



Panel on

Services in Smart Cities: All  
about Security, Mobility and  
Autonomy



## Moderator and Panelists

### Panel Moderator

**Kevin Daimi**, University of Detroit Mercy, USA

### Panelists

**Antonio José Ribeiro Neves**, University of Aveiro, Portugal

**Irina Topalova**, Technical University Sofia, Bulgaria

**Petre Dini**, IARIA, USA

**Kevin Daimi**, University of Detroit Mercy



## Topics

- Smart Cities Security (**Kevin Daimi**)
- Autonomous Agents in Smart Cities (**Antonio José Ribeiro Neves**)
- Implementation and Impact of Artificial Intelligence on Smart Cities. (**Irina Topalova**)
- Mobility as a service: crowd mobility, vehicular flow, and mobility-driven energy balancing (**Petre Dini**)

# Questions that will be answered

- How can mobility-as-a-service cover the spectrum of mobility facets?
- What is the impact of mobility on the energy systems?
- Is the population sufficiently and culturally aware to embrace mobile (self-driving) entities?
- What are the possible areas for improving the AI applications in TMT and achieving high efficiency?
- What are the main challenges of autonomous vehicles in current cities?
- How will smart cities deal with (and accelerate) the use of autonomous vehicles?
- Are smart cities secure?

# Implementation and Impact of Artificial Intelligence over Smart Cities

Artificial Intelligence to transform TMT  
(Technology, Media and Telecoms) smart  
cities

# Smart cities

The United Nations' World Cities Report predicts that by 2050 over 70% of the world's population will be living and working in cities.

A smart city is characterised by the integration of technology into a strategic approach to

sustainability,

citizen well-being and

economic development.”

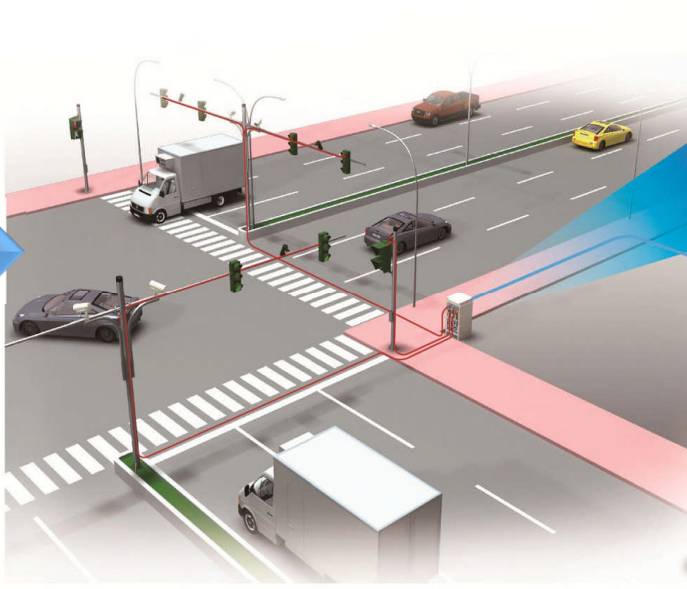
(According to *Scoring methodology, Juniper Research, 2017*)

**advanced technologies, such as IoT** (Internet of Things: physical devices that are connected with each other and the Internet) to improve their operations and services.

**These services are often based on intelligent automation (PLCs)** – designed to control all services, the communication between end sensors and actuators).

**ort:** *How connected and efficient are the services?*

*city gathering data from real-time traffic monitoring and using this data to adjust flow, based on emergency response requirements?*



