

GEOProcessing12 Conference – Valencia, Spain

Challenges in Handling Large Data Volumes for (Geo-)Processing

GEOProcessing12 Panel Discussion





Prof. Dr. Bernd Resch

31 January 2012

Panelists

Claus-Peter Rückemann
Leibniz Universität Hannover / WWU / HLRN, Germany

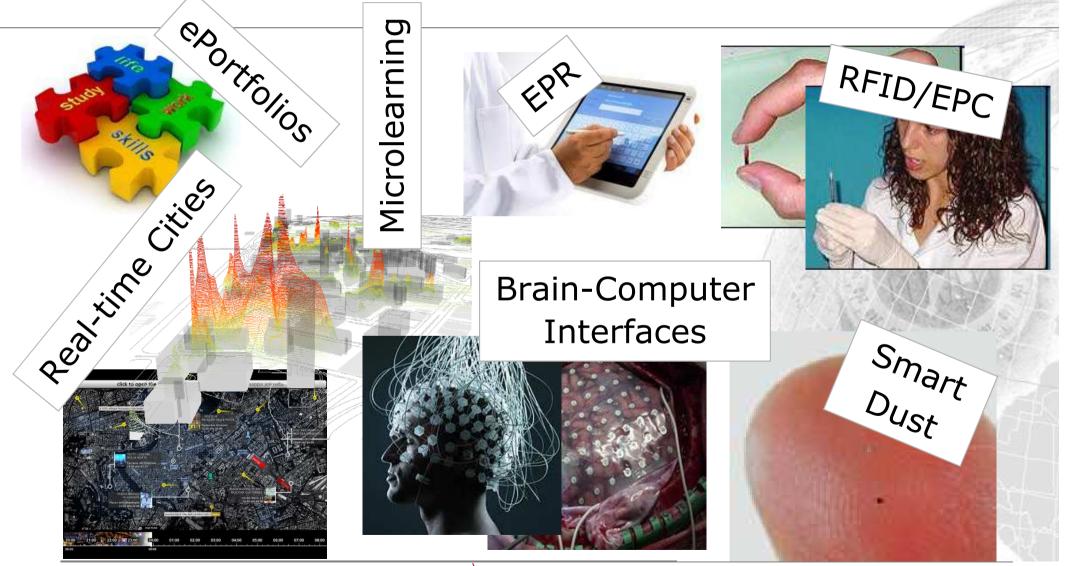
David Pheanis

Arizona State University-Tempe, USA

Yerach Doytsher, Technion
Israel Institute of Technology - Haifa, Israel

