Magazine



ENABLING MOBILE AND WIRELESS TECHNOLOGIES FOR SMART CITIES

UAV-Enabled Intelligent Transportation Systems for the Smart City: Applications and Challenges

Hamid Menouar, Ismail Güvenc, Kemal Akkaya, A. Selcuk Uluagac, Abdullah Kadri, and Adem Tuncer

Due to their mobility, autonomous operation, and communication/ processing capabilities, UAVs are envisaged in many ITS application domains. The authors describe the possible ITS applications that can use

ABSTRACT

There could be no smart city without a reliable and efficient transportation system. This necessity makes the ITS a key component of any smart city concept. While legacy ITS technologies are deployed worldwide in smart cities, enabling the next generation of ITS relies on effective integration of connected and autonomous vehicles, the two technologies that are under wide field testing in many cities around the world. Even though

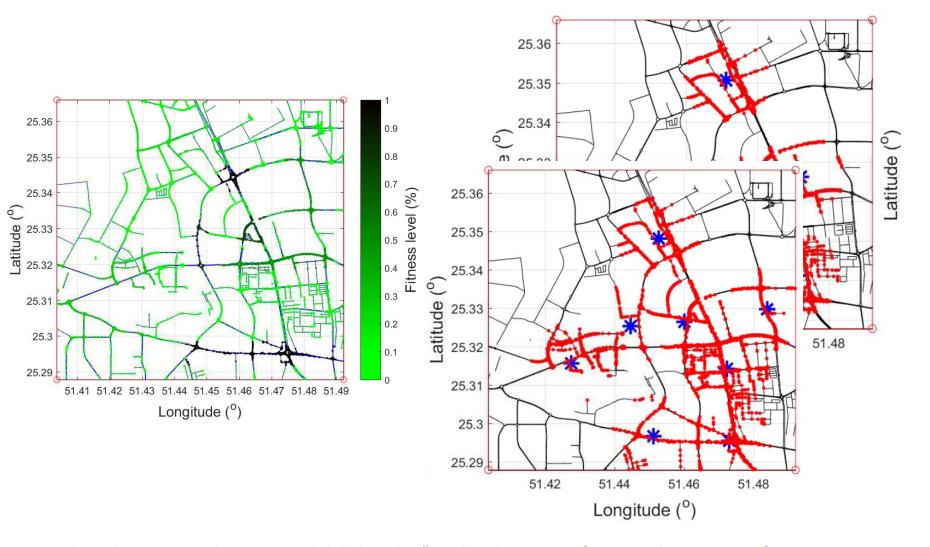
com/b?node=8037720011). Similarly, DHL of Germany and China's largest mailing company have started their experiments with a fleet of UAVs that could deliver around 500 parcels every day. Use of UAVs for daily consumer-oriented services is expanding and becoming a reality.

Automation of the overall transportation system cannot be achieved through only automating the vehicles. Indeed, other components of the road and the end-to-end transportation system, such as the field support team, traffic police, road

Hamid Menouar, Ismail Guven, Kemal Akkaya, A. Selcuk Uluagac, Abdullah Kadri, Adem Tuncer, "<u>UAV-Enabled Intelligent</u> <u>Transportation Systems for the Smart City: Applications and Challenges</u>", <u>IEEE Communication Magazine</u> – Special Issue "Enabling Mobile and Wireless Technologies for Smart Cities, March 2017.

Placement of the UAV Docking Stations

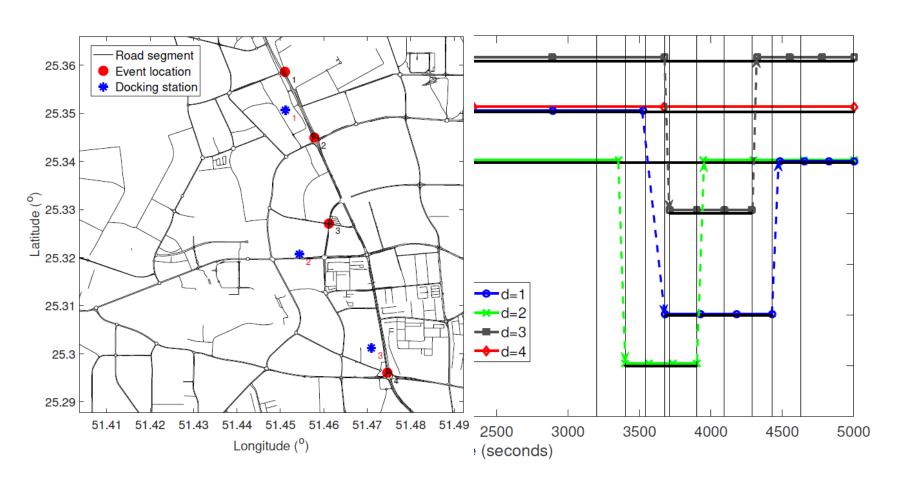




Hakim Ghazzai, Hamid Menouar, Abdullah Kadri, "On the Placement of UAV Docking Stations for Future Intelligent Transportation Systems", the 2017 IEEE 85th Vehicular Technology Conference (VTC), 4–7 June 2017 in Sydney, Australia.

