Young Researchers Panel

Hot Topics and Future Developments

Moderator: Miguel García InfoWare 2010 September 20-25, 2010 -Valencia, Spain



InfoWare 2010 September 20-25, 2010 - Valencia, Spain

Guest Panelists

- Andreas Loeffler, Friedrich-Alexander-University of Erlangen-Nuremberg, Germany
- Miguel Garcia, Polytechnic University of Valencia, Spain
- Zbynek Kocur, FEE CTU in Prague, Czech Republic
- Anilloy Frank, Graz University of Technology, Austria
- Yuki Minami, Osaka University, Japan







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Project activities

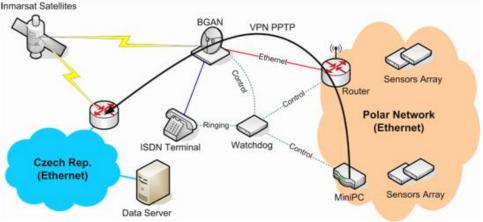
Marek Neruda {nerudmar@fel.cvut.cz} Zbyněk Kocur {kocurzby@fel.cvut.cz}



CTU FEE Department of Telecommunications Engineering **Projects – Budnik Team Research Group**

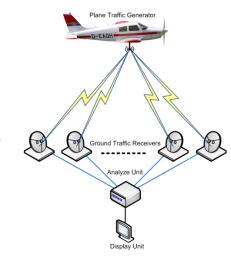
• Data transfer from Antarctica

- Goal: Automatic download of data from local sensor network and its transmission to the Czech Republic.
- \checkmark Unmanned automatic operation.



• High data rates between plane and terrestrial station

- ✓ Goal: Low cost system allowing full duplex communication between plane and terrestrial station.
- ✓ Based on IEEE 802.11 and IEEE 802.16.



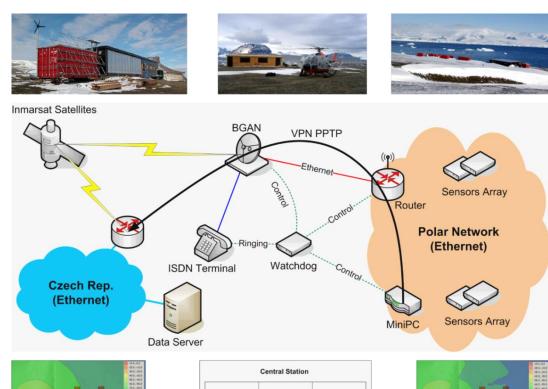
Speed: 450 km/h Distance: 3 km Rate: 6 (DL) / 2 (UL) Mbit/s Delay: 5 ÷ 200 ms



CTU FEE Department of Telecommunications Engineering **Projects – Budnik Team Research Group**

• Data transfer from Antarctica

- ✓ Bender I (2008/2009), Bender II (2010/2011)
- Funded by: Research Intention by Ministry of Education, Youth and Sports;
 Student's Grant Competition



ROUTER

Section

WatchDog Section

MiniPC

Section

BGAN

Section



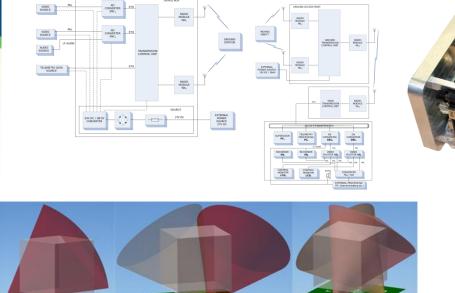


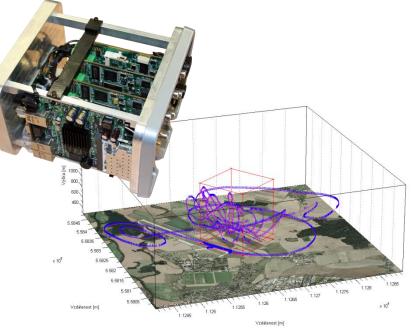
CTU FEE Department of Telecommunication Engineering **Projects – Budnik Team Research Group**

• High data rates between plane and terrestrial station

- Receiving and transmitting in several directions.
- ✓ Using of more independent data channels.
- ✓ Optimization for Ethernet and TCP/IP.
- ✓ Data redundancy.
- Founded by: Research Intention by Ministry of Education,
 Youth and Sports; Technological Agency of Czech Republic, LAC