NPort IA5150A-T



EDS-205A-T

Ethernet



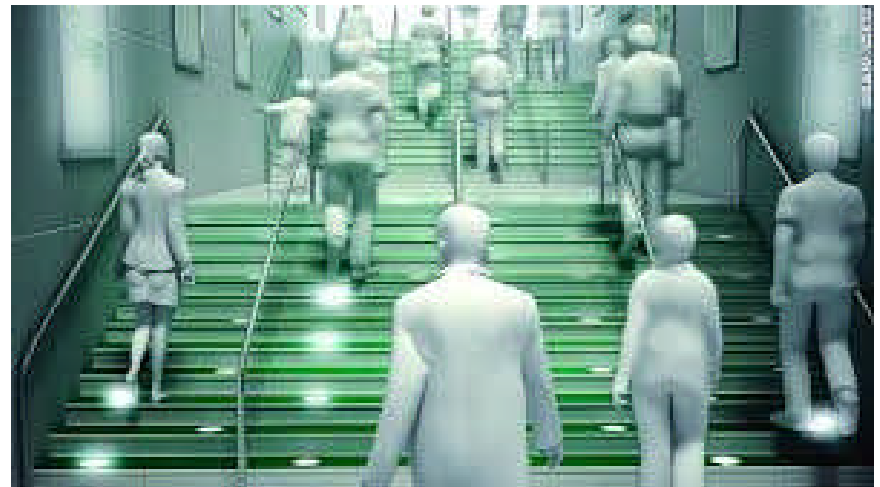
Traffic Management Center



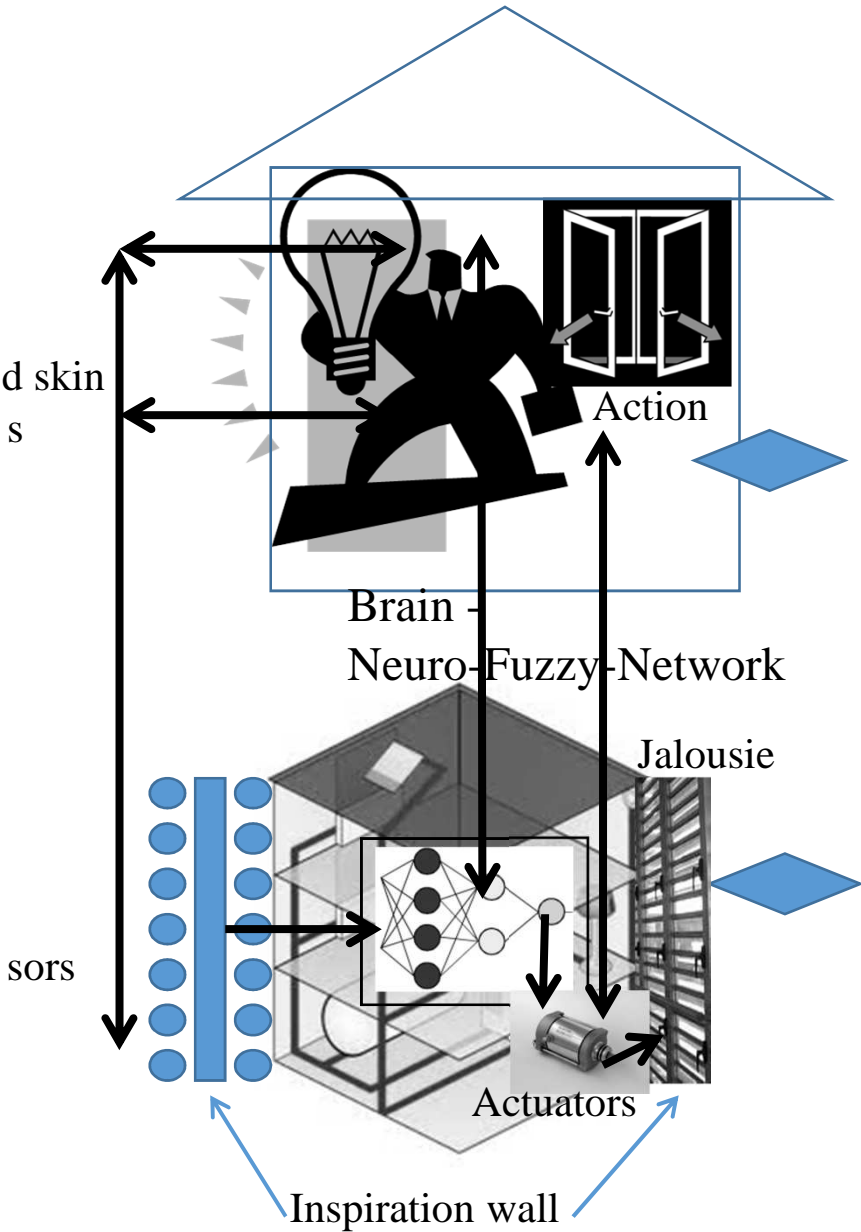
**Public Safety:** Is intelligent video surveillance analytics or predictive crime and fire risk software being used?

**Energy Sectors:** Is the city applying technologies, such as Artificial intelligence controlled *smart traffic light systems*,  
some energy storage solutions, solar panels etc.?

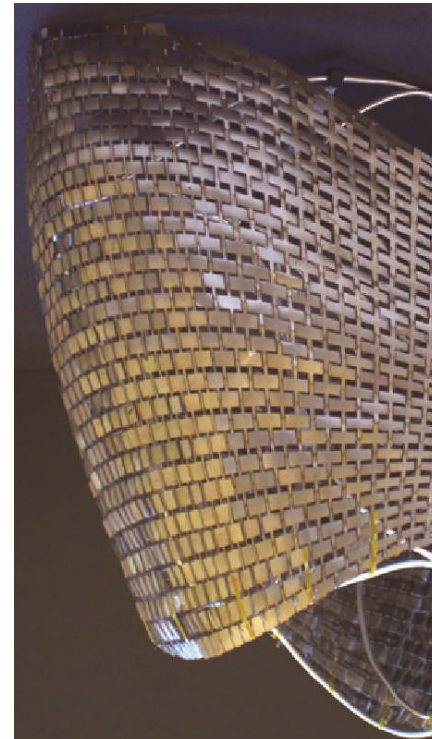
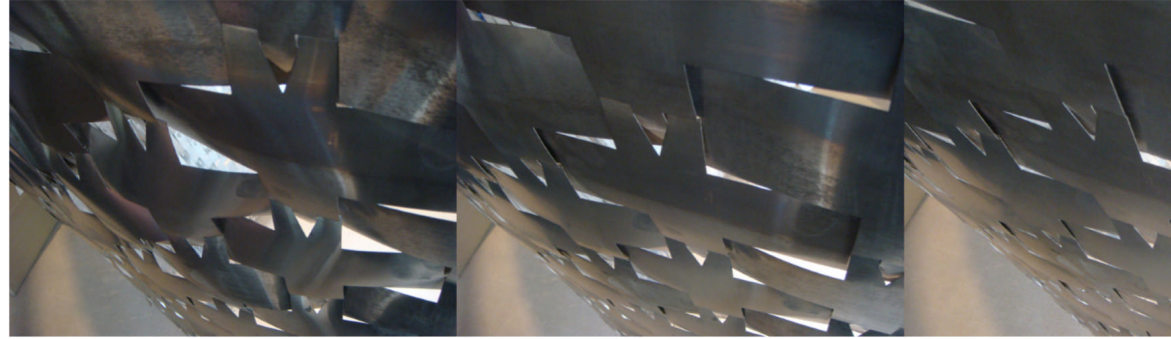
**Smart Pavements** – set on the most busiest/crowded areas



