



# *Handling Uncertainty as a Human Factor in Transportation Problems*

Nice, October 2018

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*'Only certainty is that nothing is certain.'*

*Chinese fortune cookie*

*"An important source of bad decisions is illusion of certainty."*

*Kenneth Boulding*



# NATURE OF UNCERTAINTY

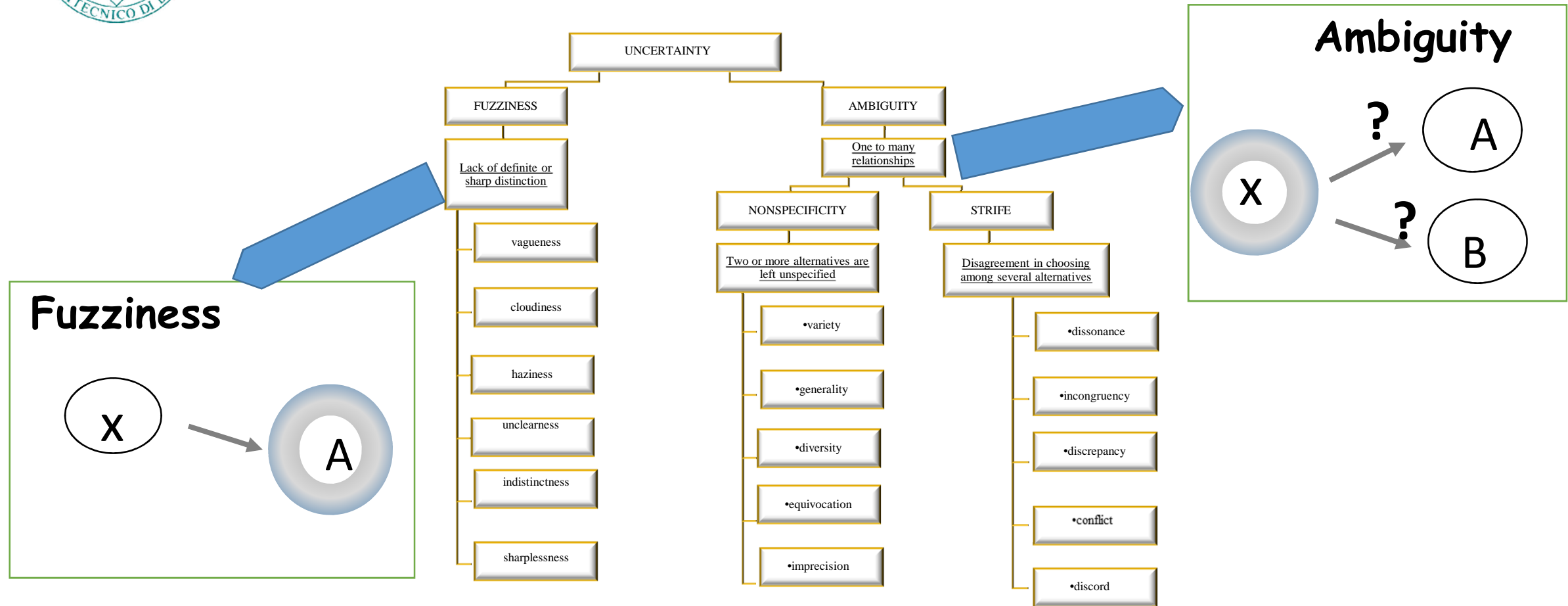
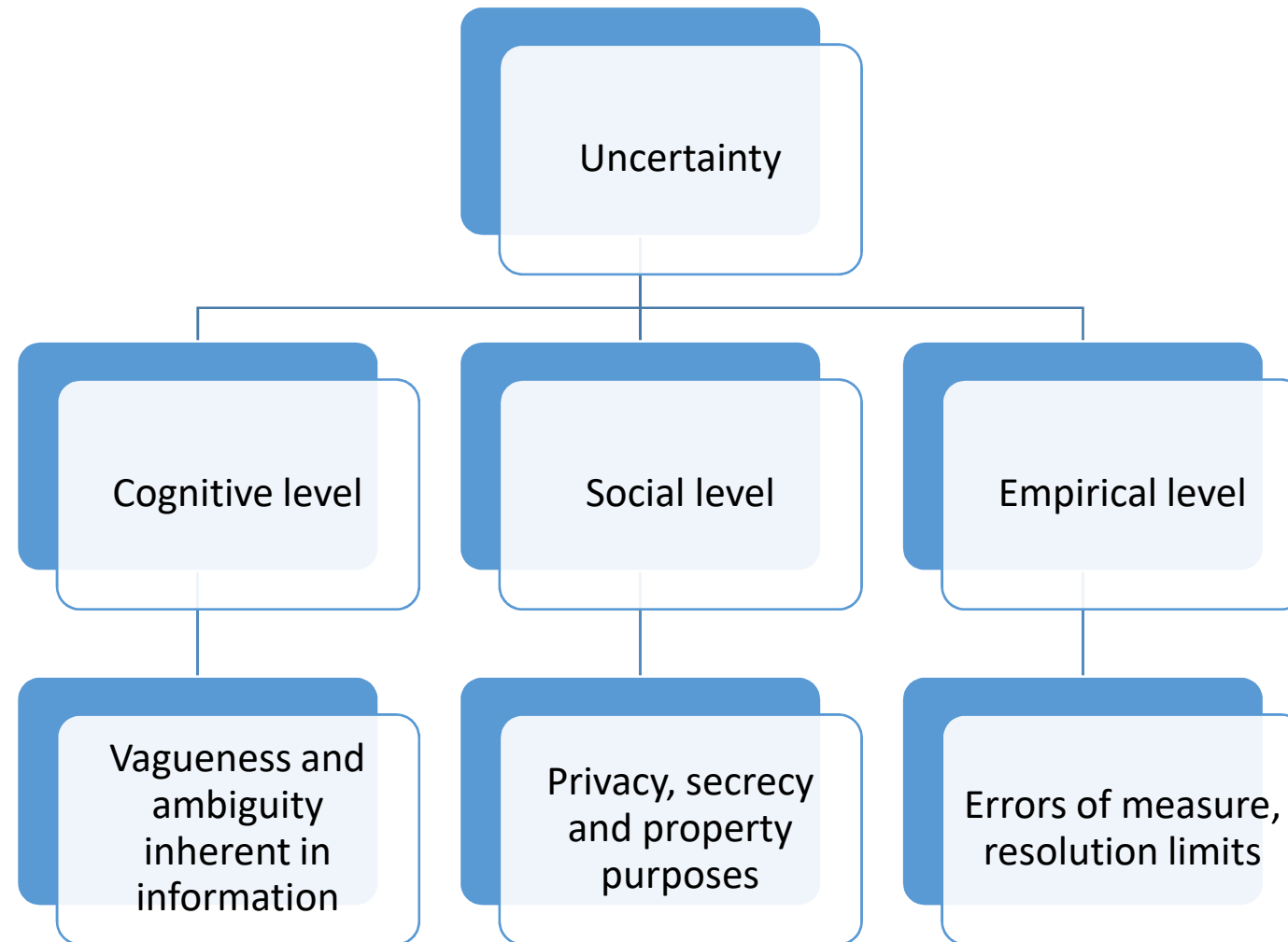