The Sixth International Conference on Wireless and Mobile Communications ICWMC 2010

Panel Discussion:

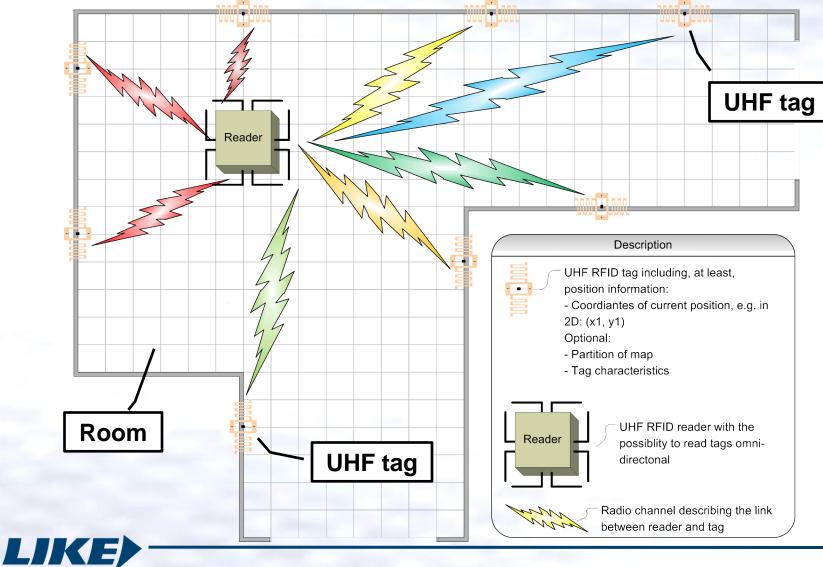
Localization of passive RFID UHF tags

Andreas Löffler

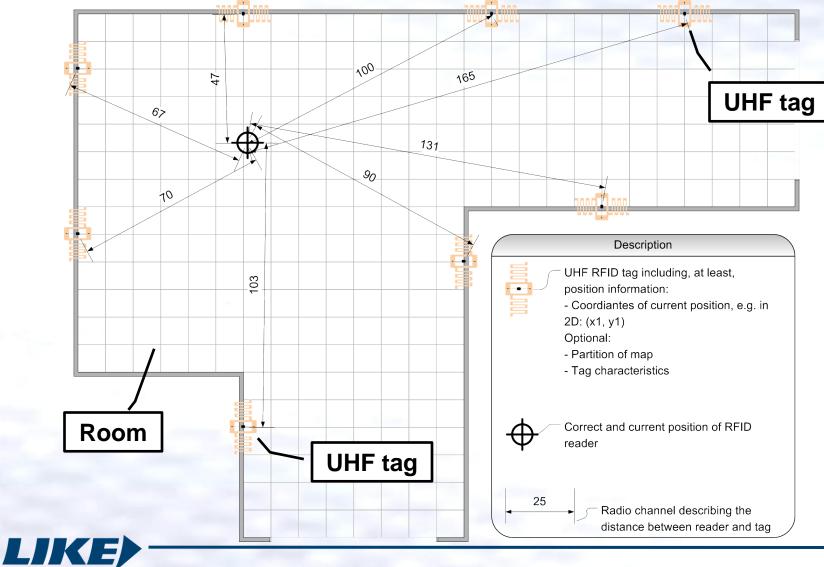
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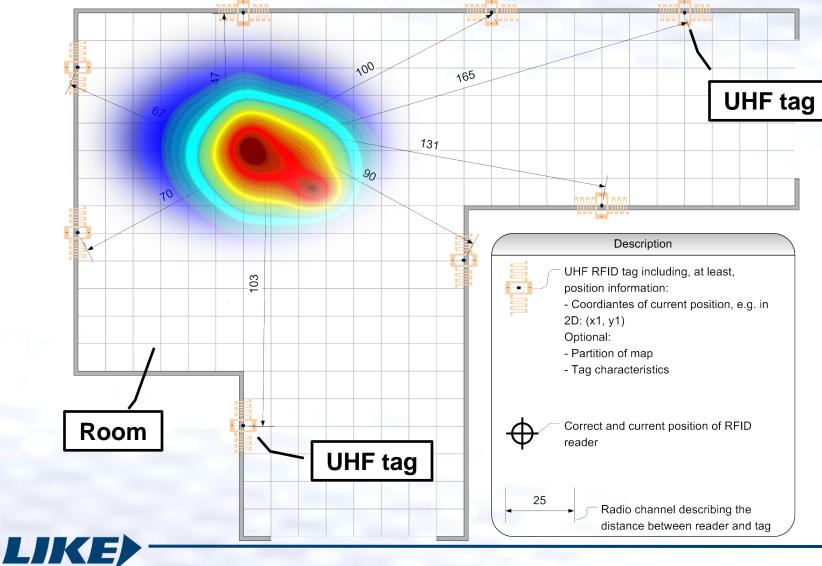