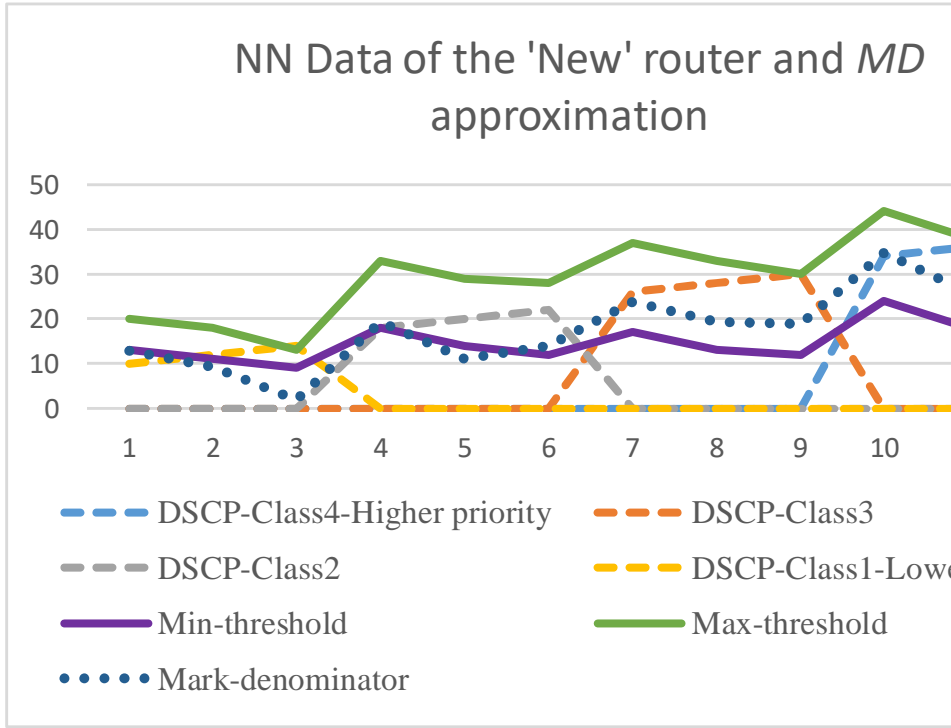
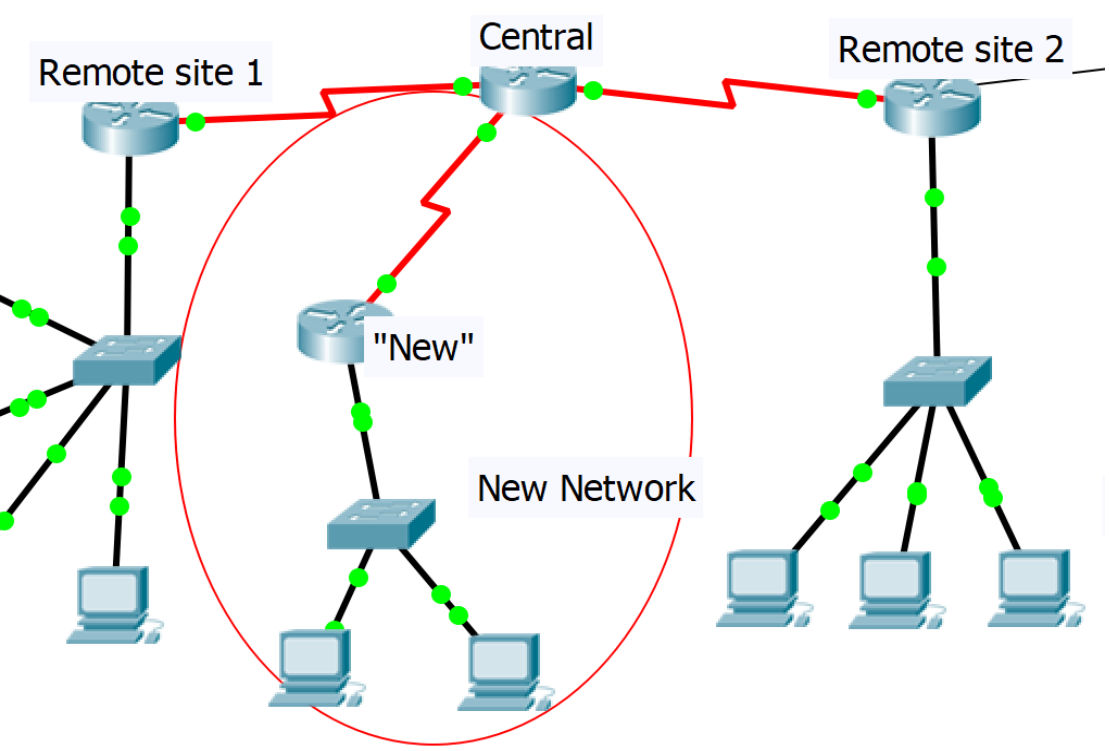
# ding and architecture area



Doris Kim Sung - University of Southern California  
bimetal thermal plates for "self ventilation skin of the building"



munication area – for traffic prediction and congestion avoidance



he Technology, Media and Telecoms (TMT) industry will be one  
the first to be transformed.

Over the next three to five years, the combination of AI  
and 5G will power the emergence of a new  
generation of devices that  
*will redefine the word 'smart' by differing from today's.*

**Key areas for improvement in the application of AI in TMT, aimed at increasing efficiency?**

Too many end users and need for increasing the calculation power  
**Reconfigurable Chips** – potentially capable of **accelerating Machine Learning**  
)

Work on implementing **AI in the human-machine interface** – include **voice recognition, gestures, emotions**.

Implementation of **AI in API** (Application Programming Interface)-

*Automating the process of **discovering APIs***

*Machine behaviour prediction in **machine-machine communication**  
(**Machine-to-PLC**)*

m industrial machinery to  
munication,

lets innovators reimagine the art of  
possible and enable decision-  
making that is better and faster — and  
ed on vastly more information.

e outcome for the industry will be a  
rld that's very different from today  
but which is already taking shape  
und us.



the past



Voice control



Even during a home off-duty w



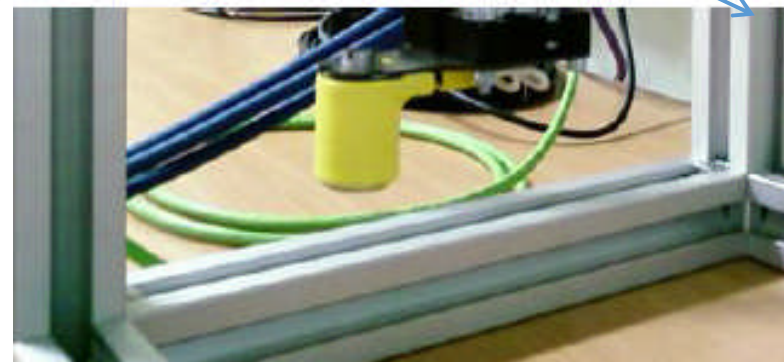
ently, the focus of AI in many industries is on developing techniques such as *deep*

*g, natural language processing.*

ng *need for advanced computing power* — probably from quantum computing

r further understanding of *more advanced cognitive and emotional responses* an

(Programmable Logic Controller)  
good method for controlling any  
ustrial processing but it did not  
e full picture about this process in  
time.  
ral network can make a survey on  
process at all time. Learning NNs  
expect the next instruction of the  
ustrial operation before applying  
input signal controlling.