Fig. 1 -Different facets of Uncertainty



# Handling Uncertainty as a Human Factor in Transportation Problems





# Handling Uncertainty as a Human Factor in Transportation Problems

Green:



go

Yellow:



clear the intersection

Red:



stop



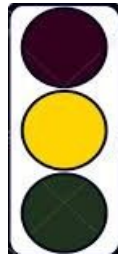
# Handling Uncertainty as a Human Factor in Transportation Problems

Green:



go

Yellow:



Speed up

Red:



Speed up more



# Handling Uncertainty as a Human Factor in Transportation Problems

- Gödel's theorems of incompleteness.

The theorems demonstrate the inherent limitations of every formal axiomatic system containing basic arithmetic.

- Shackle [1961] :

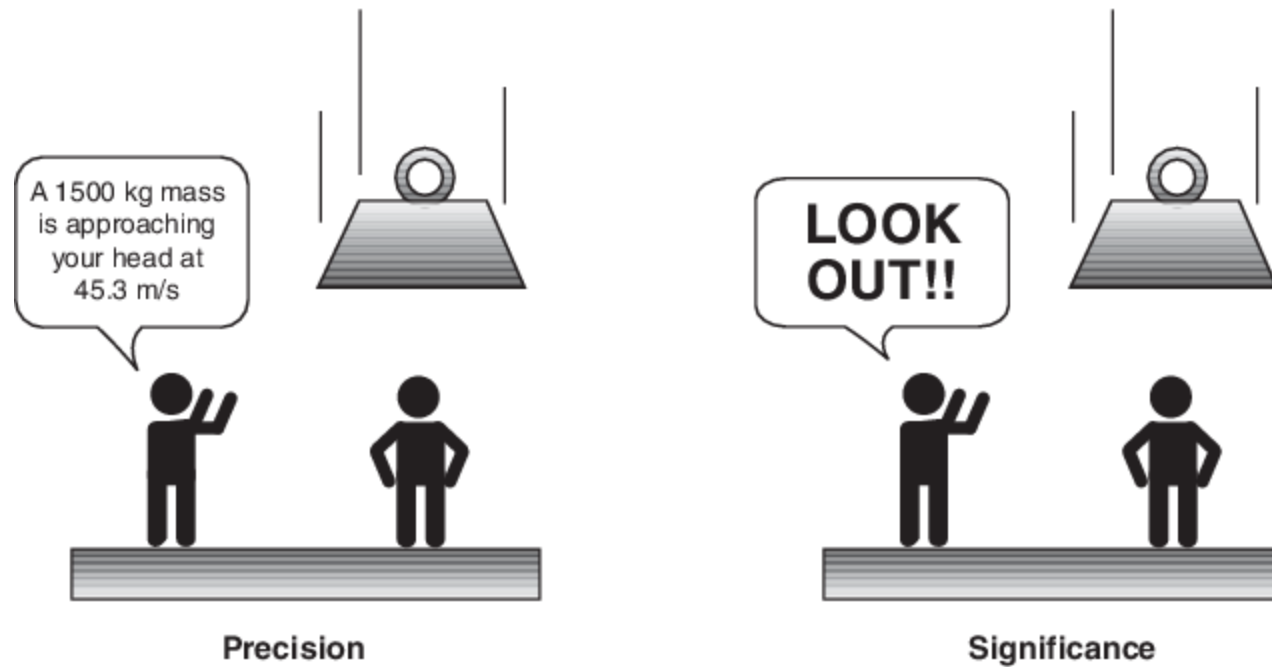
"In a predestinate world, decision would be *illusory*; in a world of a perfect foreknowledge, *empty*; in a world without natural order, *powerless*. Our intuitive attitude to life implies non-illusory, non-empty, non-powerless decision.... Since decision in this sense excludes both perfect foresight and anarchy in nature, it must be defined as choice in face of bounded uncertainty."