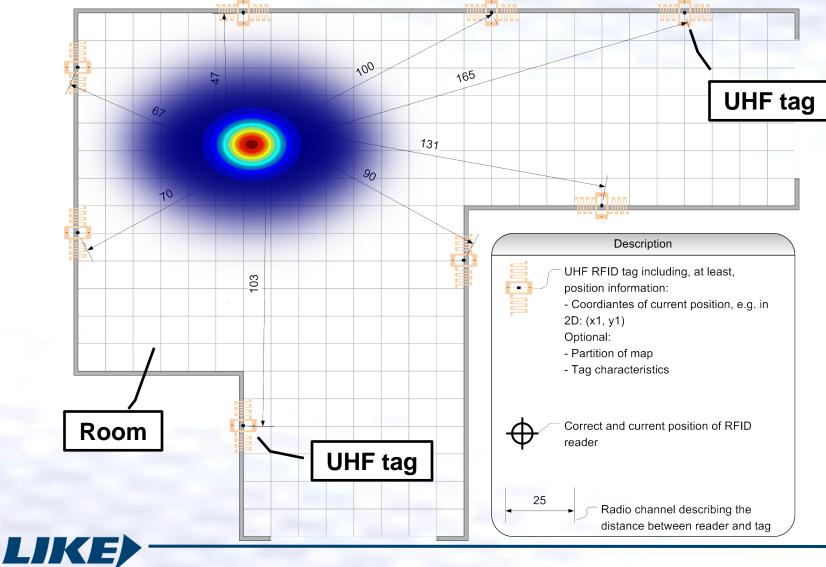
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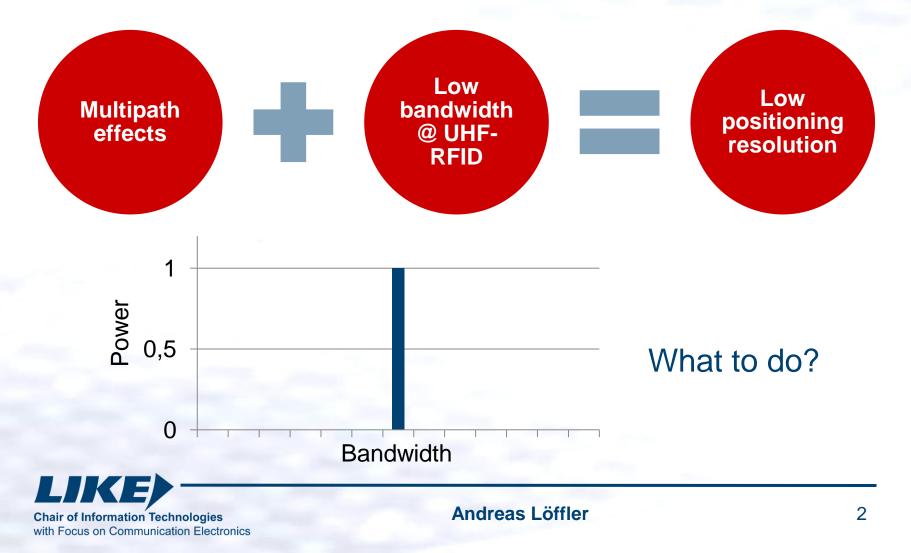
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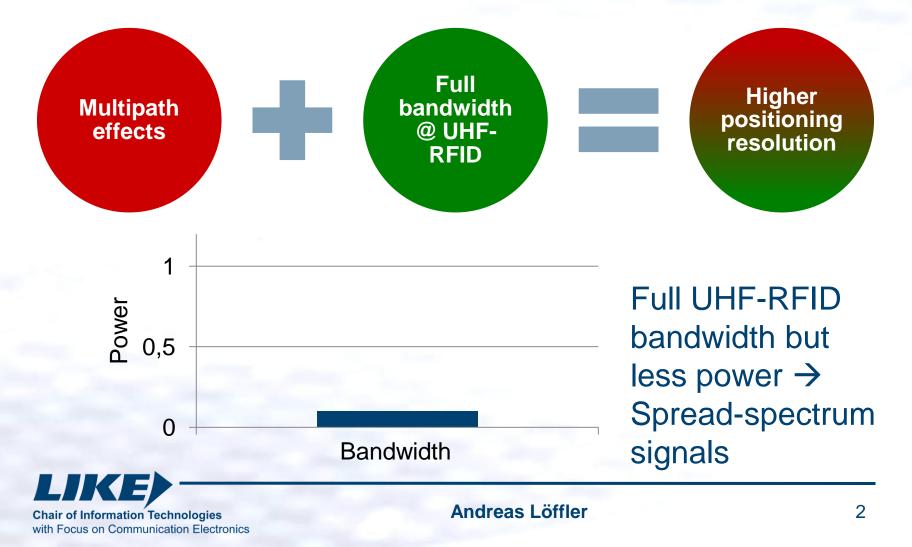
State-of-the-Art