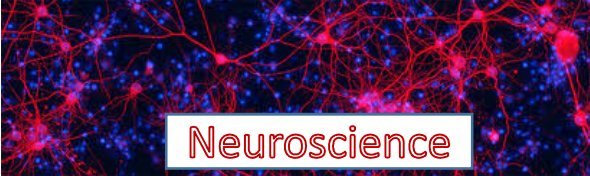




before

PC

PLC

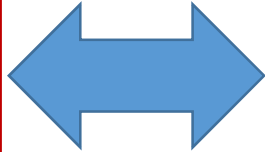


Neuroscience

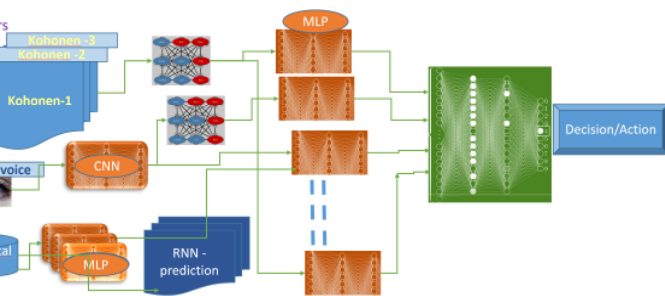


Acquisition of the environment

Action / Change the environment

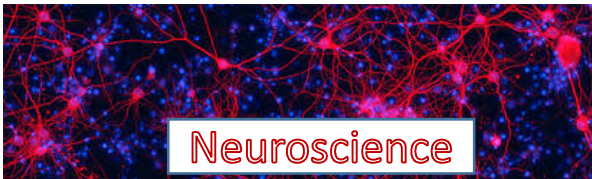


!



today

PLC



Acquisition of the environment

Processing      Train / Decision

Action / Change the environment

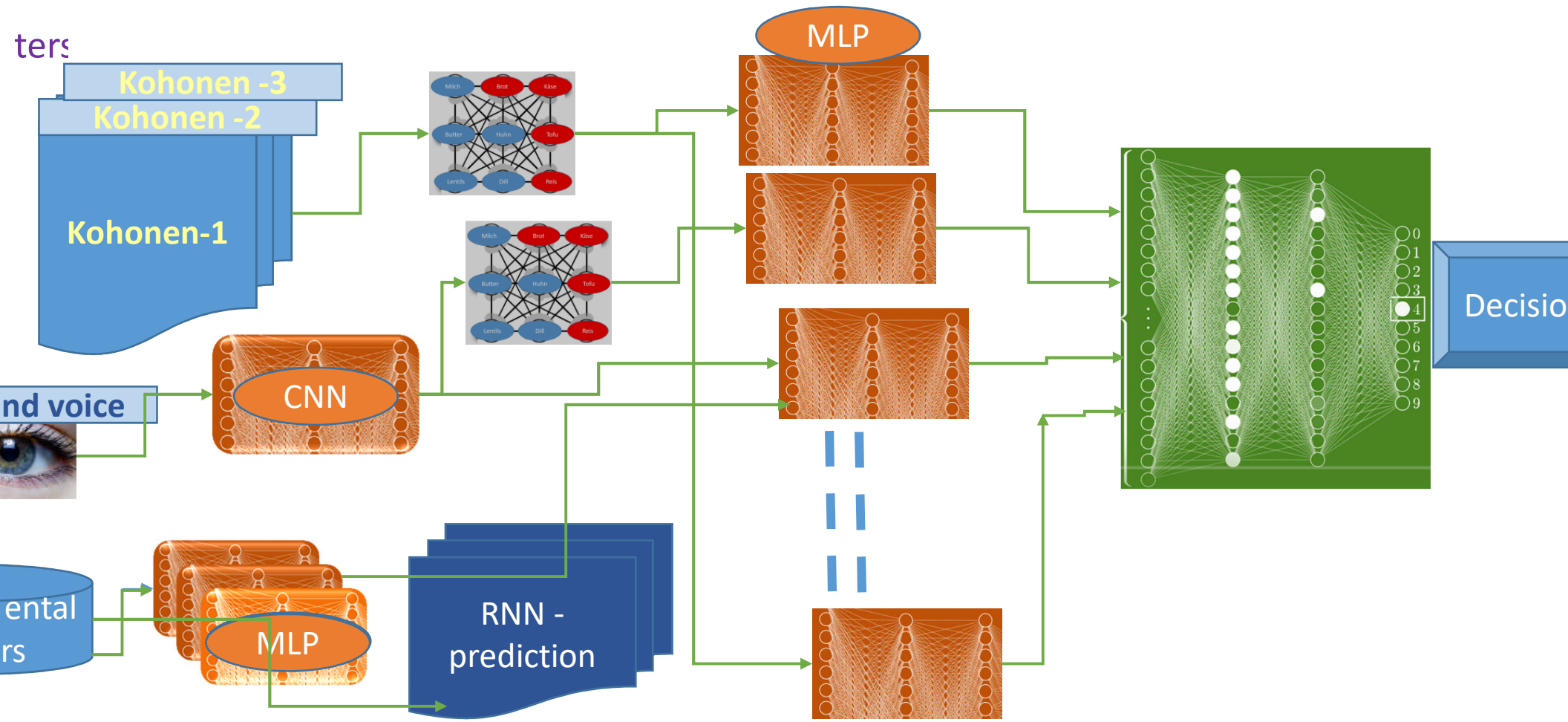


Data base / Knowledge



!

different types of NNs to solve individual subtasks  
fed in a network for making a final decision



# demonstration – AI – MLP Neural Network in a PLC – make decision in real-time

The screenshot shows the SIMATIC Manager interface with a ladder logic program for a temperature control system. A dialog box titled "PLC Asynchronous DB Writer" is open, displaying a table of data for DB1. The dialog includes settings for file path, rows, columns, and PLC parameters.