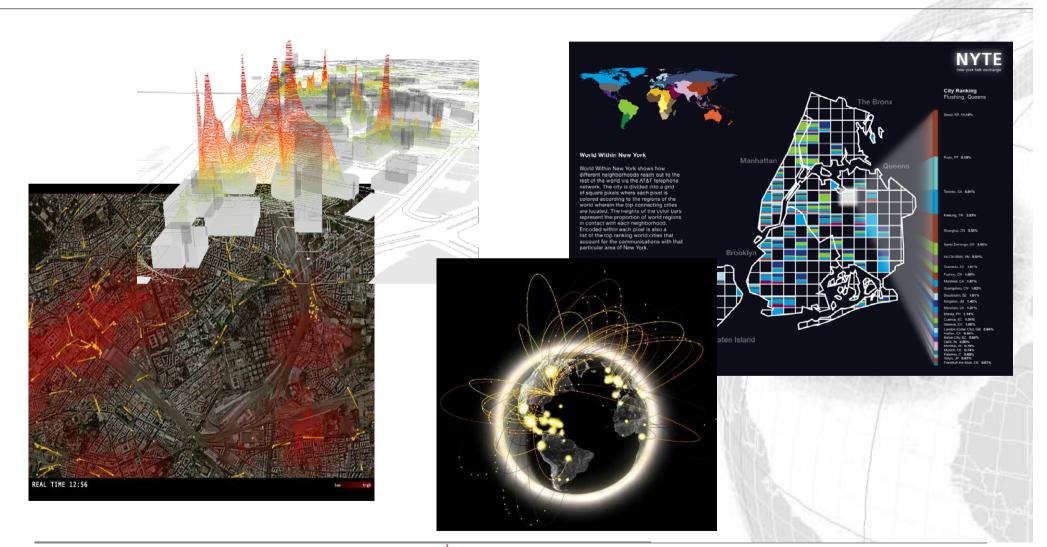


Large Data Volumes in Research





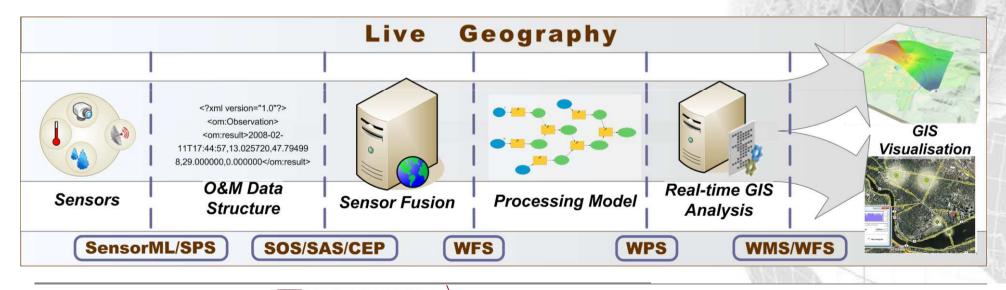
Large Data Volumes in GI Research





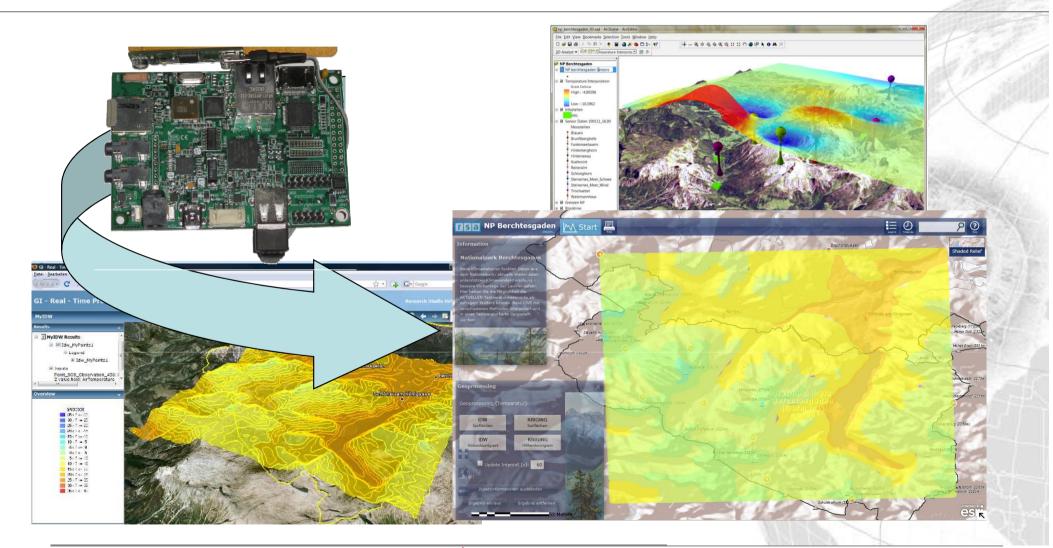
Large Data Volumes in GI Research

- Flexible and portable monitoring infrastructure
- Standardisation enables a wide variety of monitoring applications
- Sensor systems: not only view and analyse the world, but influence it in real-time