Now: Low positioning resolution of the reader's location



Approach

Goal: High positioning resolution of the reader's location





The Sixth International Conference on Wireless and Mobile Communications ICWMC 2010

Panel Discussion!?

loeffler@like.eei.uni-erlangen.de



Friedrich-Alexander-Universität Erlangen-Nürnberg

Automatic Systems for Fish Feeding in Marine Fish Farms

Miguel García

migarpi@posgrado.upv.es

Researcher of Research Institute for Integrated Management of Coastal Areas. InfoWare 2010 September 20-25, 2010 -Valencia, Spain







Reasons

- Nowadays many fishes that we consume, they are bred in fish farms.
- The lost food in the cages is close to 8.26%, of the total food.
- The food expenses almost represent the 60% of the total costs of the marine farm exploitation.
- The food that gets lost in the feeding process of these facilities should be controlled, because:
 - the wasted food is translated into important economic losses.
 - the wastage accumulation in the seabed causes notorious changes in the silts chemistry of the near farm areas





Challenges

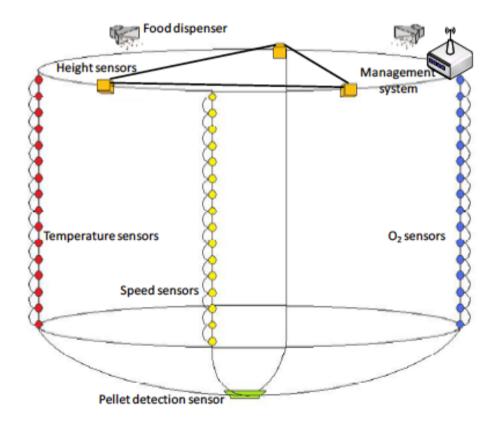
- Many water parameters should be taken into account:
 - PH, salinity, the temperature, dissolved oxygen (OD) the transparency, the suspended solids (SS), ammonium, nitrates, the total nitrogen (NT) or match soluble reagent (PSR), etc.
 - All this parameters influence the behavior of fishes in cave.
- The underwater communications are difficult, even more if we use wireless communications.
- The conditions of the water are not always good and suitable to place the sensor nodes.
- How do we estimate the quantity of necessary food in cave?
 - It depends of the type of fish, its size, the season of the year.





Possible solutions

- The traditional methods using scuda-divers or cameras.
- The systems based on mathematical formulations.
- Automatic systems, for example:













Model-based Variability Management for Complex Embedded Networks

By Anilloy Frank Eugen Brenner

Name Anilloy Frank

23-09-2010

VarMgmt

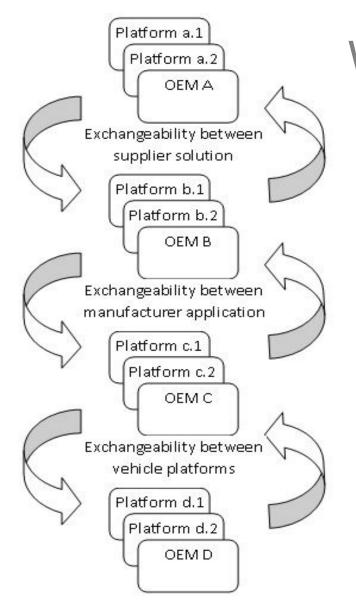


Motivation



- Complexity of Embedded software
- Exchangeability
- OEM
- Standardized Structure
- Application
 - Automotive
 - Aviation
 - Communication
 - Electronics