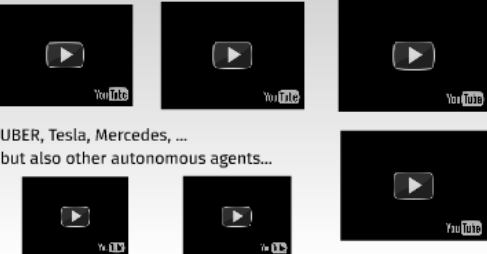
	1	2	3	4	5	6	7
1	0.0000	0.0000	0.0000	0.0001	0.0044	0.0069	0.0063
2	0.0000	0.0000	0.0000	0.0000	0.0002	0.0017	0.0010
3	0.0000	0.0000	0.0000	0.0000	0.0021	0.0043	0.0047
4	0.0000	0.0000	0.0000	0.0000	0.0017	0.0035	0.0056
5	0.0000	0.0016	0.0021	0.0029	0.0176	0.0109	0.0171
6	0.0000	0.0000	0.0000	0.0010	0.0026	0.0066	0.0069
7	0.0000	0.0000	0.0015	0.0043	0.0116	0.0152	0.0163
8	0.0000	0.0002	0.0011	0.0032	0.0079	0.0129	0.0141
9	0.0449	0.0410	0.0440	0.0019	0.1507	0.1732	0.1906
10	0.0000	0.0024	0.0273	0.0783	0.1393	0.1942	0.2265
11	0.0007	0.0021	0.0497	0.0869	0.1396	0.1776	0.2006
12	0.0001	0.0150	0.0440	0.0076	0.1406	0.1047	0.2069
13	0.0000	0.0004	0.0083	0.1950	0.5725	0.2810	0.0326
14	0.0000	0.0000	0.0000	0.0352	0.8087	0.3176	0.1022
15	0.0000	0.0000	0.0007	0.0062	0.7726	0.2999	0.0960
16	0.0000	0.0000	0.0001	0.0029	0.7090	0.2951	0.0900
17	0.0000	0.0001	0.0005	0.0018	0.0033	0.0039	0.0048
18	0.0000	0.0000	0.0000	0.0000	0.0001	0.0005	0.0014
19	0.0000	0.0000	0.0001	0.0005	0.0015	0.0020	0.0040
20	0.0000	0.0000	0.0000	0.0002	0.0009	0.0020	0.0031
21	0.0438	0.0272	0.0290	0.0545	0.3779	0.1090	0.1138
22	0.0000	0.0177	0.0300	0.0443	0.0642	0.0914	0.1026
23	0.0055	0.0253	0.0340	0.0473	0.0754	0.0977	0.1076
24	0.0046	0.0042	0.0021	0.0472	0.0724	0.0986	0.1064
25	0.0001	0.0002	0.0005	0.0015	0.0029	0.0049	0.0063
26	0.0000	0.0000	0.0000	0.0000	0.0004	0.0010	0.0030
27	0.0000	0.0000	0.0001	0.0007	0.0021	0.0035	0.0044

The screenshot shows a ladder logic network diagram with three networks. Network 1 shows a normally open contact labeled "FB101" connected to a coil labeled "M300.1". Network 2 shows a normally open contact labeled "M300.1" connected to a coil labeled "M1.2". Network 3 shows a normally open contact labeled "M300.1" connected to a coil labeled "M1.2".

**Talk About Self-Driving Cars**



**Autonomous cars...**



UBER, Tesla, Mercedes, ...  
but also other autonomous agents...

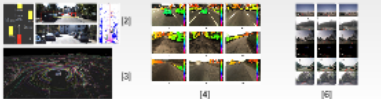
**Scientific state of the art - Autonomous cars**

- [1] Thrun, S. et al. (2006). Stanley: The Robot that Won the DARPA Challenge. *Journal of Field Robotics*, 8, 239, 9-692-992.
- [2] Was, J., Snelter, J. M., Kim, J., Dubai, J. M., Rajkumar, R., & Likhovih, R. (2013, June). Towards a viable autonomous driving research platform. In *Intelligent Vehicles Symposium (IV)*, 2013 IEEE. (pp. 762-770). IEEE.
- [3] Doherty, P. and Fiegels, L. (2012) "The BRAVE platform", in *Proc. 7th IFAC Symposium on Intelligent Autonomous Vehicles*, Lonze, Italy.
- [4] Bertozzi, M., Bontempi, L., Broggi, A., Buzzoni, M., Cardarelli, E., Cattani, S., ... & Otti, L. (2015, October). The vinci intercontinental autonomous challenge: 13,000 km, 3 months, no driver. In *Proc. 17th World Congress on ITS*, Busan, South Korea.
- [5] V. Santos et al., "ATLASCAR - technologies for a computer assisted driving system on board a concrete submarine", 13th International IEEE Conference on Intelligent Transportation Systems, Funchal, 2010, pp. 1421-1427.
- [6] Oliveira, M., & Santos, V. (2011). Autonomous driving competition: Perception approaches used in the atlas project. In *Proc. of Int. Conf. on Autonomous Robot Systems and Applications*, Lisboa.
- [7] Jin, K., Kim, J., Kim, D., Jung, C., & Surwoo, M. (2016). Development of Autonomous Car - Part I: Distributed system architecture and development process. *IEEE Transactions on Industrial Electronics*, 63(12), 7133-7140.
- [8] Y. Ju, J. Nam, D. Kim, C. Jung and M. Surwoo, "Development of Autonomous Car—Part II: A Case Study on the Implementation of an Autonomous Driving System Based on Distributed Architecture," in *IEEE Transactions on Industrial Electronics*, vol. 62, no. 8, pp. 5119-5132, Aug. 2015.



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- [1] Almeida, J., Santos, V. (2015). Pedestrian pose estimation using stereo perception. In *Robot 2015: Second Iberian Robotics Conference* (pp. 491-502). Springer, Cham.
- [2] Chen, C., Saff, A., Kornhauser, A., & Xiao, J. (2015). DeepSf: Learning affordance for direct perception in autonomous driving. In *Proceedings of the IEEE International Conference on Computer Vision* (pp. 2722-2730).
- [3] Azim, A., & Aycaud, O. (2012, June). Detection, classification and tracking of moving objects in a 3D environment. In *Intelligent Vehicles Symposium (IV)*, 2012 IEEE. (pp. 802-807).
- [4] Broggi, A., Buzzoni, M., Felka, M., & Zani, P. (2011, September). Stereo obstacle detection in challenging environments: the VIAC experience. In *Intelligent Robots and Systems (IROS)*, 2011. IEEE/RSJ International Conference on (pp. 1039-1044).
- [5] Pinto, P., Tomé, A., & Santos, V. (2015, April). Visual detection of vehicles using a bag-of-features approach. In *Autonomous Robot Systems (Robotical)*, 2015 13th International Conference on (pp. 1-4).
- [6] Jung, S., Yoon, J., & Suk, S. (2015). Efficient Lane Detection Based on Spatiotemporal Images. *IEEE Transactions on Intelligent Transportation Systems*, PP(99), 1-7.