- Smithson [1989]:

"Western intellectual culture has been preoccupied with the pursuit of absolutely certain knowledge or, barring that, the nearest possible approximation of it."



# Handling Uncertainty as a Human Factor in Transportation Problems







# Handling Uncertainty as a Human Factor in Transportation Problems

Uncertainty in Transportation Problems resides in:

- Data (numerical, descriptive, perceptive)
- Measurement
- Human perception
- Understanding of objectives and goals
- Reasoning logic based on similarity and association
- Accuracy level required for planning and design



# Handling Uncertainty as a Human Factor in Transportation Problems

## How to measure Uncertainty?

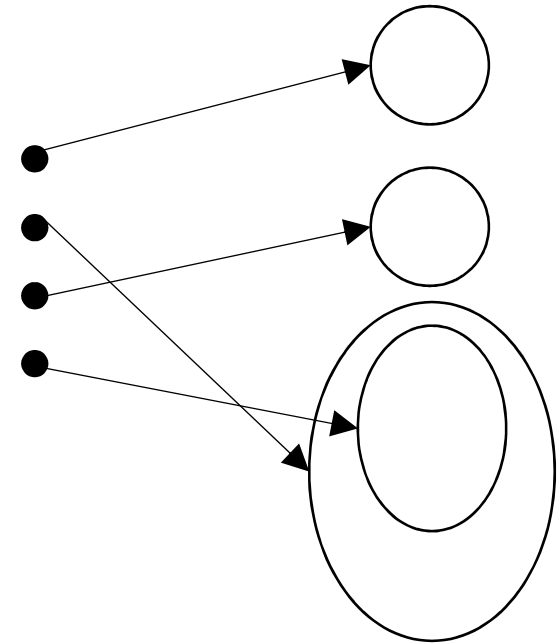
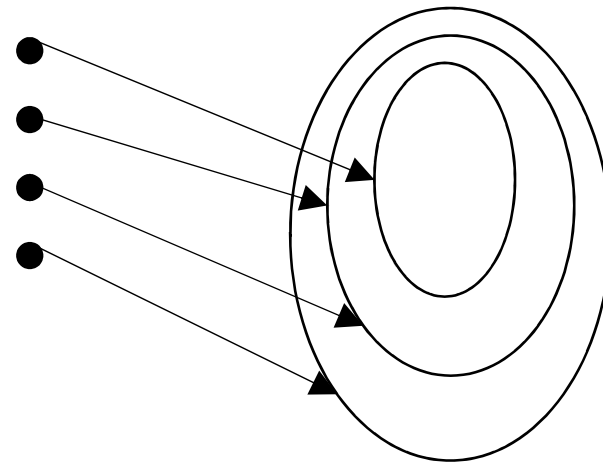
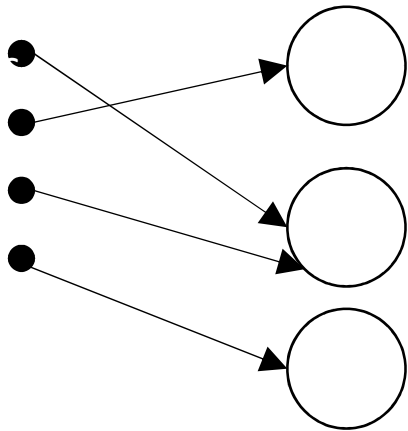


How do you want it - the crystal ball or probability?