Bernd Resch

Large Data Volumes in GI Research





Potential Challenges

- Real-time capabilities in complex data processing
- Distributed sensor/data fusion, on-the-fly integration
- Event detection (CEP, ESP)
- Integration of VGI, UGC and People as Sensors
- Visualisation, 2D/3D
- Interoperability, Semantics





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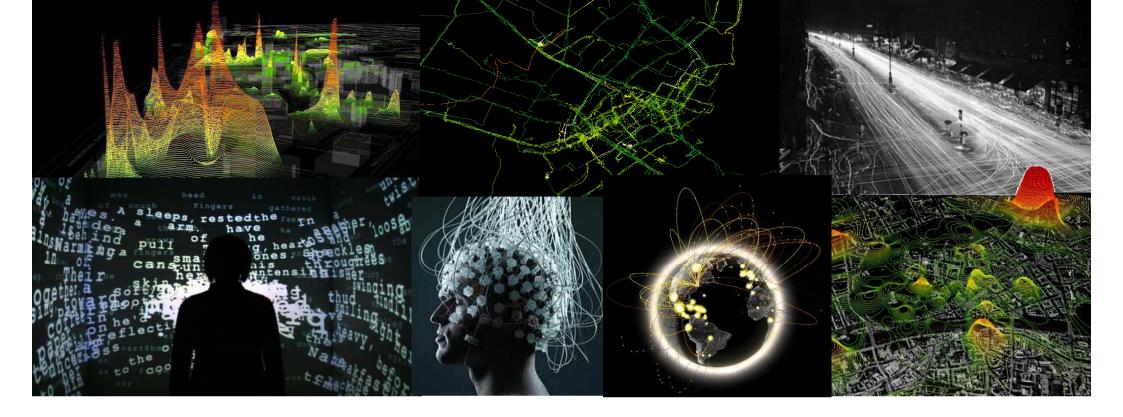


Conclusions for (GI) Research

- Tight coupling with cloud computing developments
- Efficient methods for transmission and storage needed
- Comprehensive semantic models as a central enabler
- Strong focus on efficient algorithms and implementations
- Profiling (generalisation)
- Data sub-selection







Challenges in Handling Large Data Volumes for (Geo-) Processing



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PANEL GEOProcessing Handling Large Data Volume