**Recent autonomous driving projects**



# Autonomous mobile agents in smart cities

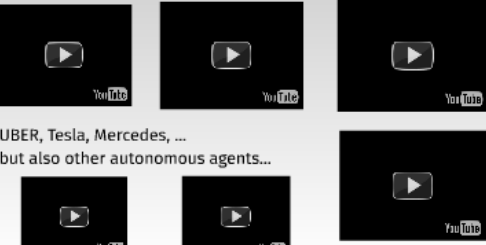
António F. R. Neves  
 (an@ua.pt)

SIGNAL 2018  
 Nice, France

**Talk About Self-Driving Cars**



**Autonomous cars...**



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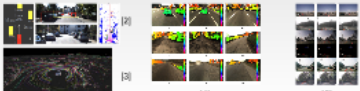
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**Recent autonomous driving projects**

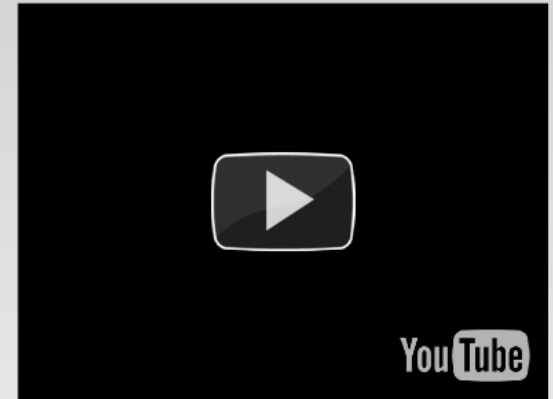
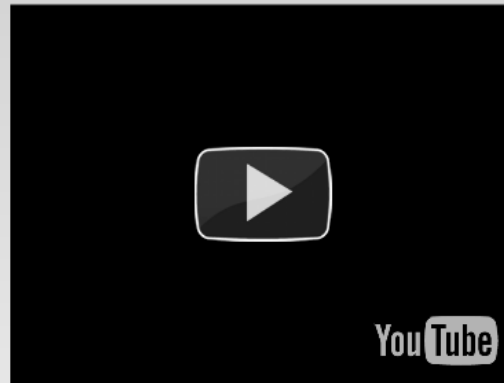


# Autonomous mobile agents in smart cities

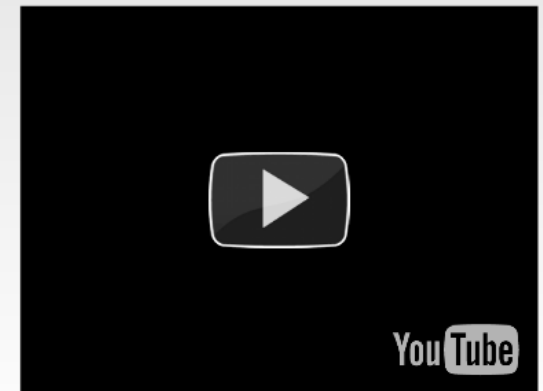
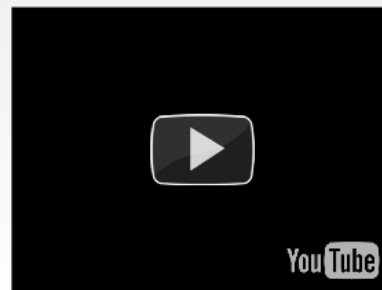
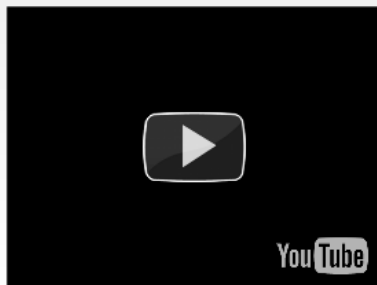
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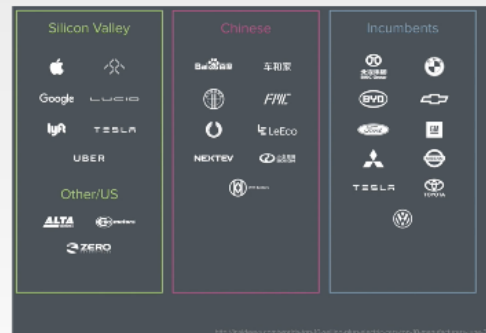
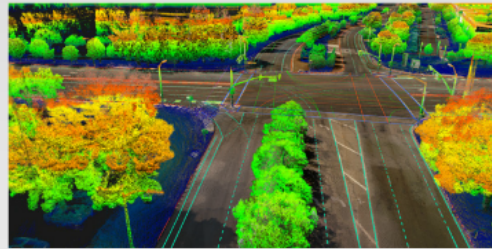
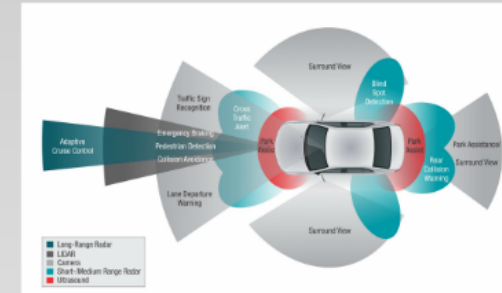
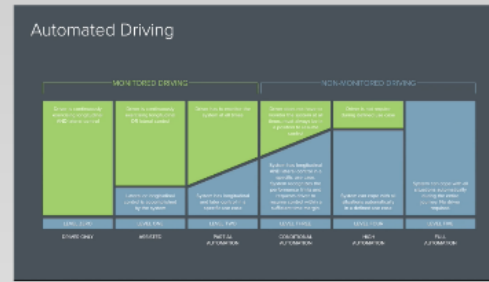
## Autonomous cars...



UBER, Tesla, Mercedes, ...  
but also other autonomous agents...



