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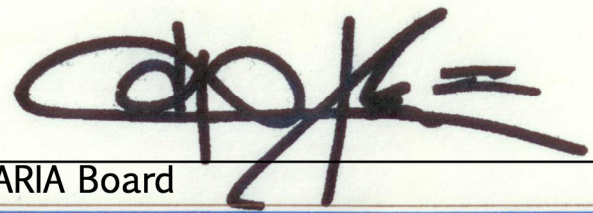
# Best Paper Award

Spatial Visibility Trajectory Planning Using  
Inverse Reinforcement Learning

By

Oren Gal, Yerach Doytsher

Presented during INFOCOMP 2019, The Ninth International Conference on Advanced Communications and  
Computation, held in Nice, France during July 28 - August 2, 2019.

  
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