Seamless Nationwide Topographic Multi-Databases Challenges

Yerach Doytsher

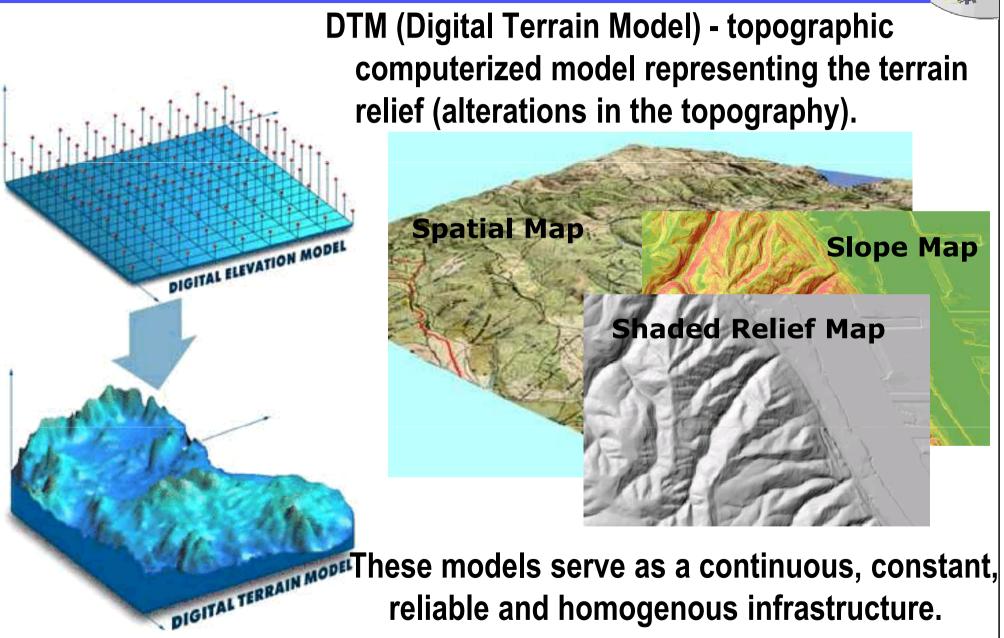
Mapping and Geo-Information Engineering

Technion, Israel

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Introduction





DTM sources



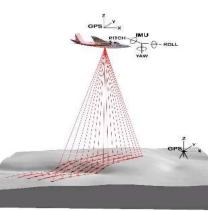
Photogrammetry

Field Surveying

Digitization/scanning

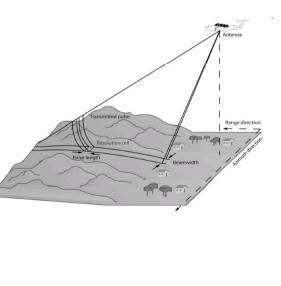
Radar based systems

ALS (LiDAR) Systems









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DTMs: Accuracy of Different Sources



Technique/Technology	Vertical Accuracy (m)
Aerial photogrammetry	0.1 – 1
Satellite photogrammetry	1 – 10
Field surveying	0.01 – 0.1
Digitization	1/3 of contouring interval
Aerial radargrammetry	2 – 5
Satellite SAR inteferometery	5 – 20
Lidar	0.1 – 0.2

Multi-Sources Challenges

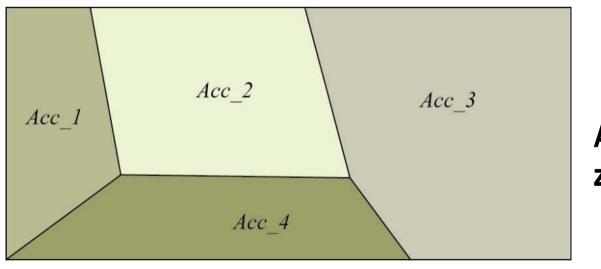


Need - integration of DTMs is essential for obtaining computerized topographic infrastructure.

Status - multi-source DTM:

Produced via various technologies and techniques;

Influenced/affected by rapid data-updates.



A typical accuracy zoning map

Problem Challenges

Different DTMs can vary and present different datacharacterizations: structure, data-density, level-of-detail, accuracy, resolution, datum, ...

Varied-scale geometric discrepancies and inconsistencies;

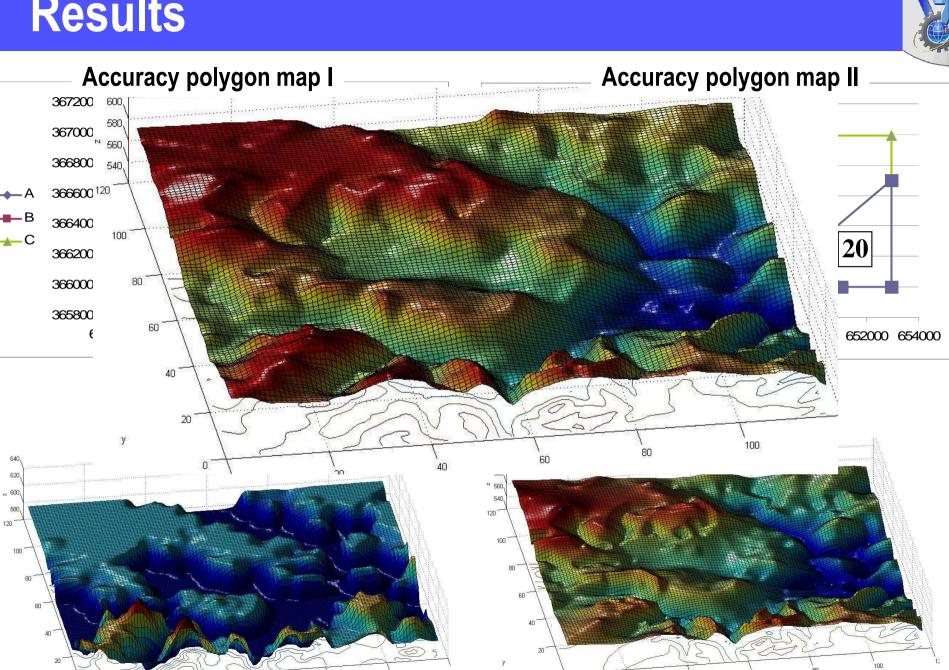
Global-systematic and local-random inaccuracies;