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## UNCERTAINTY MEASURES PATTERN

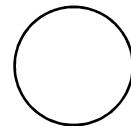


PROBABILITY THEORY

POSSIBILITY THEORY

EVIDENCE THEORY

● EVIDENCE



○ ALTERNATIVE



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$$U(S) = a \cdot \log_b |S| \quad (\text{Hartley, 1928})$$

where:

$S$  is a generic finite set

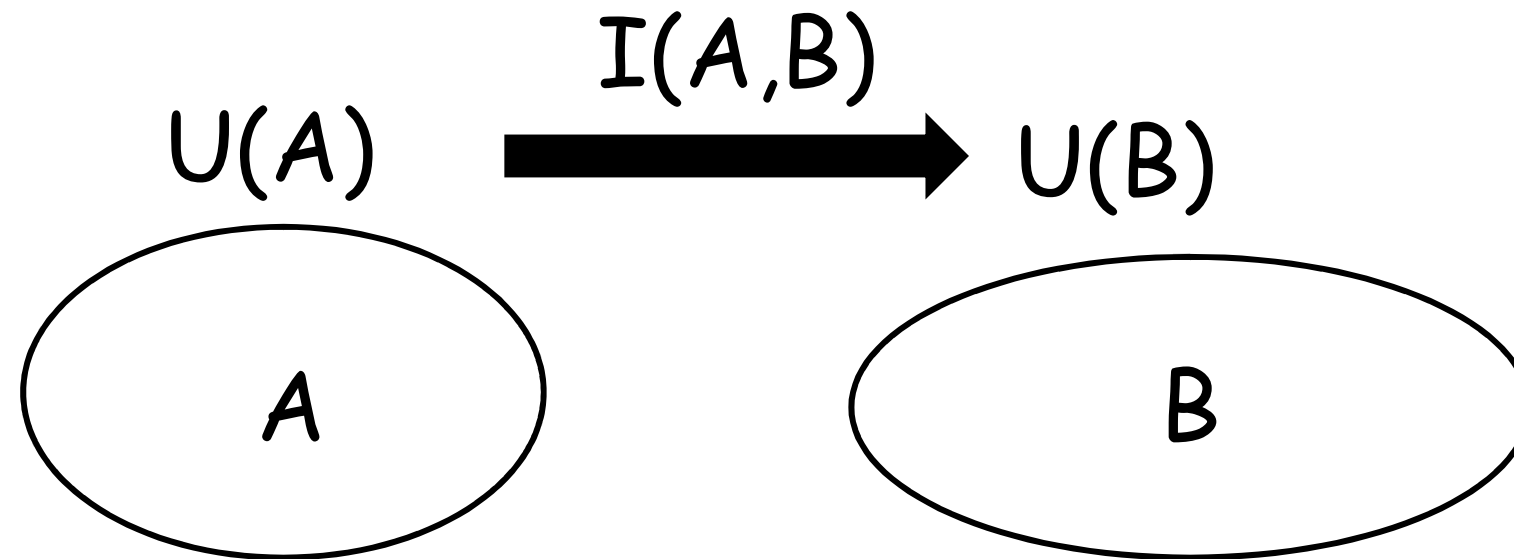
$|S|$  is the cardinality of  $S$ ;

$a$  and  $b$  are positive constants ( $a > 0$ ,  $b > 1$ ) that determine the unit of measure of uncertainty.



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## Information Theory-based Uncertainty measures



$$I(A,B) = U(A) - U(B) = \log_2(|A|/|B|)$$

$$|B| = 1 \longrightarrow I(A,B) = \log_2(|A|) = U(A)$$



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**Uncertainty as Information associated with a message  $x_k$ :**

$$I_k = -\log_2 P\{x_k\}, \quad (\text{Shannon, 1948})$$

where  $P\{x_k\}$  is the probability associated with the selection of the message  $x_k$ . The average

**Information (Uncertainty) is:**

$$H = -\sum_{k=1}^n P\{x_k\} \log_2 P\{x_k\} \quad \text{Shannon entropy}$$



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## Possibility Theory

Given a set  $X$  and its Power set  $\mathcal{P}(X)$ , a Possibility distribution is a function

$$r: X \rightarrow [0,1]$$

the Possibility measure is

$$\text{Poss}(A) = \max_{x \in A} r(x) \quad \forall A \in \mathcal{P}(X)$$

and the Necessity measure is

$$\text{Nec}(A) = 1 - \text{Poss}(\text{not } A)$$

With the following axioms:

Axiom 1:  $\text{Poss}(\emptyset) = 0$

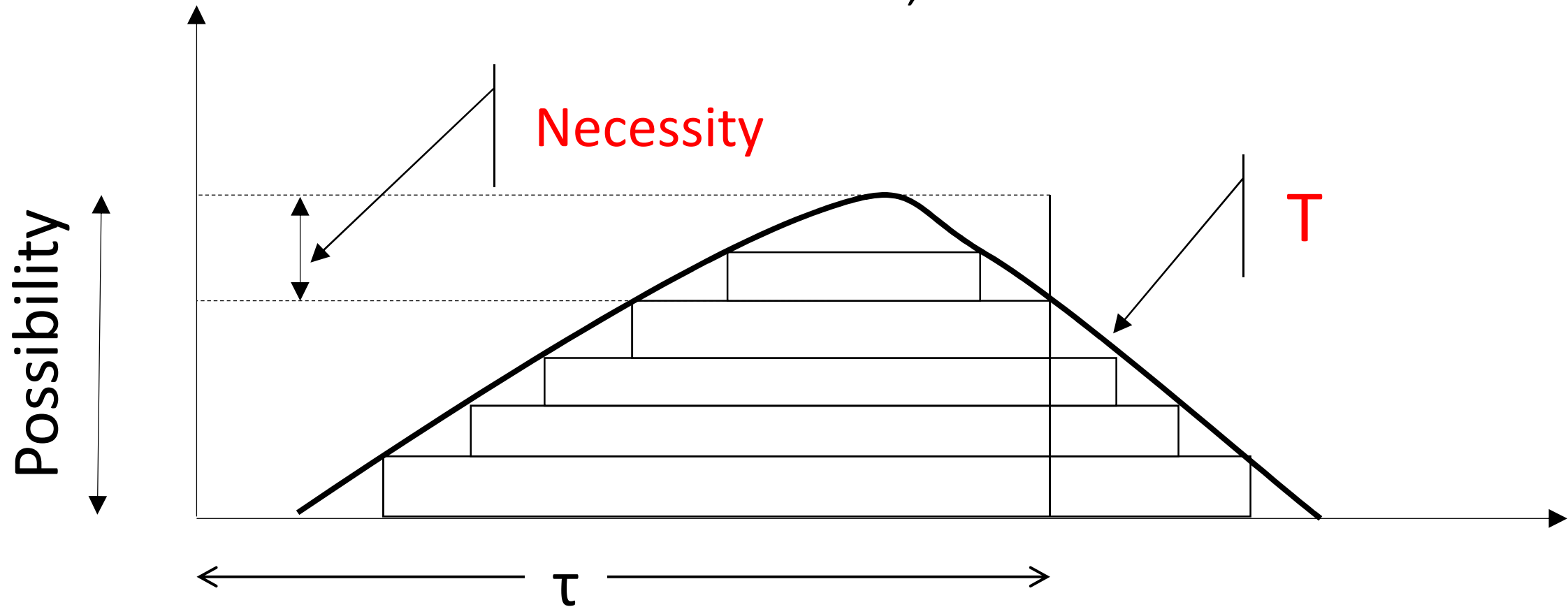
Axiom 2:  $\text{Poss}(X) = 1$

Axiom 3:  $\text{Poss}(U \cup V) = \max(\text{Poss}(U), \text{Poss}(V))$  for any disjoint subsets  $U$  and  $V$ .



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$x$  is  $A$ : in this case,  $\tau = x$  and  $A = \ll\text{less than } T\gg$

