# Low-Power, Long-Range, Precise Localization

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Maarten Weyn

Research:

- ► Localization: from *Opportunistic* to *Just Enough*
- Low-power communication
- Low-power firmware development
- Simultaneous Localization and Mapping

Courses:

- Mobile Communication
- Digital Communication
- Real-Time Localization Systems (Eng)
- Ambient Intelligence (Eng): interaction between low-power communication, sensors, actuators, low-power hardware and algorithms



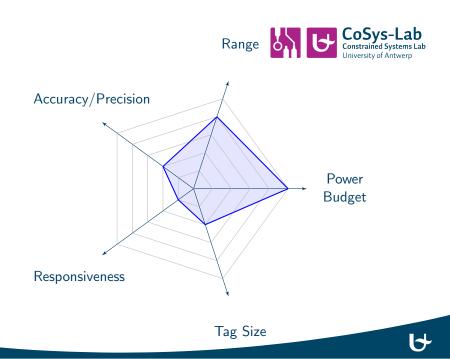
# What I'm not going to do...

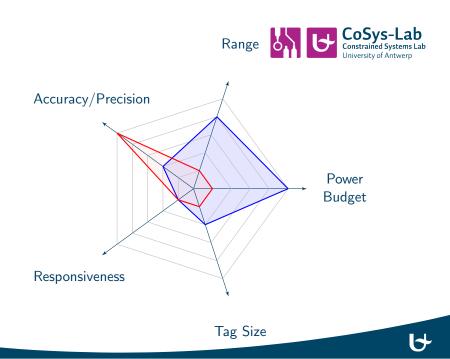
- No sales talk
- No academic formula's and equations
- No futuristic foresights
- ► No "You should's"

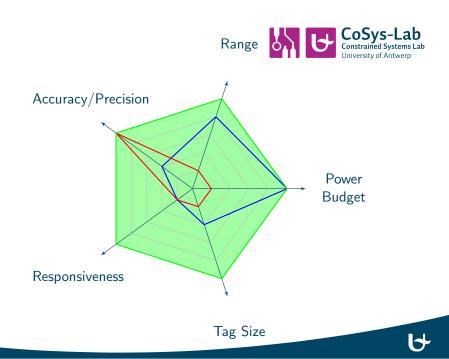


### Low-Power, Long-Range, Precise Localization











# Power Budget

Low Power?:

- LG Nexus 5: 2300 mAh / day ?!!!
- ► Raspberry pi: 500 mAh
- TelosB



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Low Power?:

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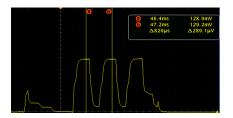
Application Driven:

- ▶ e.g.: 1 year on coin cell (220 mAh)
- ▶ e.g.: "the lifetime of the bird and weight ≤ 1 gram"
- ▶ e.g.: 2 year on 1/2 AA 3.6V battery (1100 mAh)  $\rightarrow 62\mu Ah/day$





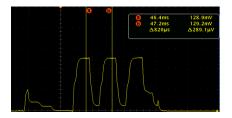
# Power Consumption: e.g. BLE



- ► 3 × 12.8 mA × 660 µs (0 dBm)
- ► 0.00704 µAh / beacon



# Power Consumption: e.g. BLE



- ► 3 × 12.8 mA × 660 µs (0 dBm)
- 0.00704  $\mu$ Ah / beacon
- ▶ iBeacon: 10 msg/s
- $\blacktriangleright$   $\rightarrow$  253.44  $\mu$ Ah

 $\rightarrow \pm \ 1$  month with a coincell battery



# Accuracy vs Precision

Not Precise or Accurate



Precise, but not Accurate



Accurate, but not Precise



Precise and Accurate





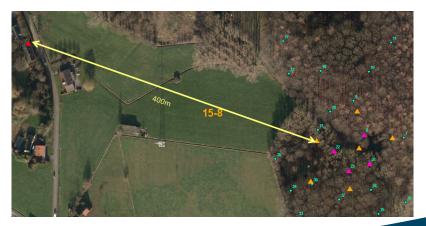
## Accuracy vs Precision



Source: Versus Technology, Inc.



# Range





### Range





# Range





# Techniques

#### Signal Strength:

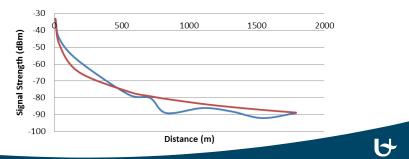
- Attenuation
- Pattern Matching (Fingerprinting)
- Presence / Proximity
- Time (Ranging):
  - Time of Flight Time Difference of Arrival
  - Round Trip Time
- Direction Finding / Angle of Arrival



# Signal Strength

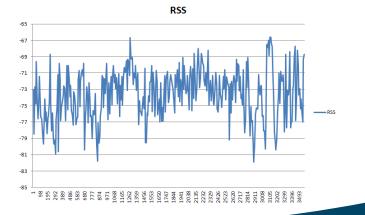
$$RSS_d = P_{rdBm} = 10 \log P_r(d_0) - 10n_p \log \frac{d}{d_0} + X$$

#### **RSS Measurements at 433 Mhz**



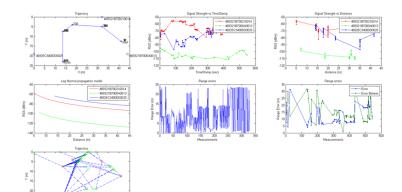


#### Attenuation





#### Attenuation



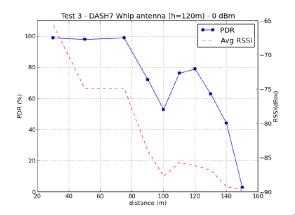
18

25

20 25 ×(m)