# Talk About Self-Driving Cars



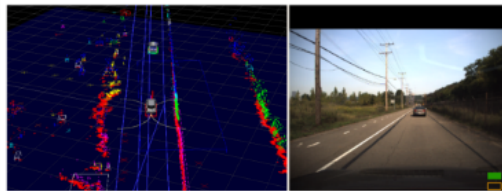


# Recent autonomous driving projects

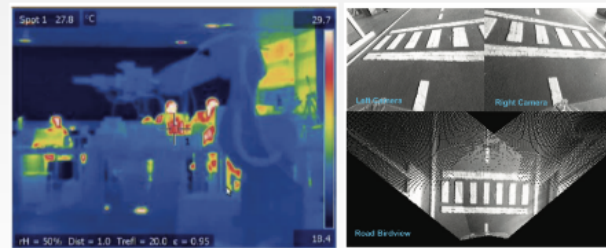


# Scientific state of the art - Autonomous cars

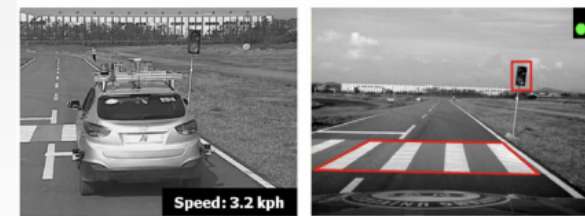
- [1] Thrun, S. et al. (2006). Stanley: The Robot that Won the DARPA Challenge. Journal of Field Robotics. n. 23(9), p.661–692.
- [2] Wei, J., Snider, J. M., Kim, J., Dolan, J. M., Rajkumar, R., & Litkouhi, B. (2013, June). Towards a viable autonomous driving research platform. In Intelligent Vehicles Symposium (IV), 2013 IEEE (pp. 763-770). IEEE.
- [3] Grisleri, P. and Fedriga, I. (2010) 'The BRAiVE platform', in Procs. 7th IFAC Symposium on Intelligent Autonomous Vehicles, Lecce, Italy.
- [4] Bertozzi, M., Bombini, L., Broggi, A., Buzzoni, M., Cardarelli, E., Cattani, S., ... & Gatti, L. (2010, October). The vislab intercontinental autonomous challenge: 13,000 km, 3 months, no driver. In Proc. 17th World Congress on ITS, Busan, South Korea.
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- [8] K. Jo, J. Kim, D. Kim, C. Jang and M. Sunwoo, "Development of Autonomous Car—Part II: A Case Study on the Implementation of an Autonomous Driving System Based on Distributed Architecture," in IEEE Transactions on Industrial Electronics, vol. 62, no. 8, pp. 5119-5132, Aug. 2015.



[2]



[5]



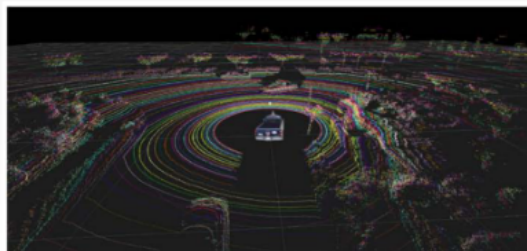
[8]

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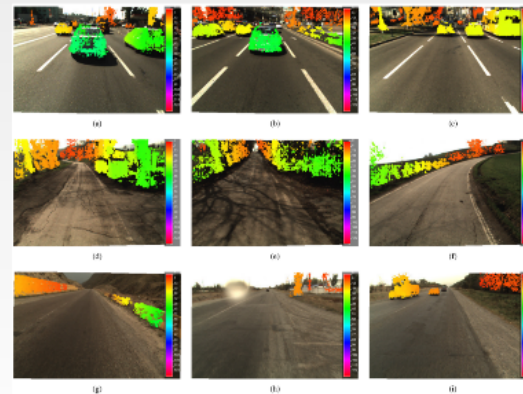
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- [5] Pinto, P., Tomé, A., & Santos, V. (2013, April). Visual detection of vehicles using a bag-of-features approach. In Autonomous Robot Systems (Robotica), 2013 13th International Conference on (pp. 1-4)
- [6] Jung, S., Youn, J., & Sull, S. (2015). Efficient Lane Detection Based on Spatiotemporal Images. IEEE Transactions on Intelligent Transportation Systems, PP(99), 1–7.



[2]



[3]



[4]



[6]



## Panel on ICAS/ICNS

# Services in Smart Cities: All about Security, Mobility and Autonomy

## On Mobility

Petre Dini, IARIA, USA

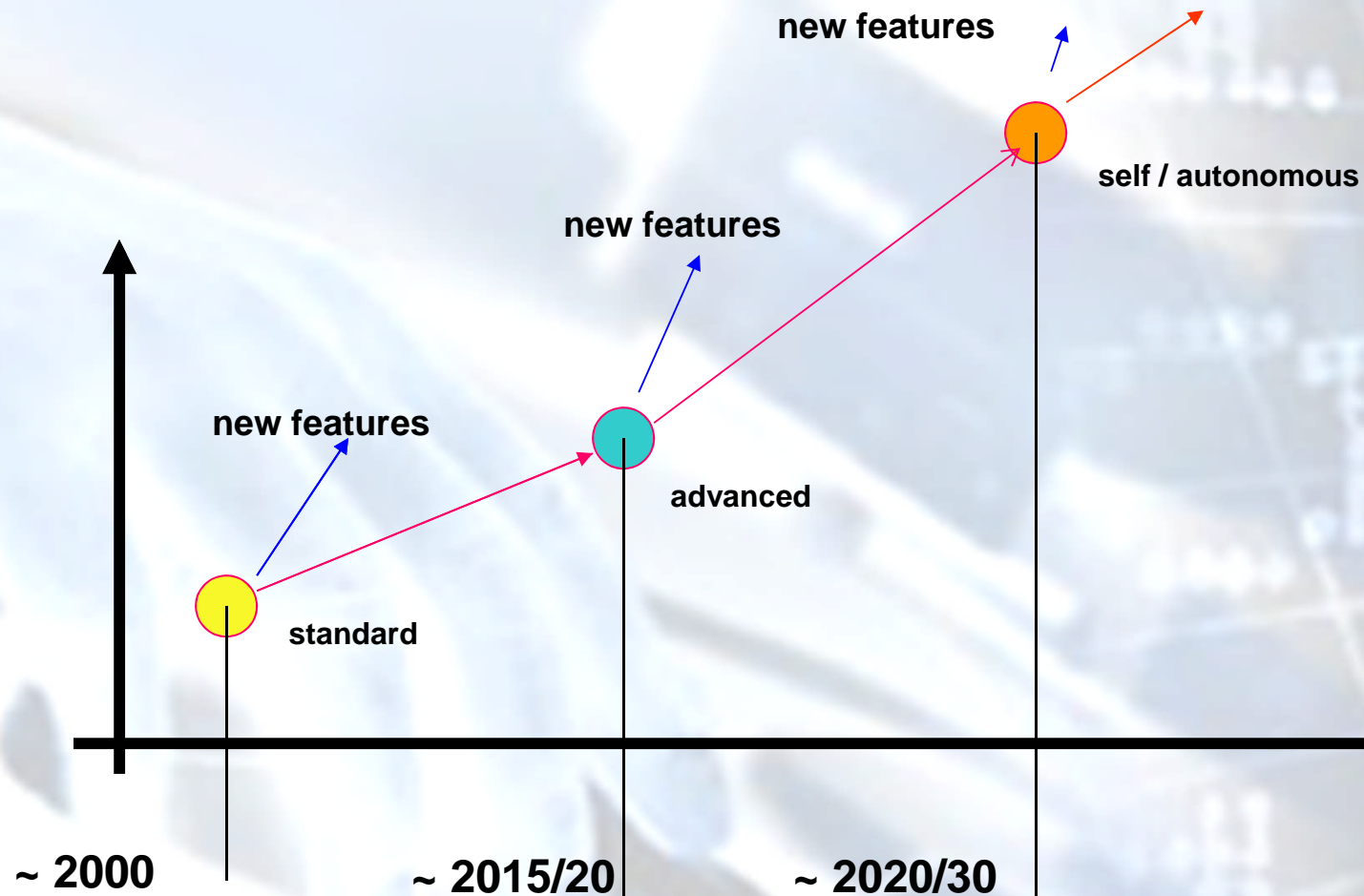
[petre@iaria.org](mailto:petre@iaria.org)