The common "coordinate-based superimposition" is not reliable and the results are not acceptable; it should be replaced with a "feature-based" matching/fusion solution (hierarchical approach)

Same coverage area – different models

620

Results



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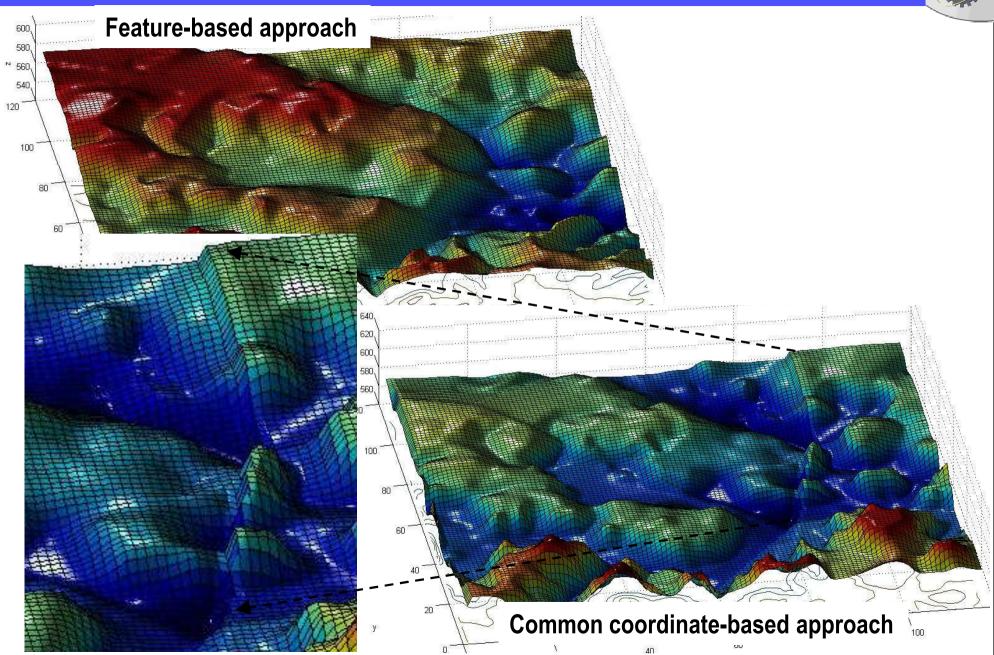
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Results





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High End Computing and Data Volume

International Conference on Advanced Geographic Information Systems, Applications, and Services (GEOProcessing 2012) DigitalWorld 2012, January 31, 2012, Valencia, Spain



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International Panel GEOProcessing 2012: Challenges in Handling Large Data

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Status on High End Computing and Data Volume: Supercomputing

Status on High End Computing and Data Volume: Supercomputing

Supercomputing, High Performance Computing

Challenges with users application scenarios, service providers, resource providers large volume data handling for geo-data and funding point of view:

Disciplines:

- Seismics and Seismology (SEG-Y), Geosciences, Natural Sciences ...
- Geophysics, Global Environment, Climatology (NetCDF), Archaeology, ...
- Visualization, streaming data ...