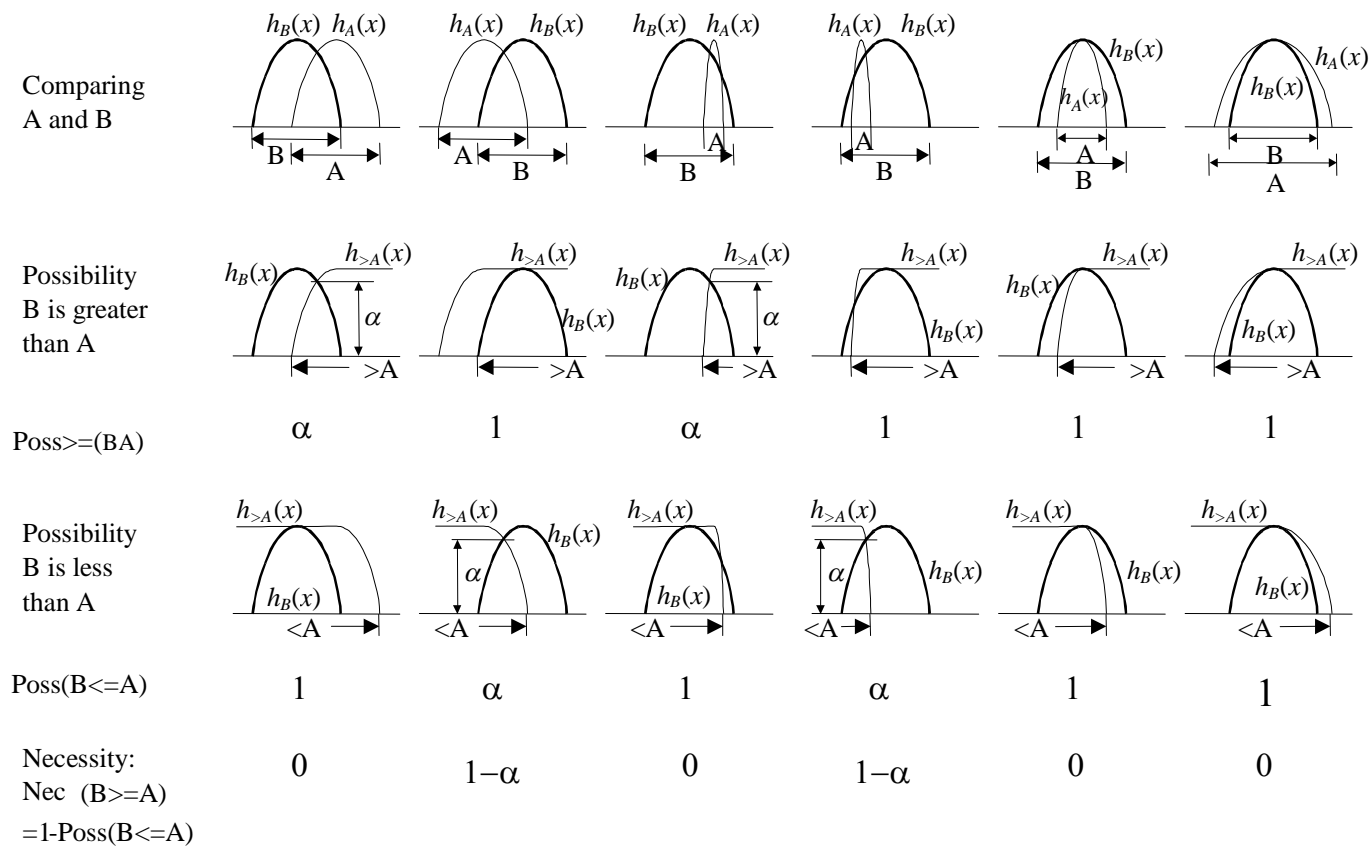






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$$\text{Poss}(B \geq A) = \text{Max Min} (\text{Poss}_B(x), \text{Poss}_{\geq A}(x)) \text{ for } x \in X$$



Note: h = Poss



## Handling Uncertainty as a Human Factor in Transportation Problems

$$\text{Poss}(A \cup B) = \max \{ \text{Poss}(A), \text{Poss}(B) \}$$

$$\text{Nec}(A \cap B) = \min \{ \text{Nec}(A), \text{Nec}(B) \}$$



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## U-Uncertainty

$$U(A) = \sum_{i=2}^n \log_2(i) \cdot [Poss(x_i) - Poss(x_{i+1})]$$

with  $Poss(x_1) = 1$ ,  $Poss(x_{n+1}) = 0$  by convention



# Handling Uncertainty as a Human Factor in Transportation Problems

Principle of Uncertainty Invariance:

$$H = U$$

$$\begin{aligned} & -\sum_{i=1}^n P(x_i) \cdot \log_2 P(x_i) \\ = & \sum_{i=2}^n \log_2(i) \cdot [Poss(x_i) - Poss(x_{i+1})] \end{aligned}$$



# Handling Uncertainty as a Human Factor in Transportation Problems

- Probabilistic normalization:

$$\sum_{k=1}^n P(x_k) = 1$$

- Possibilistic normalization

$$\text{Max}(\text{Poss}(x_i)) = 1$$



## Handling Uncertainty as a Human Factor in Transportation Problems

- The log-interval scale transformation has the form:

$$Poss(x_i) = \beta \cdot P(x_i)^\alpha \quad i = 1, 2, \dots, n$$

where  $\alpha$  and  $\beta$  are positive components.

From probabilistic normalization, we obtain  $\beta^{1/\alpha} = \sum_i Poss(x_i)^{1/\alpha}$  and then, with  $\gamma = 1/\alpha$ :

$$P(x_i) = \frac{Poss(x_i)^\gamma}{\sum_{i=1}^n Poss(x_i)^\gamma}$$



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$$-\sum_{k=1}^n \frac{Poss(x_k)^\gamma}{\sum_{i=1}^n Poss(x_i)^\gamma} \log_2 \frac{Poss(x_k)^\gamma}{\sum_{i=1}^n Poss(x_i)^\gamma} = \sum_{i=2}^n \log_2(i) \cdot [Poss(x_i) - Poss(x_{i+1})]$$



# Handling Uncertainty as a Human Factor in Transportation Problems

## AN EXAMPLE

### MODELLING PARKING CHOICE BEHAVIOUR USING POSSIBILITY THEORY





# MODELLING PARKING CHOICE BEHAVIOUR USING POSSIBILITY THEORY

The generalised cost for the parking facility  $j$  is defined as:

$$PFC_j = c_j + m_j \cdot \frac{1}{\alpha}$$

Where:

$$c_j = TV_{o,j} + TR_j + CT_{j,d}$$

$$m_j = \begin{cases} 0 & \text{for free parking} \\ MU \cdot [\min(1, FC_j \cdot DS_j)] & \text{for illegal parking} \\ TAR_j \cdot \text{minimum integer} \geq DS_j & \text{for charged parking} \end{cases}$$

$DS_j$  = dwell time (hours)