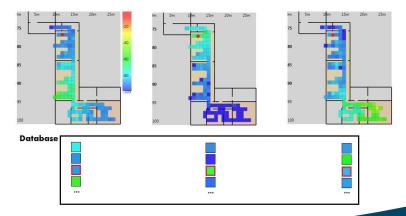


#### Attenuation





# Pattern Matching





#### Presence Detection



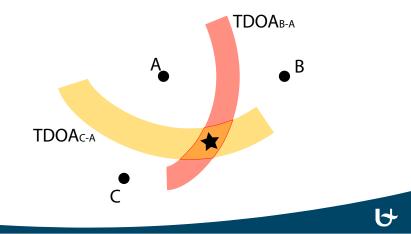






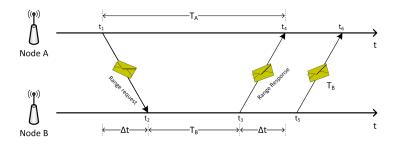


# Time of Flight: Time Difference of Arrival



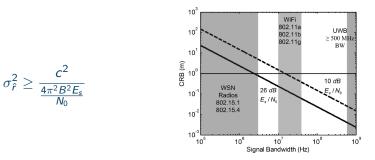


### Time of Flight: Round Trip Time



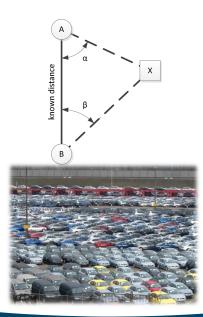


# Time of Flight: Cramer Rao Bound





Source: Lanzisera et al.: Radio Frequency Time-of-Flight Distance Measurement



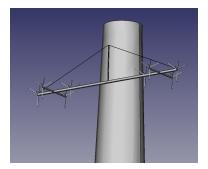


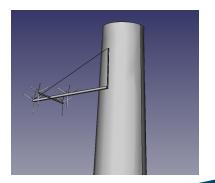
# **Direction Finding**

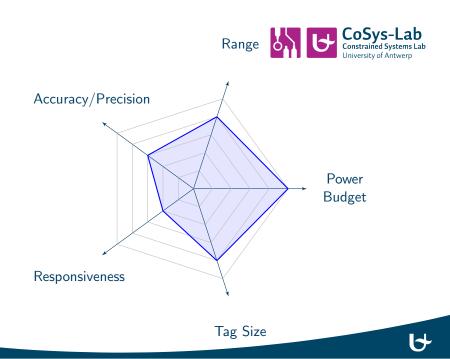




# **Direction Finding**













# DASH7

Active RFID Standard for 433 MHz.

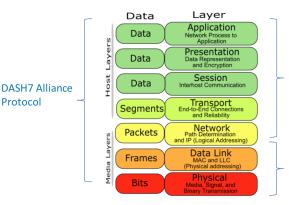
- Build on top of asynchronous WSN MAC.
- High level functionality optimized for RFID.
- Defines full functional RFID tag.
- Can be extended to non RFID applications.

Supports Tag to Tag communication.

DASH7 Alliance Protocol is designed to support fixed and mobile nodes that need to upload or retrieve small chunks of information



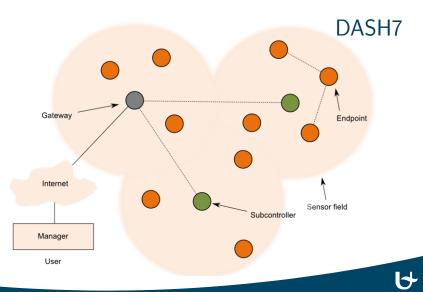
### DASH7



ZigBee WirelessHart ISA100.11a

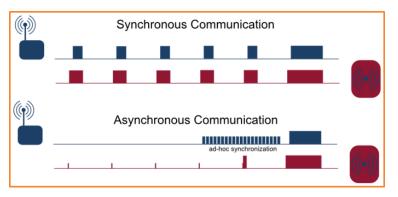
IEEE 802.15.4







### DASH7





## **Open Source Stack for DASH7**

#### http://oss-7.cosys.be LGPL v2.1

#### III Archives Tags Welcome General About DASH7 GitHub Repos The DASH7 Alliance Protocol is an open standard which originates from ISO/IEC 18000-7 standard for active RFID in the 433 Links About OSS-7 About CoSvs-Lab



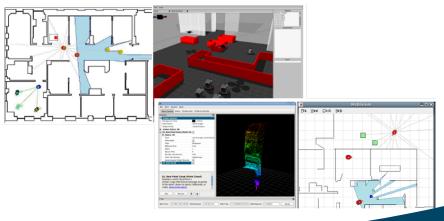


## Open Source Stack for DASH7

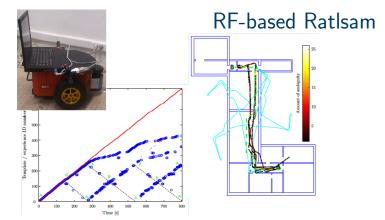




# Localization Benchmarking









# Questions?

**1** Birth Form question in your mind **2** Evaluate Is it a reasonable question?

Remember
Until you can ask the question

**4 Courage** To ask the question out loud

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