UAV Missions Scheduling





Hakim Ghazzai, Hamid Menouar, Abdullah Kadri, Yehia Massoud, "<u>Future UAV-based ITS: A Comprehensive Scheduling Framework</u>", to appear in IEEE Access. June 2019, pages 1-18, Print ISSN: 2169-3536, Online ISSN: 2169-3536, DOI: 10.1109/ACCESS.2019.2921269.

Flying IoT Gateway



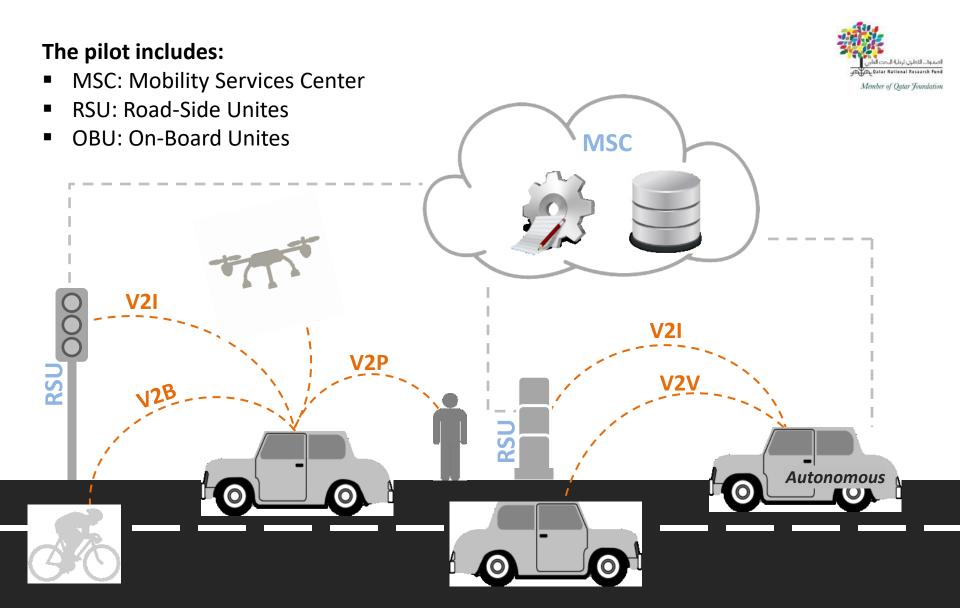


Video link: https://www.youtube.com/watch?v=jmxxL9

Hamidullah Binol, Eyuphan Bulut, Kemal Akkaya, Ismail Guvenc, "<u>Time Optimal Multi-UAV Path Planning for Gathering ITS Data from Roadside Units</u>", In Proc of 2018 IEEE 88th Vehicular Technology Conference: VTC2018-Full, 27–30 August 2018, Chicago, USA.

Qatar V2X Pilot - Architecture





Qatar V2X Pilot - Architecture







Unmanned Areal Vehicles (UAVs) **Drones for ITS**

Flaying V2X Road-Side Unit





Video link:
https://www.youtube.com/watch?v=eJ_JUj
mgLOQ

Nico Saputro, Kemal Akkaya, Ramazan Algin, and Selcuk Uluagac, "<u>Drone-assisted Multi-purpose Roadside Units for Intelligent Transportation Systems</u>", In Proc of 2018 IEEE 88th Vehicular Technology Conference: VTC2018-Full, 27–30 August 2018, Chicago, USA.

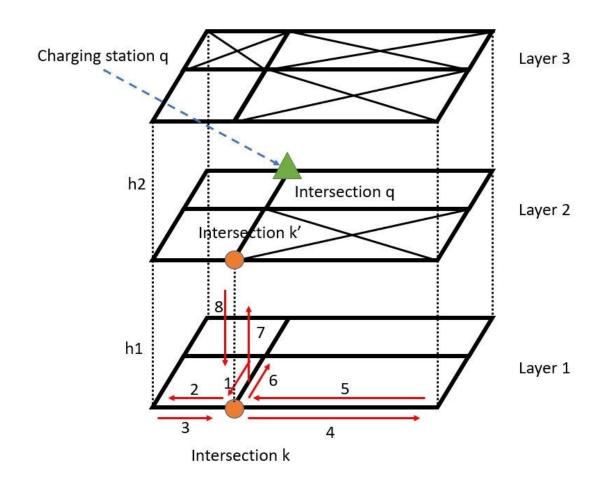
3D Space Navigation





3D Space Navigation





Xiangpeng Wan, Hakim Ghazzai, Yehia Massoud, Hamid Menouar, "Optimal Collision-free Navigation for Multi-Rotor UAV Swarms in Urban Areas", In Proc of 2019 IEEE 89th Vehicular Technology Conference: VTC2019-Spring, 28 April – 1 May 2019, Kuala Lumpur, Malaysia.