Monday, May 21st

InfoSys 2018, May 20-24, 2018 Nice, France

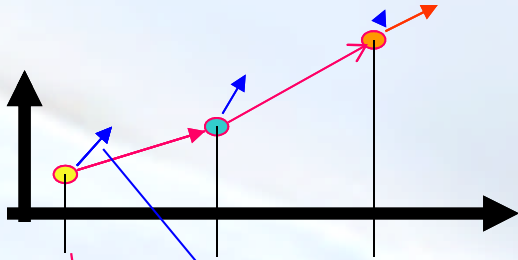


# MOBILITY AS (a FUTURE) REALITY





# Standard



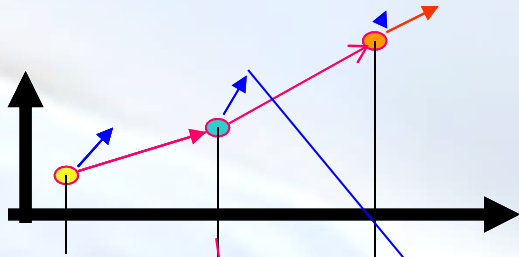
- optimal path, car size, etc.
- rapidity/covered region
- order a taxi
- parking a car

- transportation systems
- fire/health emergency
- waste mgmg
- postal services

- access disable peoples
- uber service
- FedEx
- postal delivery from home
- waste-by-request
- etc.



# Advanced



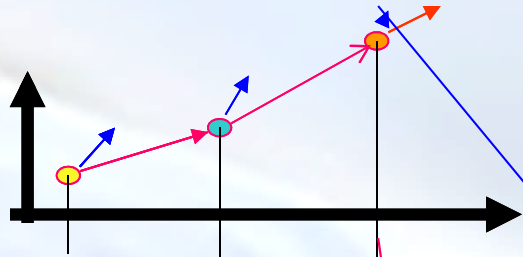
- individual tracking
- children tracking
- self-parking cars
- electrical-based vehicles
- pollution/noise sensing
- waste / weight sensing

- wearable devices
- alarms for elderly peoples
- etc.

- gps-based tracking
- water-plane services
- traffic re-routing
- drone-based delivery
- drove-based surveillance



# Self / autonomous



- real-time pollution metering
- ?
- ?

- on-demand fleet deployment for metering
- ?

- mobile surgery lab
- environmental monitoring services
- on-demand deployment of pollution sensors
- ordering/delivering personalized taxi
- smart transportation | impaired passengers
- self-sizing fleet





# Facets of Mobile Smart Environments (Cites)

- **Urban traffic safety apps** | security/communication
- **Traffic optimizing services** | special algorithms/real-time
- **Localizing street services** (gas, stations, electrical, foods, etc.) | graphics/visual/interfaces
- **Tracking citizen** | elderly | geolocation | geolocaiton in IoT |
- **City service mapping/location** | cartography software | cloud-based services | interactive software | dedicated apps
- **Wearable smart devices** | special screen/interface | special body-related software | body sensing apps | ... chip for monitoring alcohol/drugs
- **Body systems** | special software execution systems | balancing procedures execution/data volumes
- **Sensing and data processing** | data fusion, data mining, pattern recognition
- **Accessibility services** | special interfaces | distributed software for bus/pedestrian/disabled drivers
- **Forecasting services** | databases, datasets, information mining techniques, machine learning
- **Sensing and dissemination info on pollution and noise** | surveillance, alarm systems, optimal traffic rerouting
- **Public services** | waste management |mobile sensing | waste estimation | redirecting services where needed
- **City evolving services/systems** | version software managements, rule-based systems, run-time updates and testing
- **Smart utility control/measurement/payment** | gas + electricity + | special/dedicated networks + software
- **Goods/products delivery** | drones systems
- **Self-driving cars + electric cars** | artificial intelligence + cognitive modeling +
- **etc.** | etc.



## Yet to consider

- **Q1:** How can mobility-as-a-service cover the spectrum of mobility facets?
- **Q2:** What is the impact of mobility on the energetic system?
- **Q3:** Is the population sufficiently and culturally aware to embrace mobile (self-driving) entities?
- **Q4:** What is the drawback on citizen well-being, considering accessibility

**Mobility-as-a-Service** might take advantage from a **Mobility-Platform**, where

- Services are offered and ordered on a personal or corporate basis
- Services are developed, maintained, ... by a Smart-City entity



# Thanks

# Q&A



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Panel on  
Services in Smart Cities: All  
about Security, Mobility and  
Autonomy

**Conclusion**



## Moderator and Panelists

### Panel Moderator

**Kevin Daimi**, University of Detroit Mercy, USA

### Panelists

**Antonio José Ribeiro Neves**, University of Aveiro, Portugal

**Irina Topalova**, Technical University Sofia, Bulgaria

**Petre Dini**, IARIA, USA

**Kevin Daimi**, University of Detroit Mercy

## Panel Conclusion

- Smart cities have complex connectivity infrastructure.
- AI is used to make these cities intelligent
- Autonomous vehicles will be a reality in smart cities infrastructure
- Because of their connectivity and complexity, smart cities will inherit all the currently available security attacks in addition to any specific future attack
- The hardware limitation (speed and memory) makes devices in smart cities unresponsive to a number of security techniques currently used in our computers.