Services and Resources:

- Parallel IO on large TeraByte-datasets.
- Large numbers of datasets on parallel high end filesystems.
- Running parallel NetCDF on High End Resources.
- Data storage and archiving of large data.
- Transfer and broad band for geo-computation data.
- HW architecture aspects, bottlenecks (appliances, storage targets, IO servers).
- Data-staging and pre-staging for large geo data.

Development of Applications and Methods:

- MPI and efficiency for large datasets.
- Funding for handling of parallelisation and parallel IO.
- Future IO challenges and strategies ...

Status on High End Computing and Data Volume: Distributed Computing

Distributed Computing

Disciplines:

- Interactive communication requirements (quantity and quality).
- Data transfer to/from distributed resources (interactive and batch).

Services and Resources:

- Communication: Insufficient data transfer rates for large data volumes.
- Storage: Insufficient backup capacities for large data volumes.

Development of Applications and Methods:

- ... depending on funding, physical resources, consulting.
- ... depending on reliability, high availability, security.

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- Vision

Vision

What has to be done for the next generation of high end systems

Next generation: The next generation of complex high end systems will not be just only the next sizeof-factor multiplied with all the items required or just another project. The next generation step can neither be reached by hardware nor by software alone.

Holistic view: For reaching a general state of the art there is no efficient solution available other than an holistic handling, integrating user applications, services, and resources.

Common understanding: An overall understanding of integrated use, operation, and provisioning regarding software and hardware is neccessary for appropriate funding.

Real life case studies: Real life large data case studies with keyplayer participants from academia and industry representing disciplines, services, and resources providers.

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Challenges on Future Prerequisites

Challenges on Future Prerequisites

Prerequisites on development and technology

- Funding for integrated systems with academia and industry for user applications and developer support. This has been shown not to be possible with standard restricted project funding.
- Common availibility of data transfer to compute resources, international Broadband resources (TeraBytes per hour, per user group).
- Fast and massive I/O (> 100 GB per second, per application; > 1 GB per second, per core).
- Fast massive communication (> 100000 requests per interactive application, per operation).
- Fast Archiving, Storage and Retrieval (PetaBytes per day, per user group).
- Reliable and secure data and resources access (homomorphic?).
- Data-Staging (hardware and software technology efficiently using the high end resources, availability of about 1 TeraByte per 5 Minutes).



Using GPS-Enabled Cell Phones for Traffic-Flow Data Collection

Bruce Beyeler and David C. Pheanis Computer Science and Engineering Ira A. Fulton School of Engineering Arizona State University Tempe, AZ 85287-8809 Bruce.Beyeler@ASU.edu or David.Pheanis@ASU.edu



Context

Measuring Traffic Flow

- Using cell phones as sensors
- Need to understand provided accuracy

Questions to be Answered

- How accurate are cell-phone reports?
- How does accuracy vary?
- Are cell-phone accuracy reports accurate?

Research Goal

- Optimize collection algorithms
- Minimize required data collection.



Existing Research Static Collectors

- ✤ Inductive loops, cameras, …
- Vehicle counts, speeds, at fixed locations
- Average results per road segment

Dynamic Collectors

- ✤ Cell phones, GPS probes, …
- Report data based on time, distance, etc.
- Provide individual reports continuously

Comparison to Static Collectors

 Cell-phone data transformed in order to compare against static data.



Cell-Phone GPS

Cell phones include GPS
Network-Assisted GPS
Assumptions

- Majority of future phones will be GPS-enabled
- Accuracy will improve
- Capability of running user programs

Available low-cost bandwidth.



Compare to Ground Truth

Ground-Truth Measurements

- Utilize known map data
- Vehicle data
- Operator inputs

Current Research Focus

- Accuracy of individual cell phones
- Different conditions/positions
- Goal: Determine the *actual* speed and position of a test vehicle at any given time.