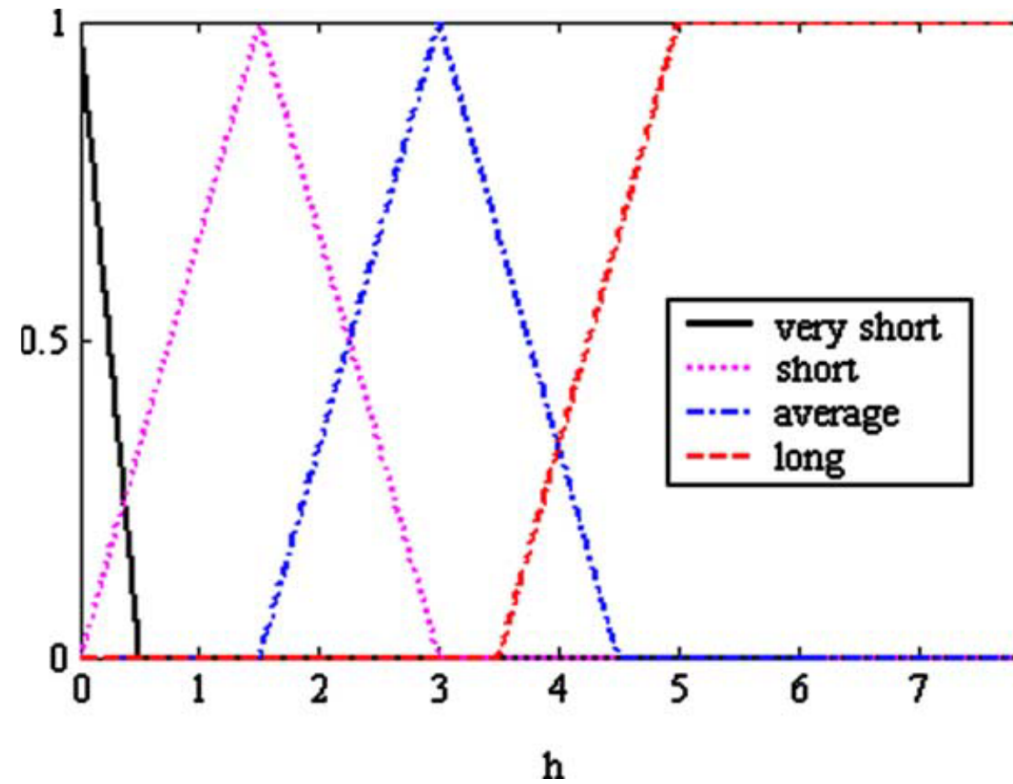


# MODELLING PARKING CHOICE BEHAVIOUR USING POSSIBILITY THEORY

| Scenario | TAR (€/h) | MU (€) | DS      | FC      |
|----------|-----------|--------|---------|---------|
| 1        | 1         | 50     | short   | weak    |
| 2        | 1         | 50     | average | average |
| 3        | 1         | 50     | average | strong  |



# MODELLING PARKING CHOICE BEHAVIOUR USING POSSIBILITY THEORY

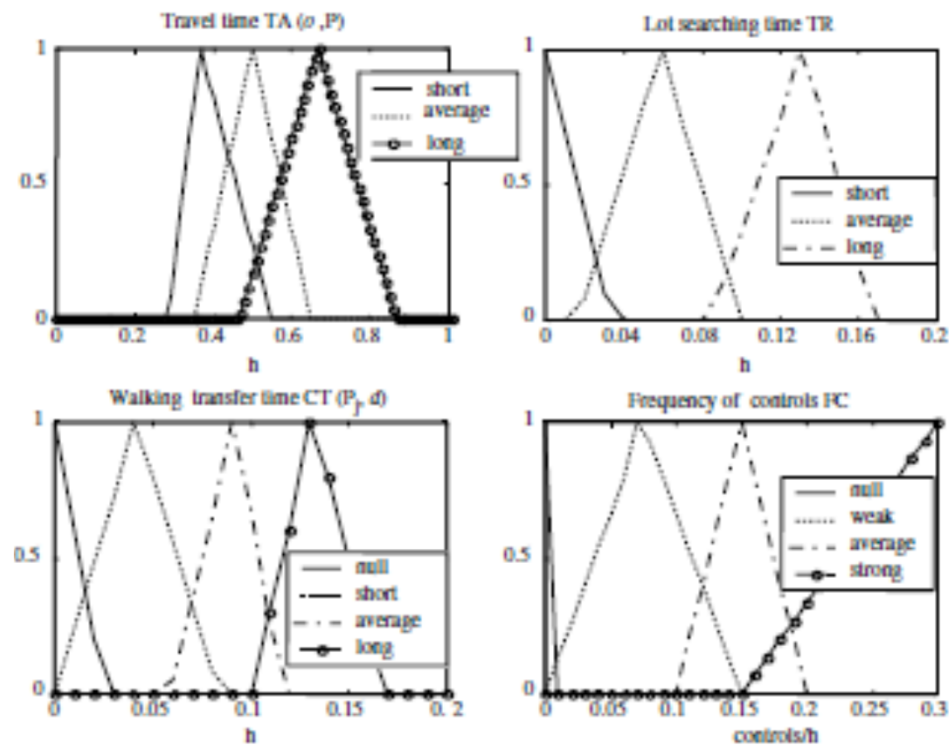


Possibility values for 'Dwell Time' (DS)