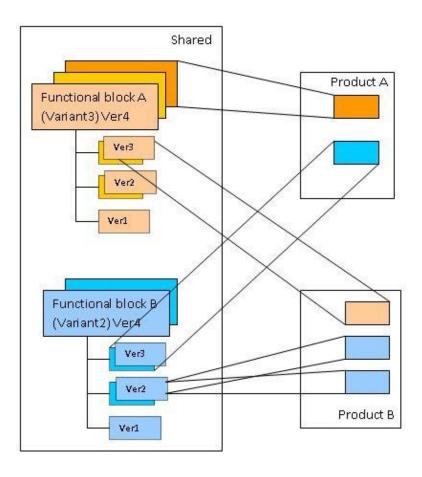
Why Variants?

- Ability to customize
- Reuse
- Software for different regions (Europe, US, Asia, etc.)
- Different Sensors/Actuators, different device drivers
- Functionality distribution to different ECU's

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Specification of cases



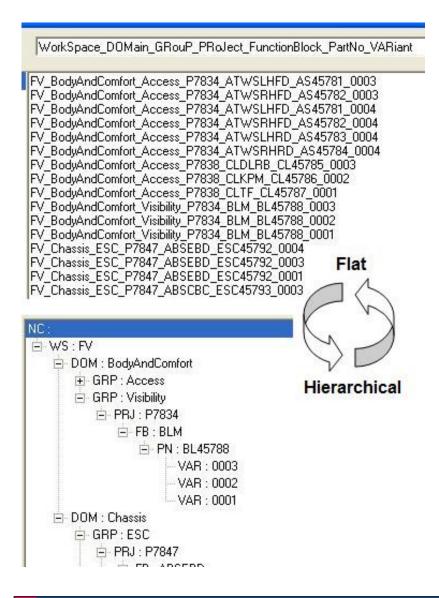
- exhibit compatibility issues between functional blocks
- extracting features to identify and specify the functional blocks
- tracks usability and prevent inconsistencies due to deprecating variants
- testing mechanism for validations to maintain high quality for components and it variants.
- a process to determine whether a functional block or its variant exist



VarMamt











Challenges

- Identify components from name
- Searching SW components, Variants in core assets

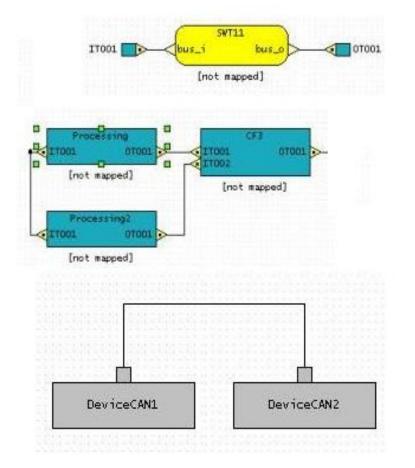
Names

- Transform flat to hierarchical
- Build a dictionary
- Assign weights









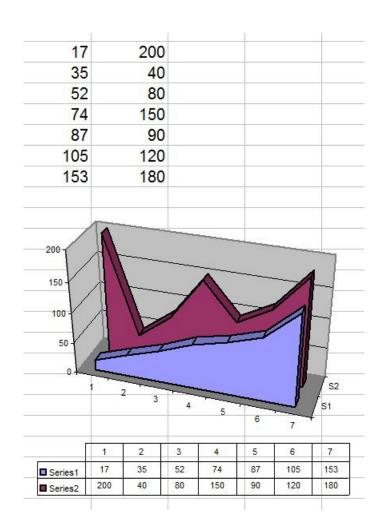
Challenges

 Identifying types based on spatial features

Architectural (spatial) features

- Input, output, types
- Object description
- Meta data, key words





Project Solution



Challenges

 Identify types based on functionality

Functional features

- Functional use
- Parameters
- Map variants
- Truth tables
- Calibrations

Conclusion



The idea focuses on the interactive aspect of design tools, to enhance variability management.



Model-based Variability Management for Complex Embedded Networks

Thank you for your attention.

Anilloy Frank Institute of Technical Informatics Graz University of Technology Inffeldgasse 16/1 8010 Graz anilloy.frank@student.tugraz.at, frankanilloy@gmail.com

Name Anilloy Frank

23-09-2010