UAVs Applications ... A Reality!





An Example





What if we let the UAV ride the bus?

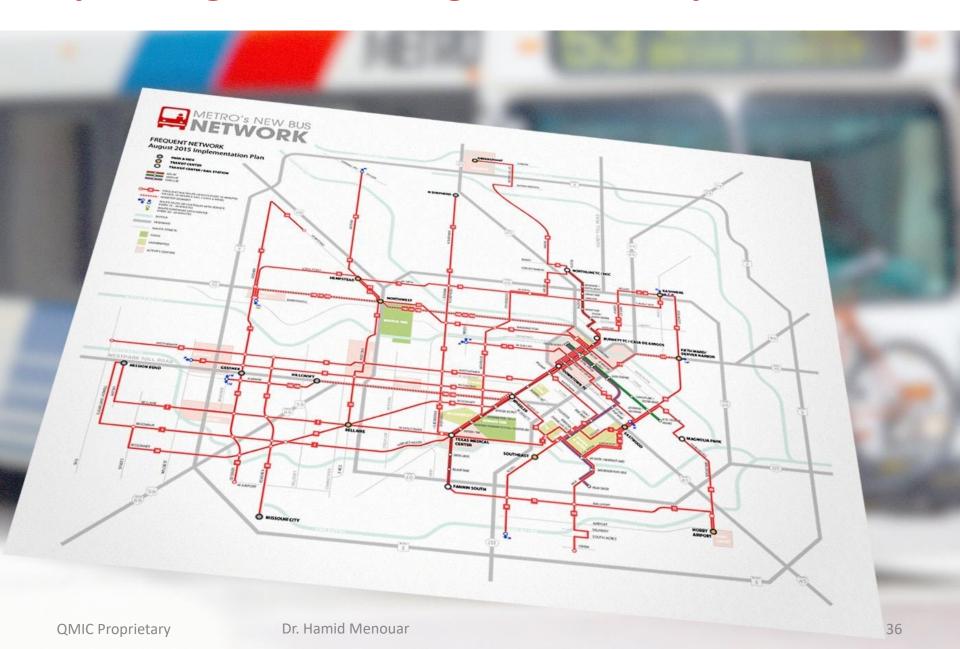




Noureddine Lasla, Hakim Ghazzai, Hamid Menouar, Yehia Massoud, "Exploiting Land Transport to Improve the UAV's Performances for Longer Mission Coverage in Smart Cities", In Proc of 2019 IEEE 89th Vehicular Technology Conference: VTC2019-Spring, 28 April – 1 May 2019, Kuala Lumpur, Malaysia.

Exploiting the Existing Land Transport!





Others already doing it...





Automated Landing

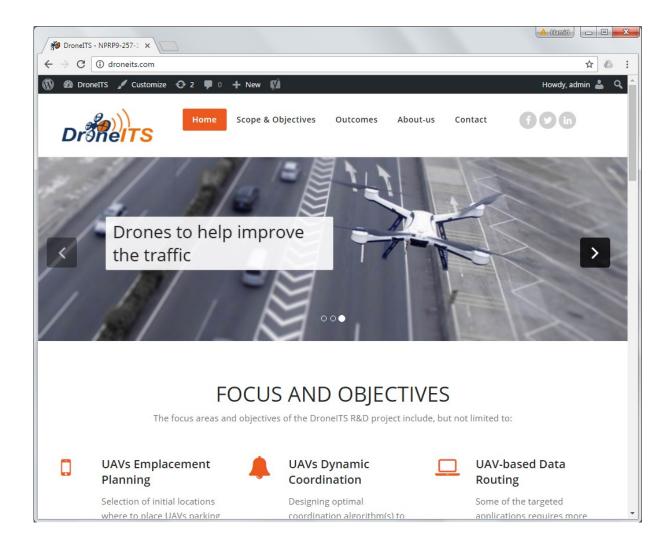




Video link: https://www.youtube.
com/watch?v=iUO39s
-Zj08









Thank You!

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