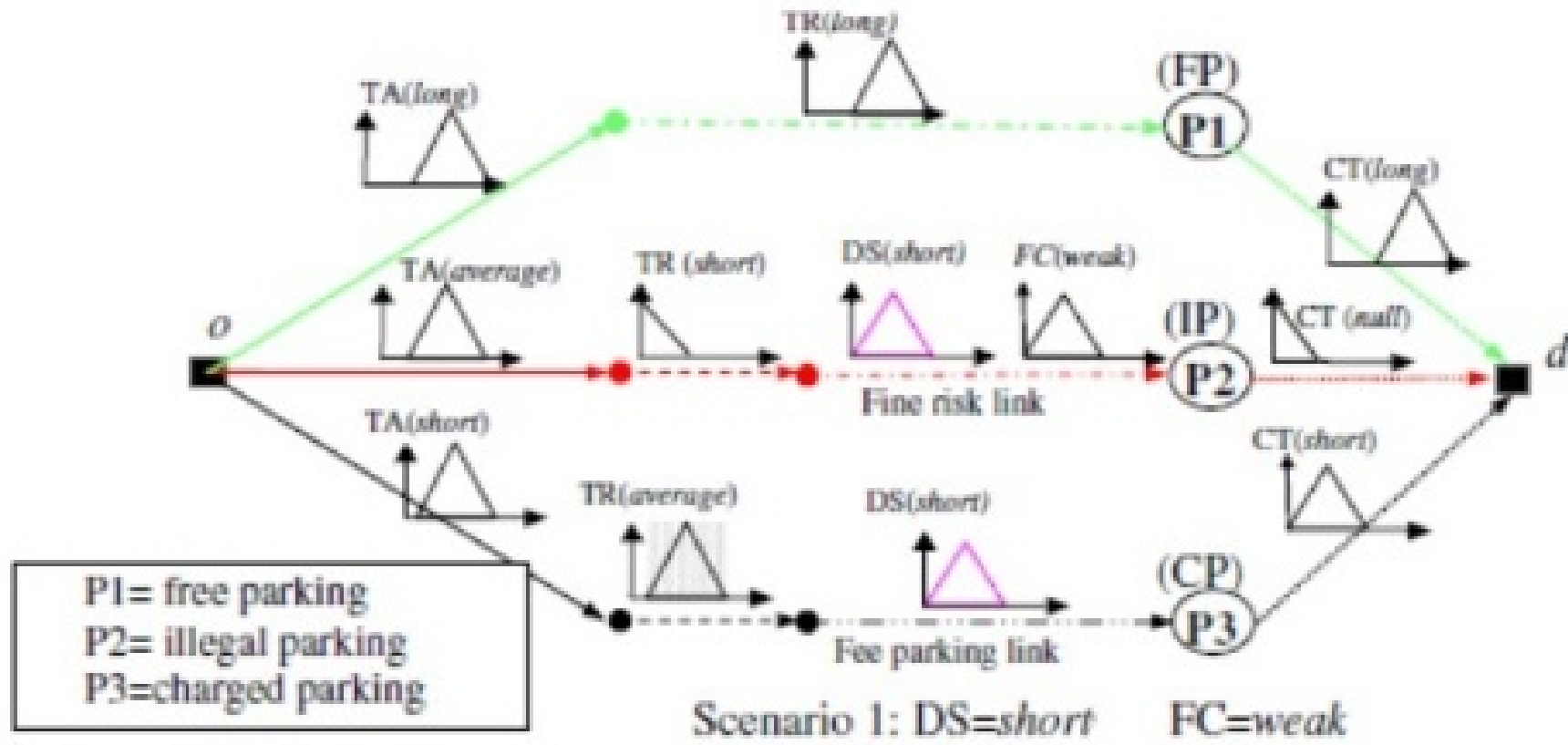
# MODELLING PARKING CHOICE BEHAVIOUR USING POSSIBILITY THEORY

- Values of the perceived costs





# Handling Uncertainty as a Human Factor in Transportation Problems





# MODELLING PARKING CHOICE BEHAVIOUR USING POSSIBILITY THEORY

|                   | Scenario    |             |             |
|-------------------|-------------|-------------|-------------|
| Parking facility  | 1           | 2           | 3           |
| 1 free parking    | 0.06 (0.56) | 0.19 (0.89) | 0.32 (0.89) |
| 2 illegal parking | 0.55 (1.00) | 0.28 (0.93) | 0.10 (0.74) |
| 3 charged parking | 0.39 (0.92) | 0.53 (1.00) | 0.58 (1.00) |



## Handling Uncertainty as a Human Factor in Transportation Problems

- **Conclusions**

In my opinion, the Possibility Theory and the Fuzzy Set Theory are not a «cure-all» for whichever problem. There are two level of analysis: the level of the analyst , who knows statistics and probability calculations; and the level of the decision-makers, who often ignore average, standard deviation, probabilities etc.. They make decision on the basis of approximate reasonings, of their information and uncertainty about the problem. Thus, when dealing with models of decision-makers' behavior, I believe that the Possibility Theory and the Fuzzy Set Theory show all their potential



# Handling Uncertainty as a Human Factor in Transportation Problems

**Knowing ignorance is strength.  
Ignoring knowledge is sickness.**

Tao Te Ching  
by Lao Tzu



Thank you!

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